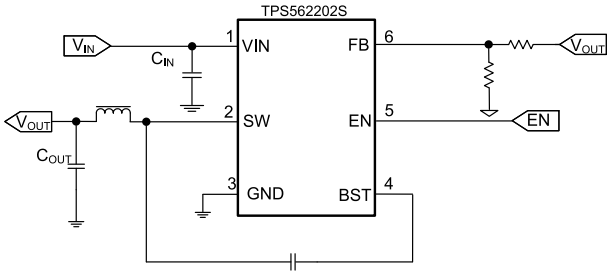
TPS562202S 4.3-V to 17-V Input, 2-A, ECO Mode Synchronous Buck Converter in SOT563

1 Features

- 2-A converter with integrated 140-mΩ and 84-mΩ FETs
- D-CAP2™ mode control with fast transient response
- Input voltage range: 4.3 V to 17 V
- Output voltage range: 0.804 V to 7 V
- ECO mode at light loading
- 580-kHz switching frequency
- Low shutdown current of less than 3 µA
- 1.5% feedback voltage accuracy (25°C)
- Support pre-bias start-up
- Cycle-by-cycle overcurrent limit
- Hiccup-mode overcurrent protection
- Non-latch UVP and TSD protections
- Fixed soft start: 1.2 ms

2 Applications

- SMPS power supply for TV
- Smart speaker
- Wired networking
- Digital set-top box (STB)
- Surveillance



Simplified Schematic

3 Description

The TPS562202S is a simple, easy-to-use, 2-A synchronous buck converter in a SOT563 package.

The device is optimized to operate with minimum external components and also optimized to achieve low standby current.

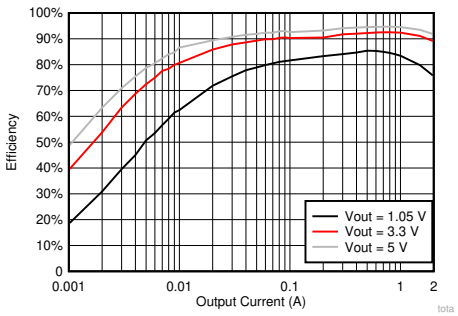
This switch mode power supply (SMPS) device employs D-CAP2 mode control providing a fast transient response and supporting both low-equivalent series resistance (ESR) output capacitors such as specialty polymer and ultra-low ESR ceramic capacitors with no external compensation components.

The TPS562202S operates in ECO mode, which maintains high efficiency during light load operation. The TPS562202S is available in a 6-pin 1.6-mm × 1.6-mm SOT563 (DRL) package, and specified from a –40°C to 125°C junction temperature.

Device Information

PART NUMBER(1)	PACKAGE	BODY SIZE (NOM)
TPS562202S	DRL (6)	1.60 mm × 1.60 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.



TPS562202S Efficiency

An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.

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4 Revision History

DATE	REVISION	NOTES
October 2020	*	Initial release

5 Device Comparison Table

PART NUMBER	WORK MODE IN LIGHT LOADING
TPS562202S	ECO
TPS562207S	FCCM

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6 Pin Configuration and Functions

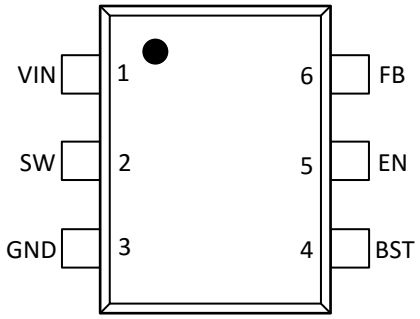

Figure 6-1. 6-Pin SOT563 DRL Package (Top View)

Table 6-1. Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
VIN	1	I	Input voltage supply pin
SW	2	O	Switch node connection between high-side NFET and low-side NFET
GND	3	—	Ground pin source terminal of low-side power NFET as well as the ground terminal for controller circuit. Connect sensitive FB to this GND at a single point.
BST	4	O	Supply input for the high-side NFET gate drive circuit. Connect 0.1-µF capacitor between BST and SW pin.
EN	5	I	Enable input control. Active high. Must be pulled up to enable the device.
FB	6	I	Converter feedback input. Connect to output voltage with feedback resistor divider.

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7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)[1]

		MIN	MAX	UNIT
Input voltage	VIN, EN	–0.3	19	V
	BST	–0.3	25	V
	BST (10 ns transient)	–0.3	27	V
	BST (vs SW)	–0.3	6.5	V
	FB	–0.3	6.5	V
	SW	–2	19	V
	SW (10 ns transient)	–3.5	21	V
Operating junction temperature, T_J		–40	150	°C
Storage temperature, T_{stg}		–55	150	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

7.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001[1]	±2000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101[2]	±500	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
V_{IN}	Supply input voltage range		4.3		17	V
V_I	Input voltage range	BST	–0.1		23	V
		BST (10 ns transient)	–0.1		26	
		BST (vs SW)	–0.1		6	
		EN	–0.1		17	
		FB	–0.1		5.5	
		SW	–1.8		17	
		SW (10 ns transient)	–3.5		20	
T_J	Operating junction temperature		–40		125	°C

7.4 Thermal Information

THERMAL METRIC[1]		TPS562202S DRL 6 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	141.0	°C/W
$R_{\theta JA_effective}$	Junction-to-ambient thermal resistance with TI EVM board[2]	75.0	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	42.0	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	25.5	°C/W
ψ_{JT}	Junction-to-top characterization parameter	1.0	°C/W

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THERMAL METRIC[1]		TPS562202S DRL 6 PINS	UNIT
ψ_{JB}	Junction-to-board characterization parameter	25.3	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report.

(2) This $R_{\theta JA_effective}$ is tested on TPS562202EVM board (2 layer, copper thickness is 2 oz) at V_{IN} = 12 V, V_{OUT} = 5 V, I_{OUT} = 2 A , TA = 25°C

7.5 Electrical Characteristics

T_J = –40°C to 125°C, V_{IN} = 12 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY CURRENT						
I_{VIN}	Operating – non-switching supply current	V_{IN} current, EN = 5 V, V_{FB} = 1 V		380	520	µA
I_{VINSDN}	Shutdown supply current	V_{IN} current, EN = 0 V		1	3	µA
LOGIC THRESHOLD						
V_{ENH}	EN high-level input voltage	EN		1.35	1.6	V
V_{ENL}	EN low-level input voltage	EN	0.9	1.05		V
R_{EN}	EN pin resistance to GND	V_{EN} = 12 V	225	400	900	kΩ
V_{FB} VOLTAGE AND DISCHARGE RESISTANCE						
V_{FBTH}	V_{FB} threshold voltage	ECO-mode™ operation		815		mV
V_{FBTH}	V_{FB} threshold voltage	Continuous mode operation at T_A = 25°C	792	804	816	mV
I_{FB}	V_{FB} input current	V_{FB} = 1 V		0	±0.1	µA
MOSFET						
$R_{DS(on)h}$	High-side switch resistance	T_A = 25°C, V_{BST} – SW = 5.5 V		140		mΩ
$R_{DS(on)l}$	Low-side switch resistance	T_A = 25°C		84		mΩ
CURRENT LIMIT						
$I_{ocl_l_source}$	Low side FET source current limit	Inductor valley current set point	2.24	3.1	4	A
THERMAL SHUTDOWN						
T_{SDN}	Thermal shutdown threshold[1]	Shutdown temperature		160		°C
		Hysteresis		25		
ON-TIME TIMER CONTROL						
$t_{OFF(MIN)}$	Minimum off time	V_{FB} = 0.5 V		220	310	ns
SOFT START						
Tss	Soft-start time	Internal soft-start time, test V_{OUT} from 10% to 90%		1.2		ms
FREQUENCY						
F_{sw}	Switching frequency	VO = 1.05 V, continuous current conditions		580		kHz
OUTPUT UNDERVOLTAGE						
V_{UVP}	Output UVP threshold	Hiccup detect (H > L)		65%		
T_{HICCUP_WAIT}	Hiccup on time			2.2		ms
T_{HICCUP_RE}	Hiccup time before restart			18		ms
UVLO						
UVLO	UVLO threshold	Wake up VIN voltage		4.0	4.3	V
		Shutdown VIN voltage	3.3	3.6		
		Hysteresis VIN voltage		0.4		

(1) Not production tested.

7.6 Typical Characteristics

V_{IN} = 12 V (unless otherwise noted)

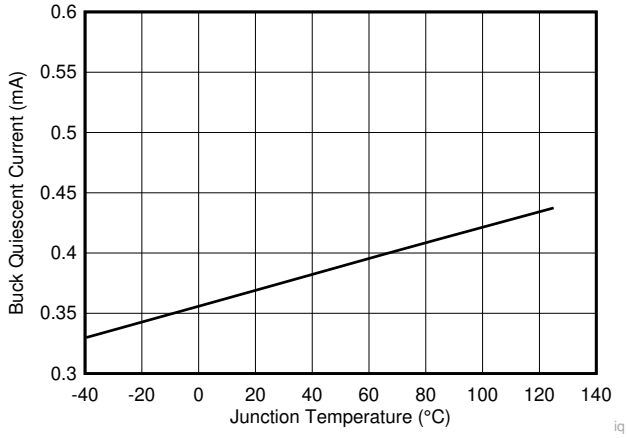

Figure 7-1. Supply Current vs Junction Temperature

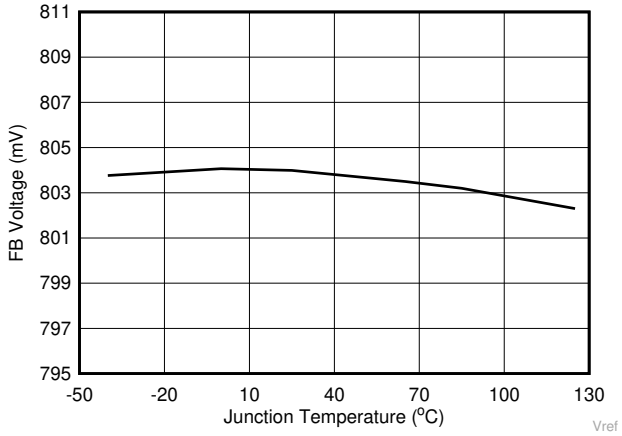

Figure 7-2. FB Voltage vs Junction Temperature

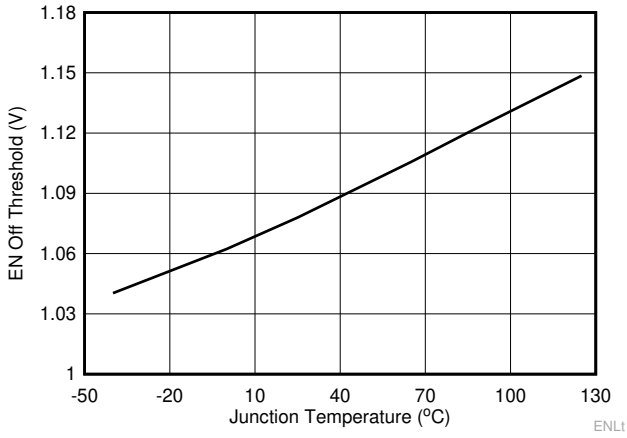

Figure 7-3. EN Off Threshold Voltage vs Junction Temperature

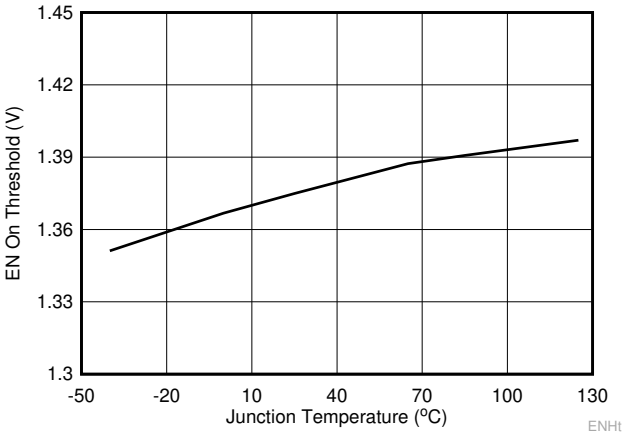

Figure 7-4. EN On Threshold Voltage vs Junction Temperature

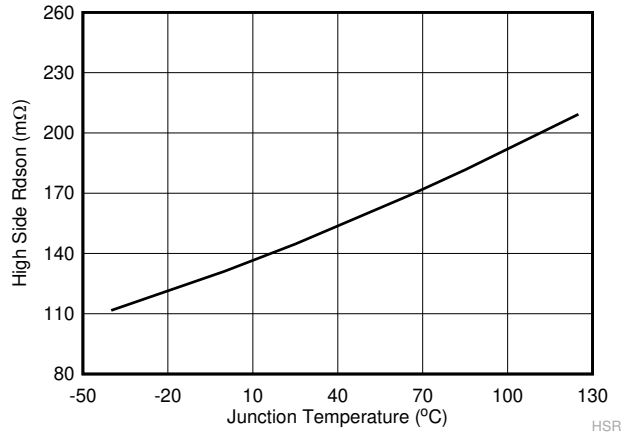

Figure 7-5. High-Side $R_{ds\text{-}On}$ vs Junction Temperature

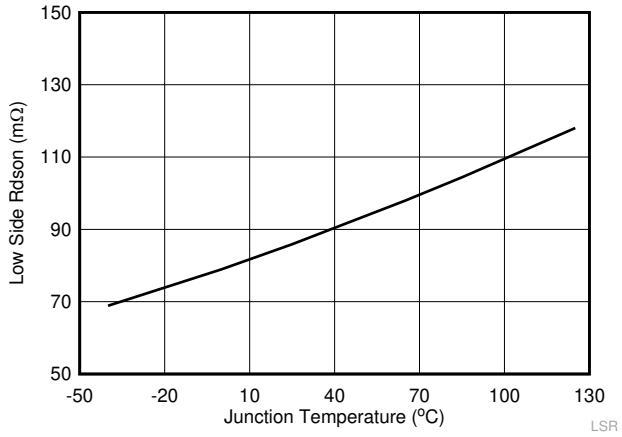

Figure 7-6. Low-Side $R_{ds\text{-}On}$ vs Junction Temperature

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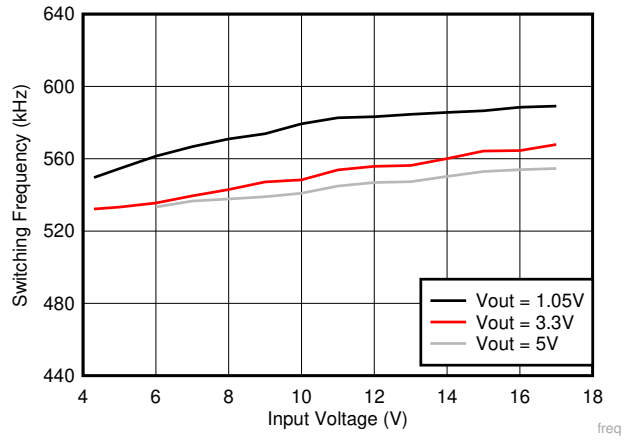

Figure 7-7. Switching Frequency vs Input Voltage

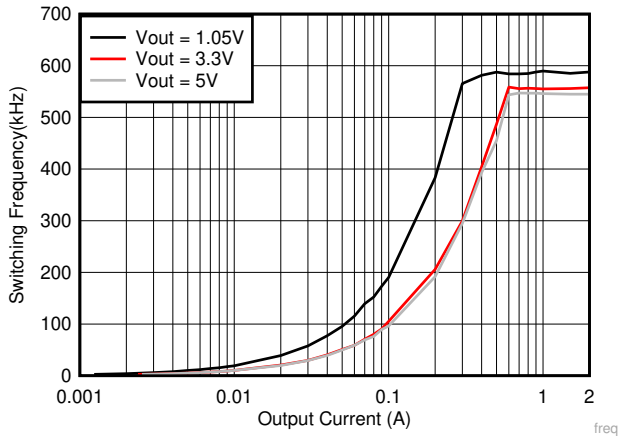

Figure 7-8. Switching Frequency vs Output Current

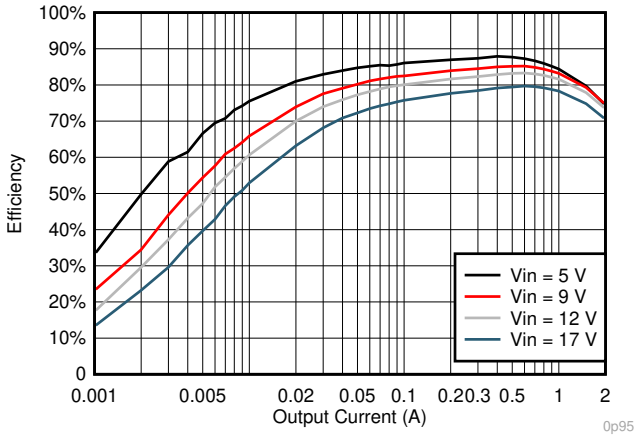

Figure 7-9. V_{OUT} = 0.95-V Efficiency, L = 2.2 µH

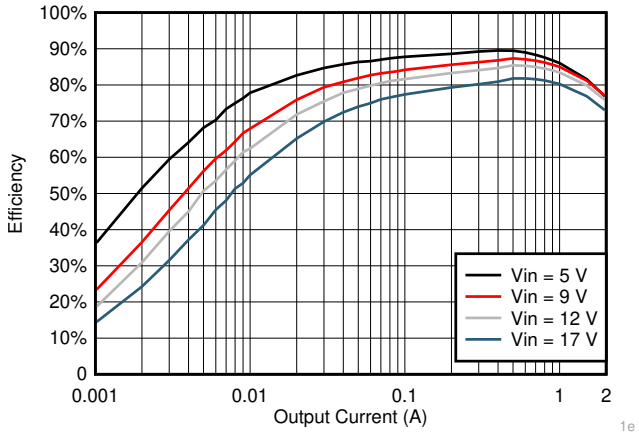

Figure 7-10. V_{OUT} = 1.05-V Efficiency, L = 2.2 µH

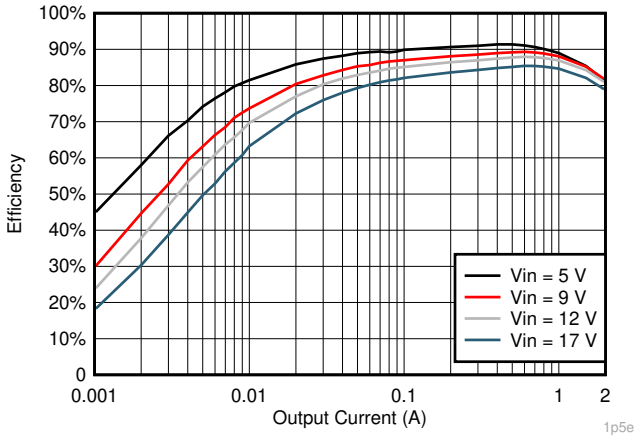

Figure 7-11. V_{OUT} = 1.5-V Efficiency, L = 2.2 µH

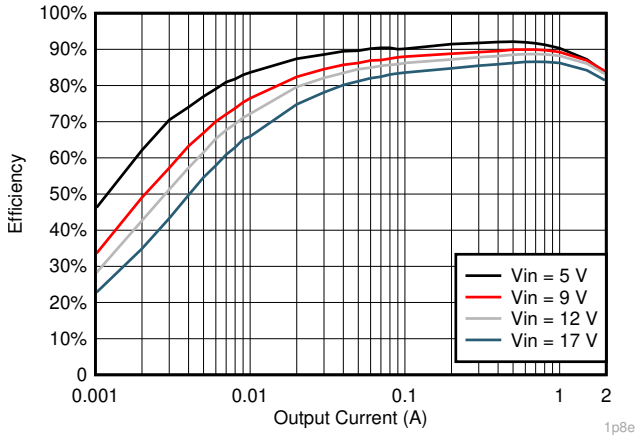

Figure 7-12. V_{OUT} = 1.8-V Efficiency, L = 2.2 µH

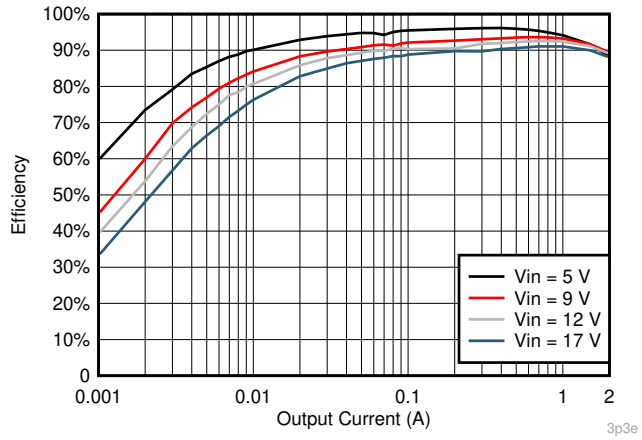

Figure 7-13. V_{OUT} = 3.3-V Efficiency, L = 3.3 µH

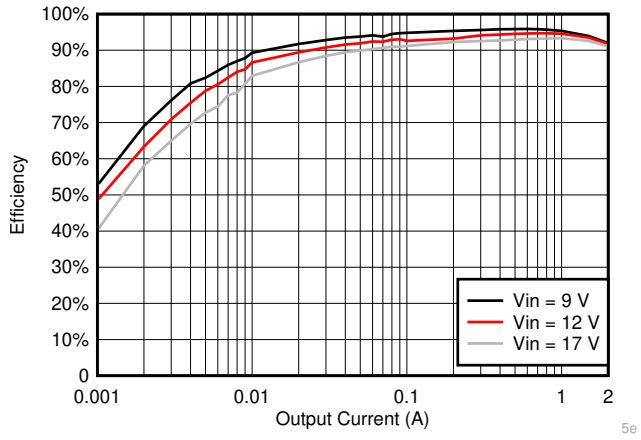

Figure 7-14. V_{OUT} = 5-V Efficiency, L = 4.7 µH

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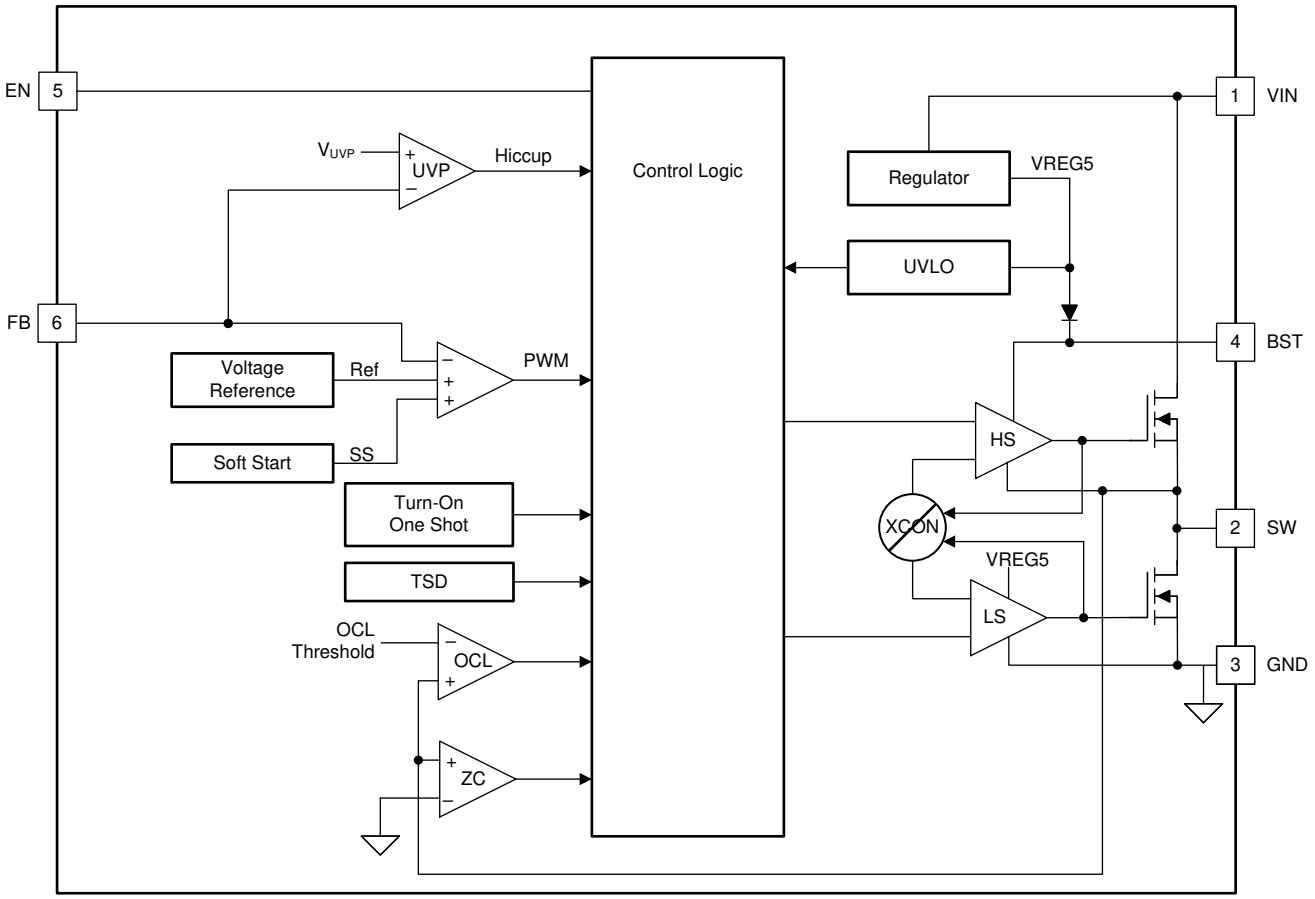
8 Detailed Description

8.1 Overview

The TPS562202S is a 2-A synchronous buck converter. The proprietary D-CAP2 mode control supports low-ESR output capacitors, such as specialty polymer capacitors and multi-layer ceramic capacitors, without complex external compensation circuits. The fast transient response of D-CAP2 mode control can reduce the output capacitance required to meet a specific level of performance.

8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 Adaptive On-Time Control and PWM Operation

The main control loop of the TPS562202S is adaptive on-time pulse width modulation (PWM) controller that supports a proprietary D-CAP2 mode control. The D-CAP2 mode control combines adaptive on-time control with an internal compensation circuit for pseudo-fixed frequency and low external component count configuration with both low-ESR and ceramic output capacitors. It is stable even with virtually no ripple at the output.

At the beginning of each cycle, the high-side MOSFET is turned on. This MOSFET is turned off after internal one shot timer expires. This one shot duration is set proportional to the converter input voltage, VIN, and inversely proportional to the output voltage, V_O, to maintain a pseudo-fixed frequency over the input voltage range, hence it is called adaptive on-time control. The one-shot timer is reset and the high-side MOSFET is turned on again when the feedback voltage falls below the reference voltage. An internal ramp is added to reference voltage to simulate output ripple, eliminating the need for ESR induced output ripple from D-CAP2 mode control.

8.3.2 ECO Mode Control

The TPS562202S is designed with advanced Eco-mode to maintain high light load efficiency. As the output current decreases from heavy load condition, the inductor current is also reduced and eventually comes to point

that its rippled valley touches zero level, which is the boundary between continuous conduction and discontinuous conduction modes. The rectifying MOSFET is turned off when the zero inductor current is detected. As the load current further decreases, the converter runs into discontinuous conduction mode. The on-time is kept almost the same as it was in continuous conduction mode so it takes more time to discharge the output capacitor with smaller load current to the level of the reference voltage. This makes the switching frequency lower, proportional to the load current, and keeps the light load efficiency high. The transition point to the light load operation $I_{OUT(LL)}$ current can be calculated in Equation 1.

$$I_{OUT(LL)} = \frac{1}{2 \times L \times f_{SW}} \times \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{V_{IN}} \quad (1)$$

8.3.3 Soft Start and Pre-Biased Soft Start

The TPS562202S has an internal 1.2-ms soft start. When the EN pin becomes high, the internal soft-start function begins ramping up the reference voltage to the PWM comparator.

If the output capacitor is pre-biased at start-up, the devices initiate switching and start ramping up only after the internal reference voltage becomes greater than the feedback voltage V_{FB}. This scheme ensures that the converters ramp up smoothly into regulation point.

8.3.4 Current Protection

The output overcurrent limit (OCL) is implemented using a cycle-by-cycle valley detect control circuit. The switch current is monitored during the OFF state by measuring the low-side FET drain-to-source voltage. This voltage is proportional to the switch current. To improve accuracy, the voltage sensing is temperature compensated.

During the on-time of the high-side FET switch, the switch current increases at a linear rate determined by Vin, Vout, the on-time, and the output inductor value. During the on-time of the low-side FET switch, this current decreases linearly. The average value of the switch current is the load current I_{out}. If the monitored current is above the OCL level, the converter keeps the low-side FET on and delays the creation of a new set pulse, even the voltage feedback loop requires one, until the current level becomes OCL level or lower. In subsequent switching cycles, the on-time is set to a fixed value and the current is monitored in the same manner.

There are some important considerations for this type of overcurrent protection. The load current is higher than the overcurrent threshold by one half of the peak-to-peak inductor ripple current. Also, when the current is being limited, the output voltage tends to fall as the demanded load current can be higher than the current available from the converter. This can cause the output voltage to fall. When the FB voltage falls below the UVP threshold voltage, the UVP comparator detects it. Then, the device will shut down after the UVP delay time (typically 24 µs) and re-start after the hiccup time (typically 18 ms).

When the overcurrent condition is removed, the output voltage returns to the regulated value.

8.3.5 Undervoltage Lockout (UVLO) Protection

UVLO protection monitors the internal regulator voltage. When the voltage is lower than UVLO threshold voltage, the device is shut off. This protection is non-latching.

8.3.6 Thermal Shutdown

The device monitors the temperature of itself. If the temperature exceeds the threshold value (typically 160°C), the device is shut off. This is a non-latch protection. The device resumes normal working once the temperature return below the recovery threshold value (typically 135°C).

8.4 Device Functional Modes

8.4.1 Normal Operation

When the input voltage is above the UVLO threshold and the EN voltage is above the enable threshold, the TPS562202S can operate in their normal switching modes at heavy loading. In continuous conduction mode (CCM), the TPS562202S operates at a quasi-fixed frequency of 580 kHz.

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8.4.2 Eco-mode Operation

When the TPS562202S is in normal CCM operating mode and the switch inductor current falls to 0 A, the TPS562202S begins operating in Eco-mode. Each switching cycle is followed by a period of energy-saving sleep time. The sleep time ends when the FB voltage falls below the reference voltage. As the output current decreases, the perceived time between switching pulses increases.

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9 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The device is a typical buck DC-DC converter. It is typically used to convert a higher dc voltage to a lower dc voltage with a maximum available output current of 2 A. The following design procedure can be used to select component values for the TPS562202S. Alternately, the WEBENCH® software may be used to generate a complete design. The WEBENCH software uses an iterative design procedure and accesses a comprehensive database of components when generating a design. This section presents a simplified discussion of the design process.

9.2 Typical Application

The application schematic in Figure 9-1 was developed to meet the previous requirements. This circuit is available as the evaluation module (EVM). The following sections provide the design procedure.

Figure 9-1 shows the TPS562202S 4.3-V to 17-V input, 1.05-V output converter schematics.

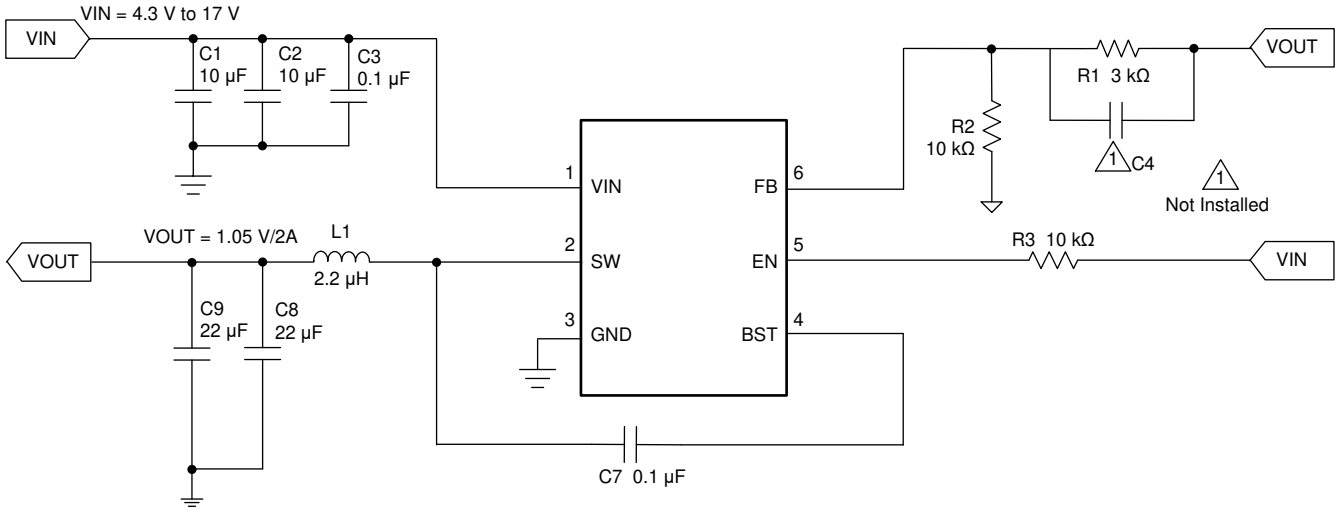

Figure 9-1. 1.05-V/2-A Reference Design

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9.2.1 Design Requirements

Table 9-1 shows the design parameters for this application.

Table 9-1. Design Parameters

PARAMETER	EXAMPLE VALUE
Input voltage range	4.3 to 17 V
Output voltage	1.05 V
Transient response, load step: 10% ~ 90% of full loading	ΔVout = ±5%
Input ripple voltage	200 mV
Output ripple voltage	20 mV
Output current rating	2 A
Operating frequency	580 kHz

9.2.2 Detailed Design Procedure

9.2.2.1 Output Voltage Resistors Selection

The output voltage is set with a resistor divider from the output node to the FB pin. TI recommends using 1% tolerance or better divider resistors. Start by using Equation 2 to calculate V_{OUT}.

To improve efficiency at very light loads, consider using larger value resistors. Too high of resistance is more susceptible to noise and voltage errors from the FB input current is more noticeable.

$$V_{out}=0.804 \times (1 + R_{FBT}/R_{FBB}) \tag{2}$$

9.2.2.2 Output Filter Selection

The LC filter used as the output filter has double pole at:

$$f_P = \frac{1}{2\pi\sqrt{L_{OUT} \times C_{OUT}}} \tag{3}$$

At low frequencies, the overall loop gain is set by the output set-point resistor divider network and the internal gain of the device. The low frequency phase is 180°. At the output filter pole frequency, the gain rolls off at a –40 dB per decade rate and the phase drops rapidly. D-CAP2 introduces a high frequency zero that reduces the gain roll off to –20 dB per decade and increases the phase to 90° one decade above the zero frequency. The inductor and capacitor for the output filter must be selected so that the double pole of Equation 3 is located below the high frequency zero but close enough that the phase boost provided be the high frequency zero provides adequate phase margin for a stable circuit. To meet this requirement use the values recommended in Table 9-2.

Table 9-2. Recommended Component Values

OUTPUT VOLTAGE (V)	R1 (kΩ)	R2 (kΩ)	TYP L1 (µH)	C8 + C9 (µF)			CFF (pF)
				MIN	TYP	MAX	
0.85	0.549	10.0	1.5	20	44	110	-
0.9	1.2	10.0	1.5	20	44	110	-
1	2.4	10.0	2.2	20	44	110	-
1.05	3.0	10.0	2.2	20	44	110	-
1.2	4.87	10.0	2.2	20	44	110	-
1.5	8.66	10.0	2.2	20	44	110	-
1.8	12.4	10.0	2.2	20	44	110	-
2.5	21.0	10.0	3.3	20	44	110	-
3.3	30.9	10.0	3.3	20	44	110	10-220
5	52.3	10.0	4.7	20	44	110	10-220

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Table 9-2. Recommended Component Values (continued)

OUTPUT VOLTAGE (V)	R1 (kΩ)	R2 (kΩ)	TYP L1 (µH)	C8 + C9 (µF)			CFF (pF)
				MIN	TYP	MAX	
6.5	70.5	10.0	4.7	20	44	110	10-220

The inductor peak-to-peak ripple current, peak current, and RMS current are calculated using Equation 4, Equation 5, and Equation 6. The inductor saturation current rating must be greater than the calculated peak current and the RMS or heating current rating must be greater than the calculated RMS current.

$$I_{P-P} = \frac{V_{OUT}}{V_{IN(MAX)}} \times \frac{V_{IN(MAX)} - V_{OUT}}{L_O \times f_{SW}} \tag{4}$$

$$I_{PEAK} = I_O + \frac{I_{P-P}}{2} \tag{5}$$

$$I_{LO(RMS)} = \sqrt{I_O^2 + \frac{1}{12} I_{P-P}^2} \tag{6}$$

For this design example, the calculated peak current is 2.35 A and the calculated RMS current is 2.01 A. The inductor used is a WE 74437349022.

The capacitor value and ESR determine the amount of output voltage ripple. The TPS562202S is intended to be used with ceramic or other low-ESR capacitors. Recommended values range from 20 µF to 110 µF. Use Equation 7 to determine the required RMS current rating for the output capacitor.

$$I_{CO(RMS)} = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{\sqrt{12} \times V_{IN} \times L_O \times f_{SW}} \tag{7}$$

For this design, two MuRata GRM21BR61A226ME44L 22-µF output capacitors are used. The typical ESR is 2 mΩ each. The calculated RMS current is 0.286 A and each output capacitor is rated for 4 A.

9.2.2.3 Input Capacitor Selection

The TPS562202S requires an input decoupling capacitor and a bulk capacitor is needed depending on the application. TI recommends a ceramic capacitor over 10 µF for the decoupling capacitor. An additional 0.1-µF capacitor (C3) from pin 1 to ground is necessary to provide additional high frequency filtering. The capacitor voltage rating needs to be greater than the maximum input voltage.

9.2.2.4 Bootstrap Capacitor Selection

A typical 0.1-µF ceramic capacitor must be connected between the BST to SW pin for proper operation. TI recommends to use a ceramic capacitor.

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9.2.3 Application Curves

Below waveforms are tested at VIN = 12 V, unless otherwise noted.

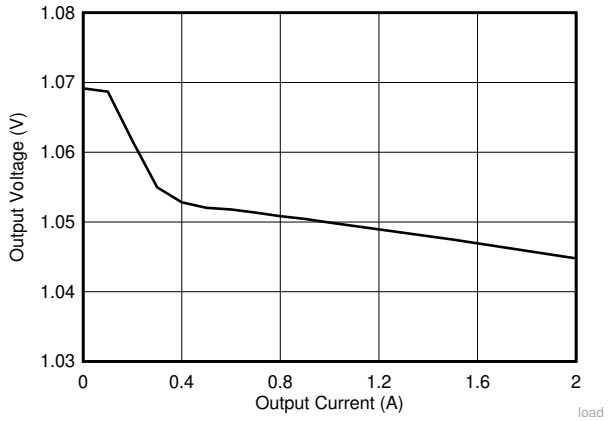

Figure 9-2. Load Regulation with Different Loading

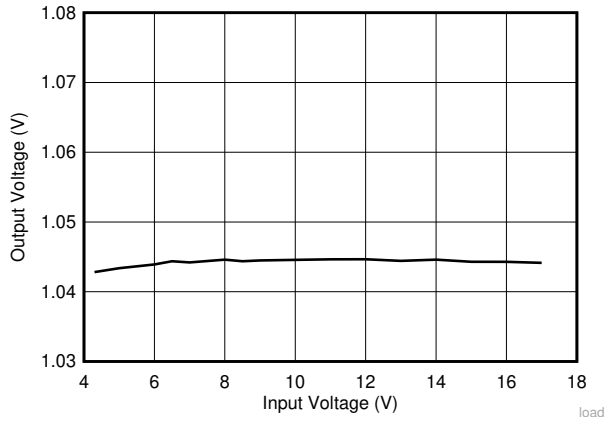

Figure 9-3. Load Regulation with Different Input Voltage

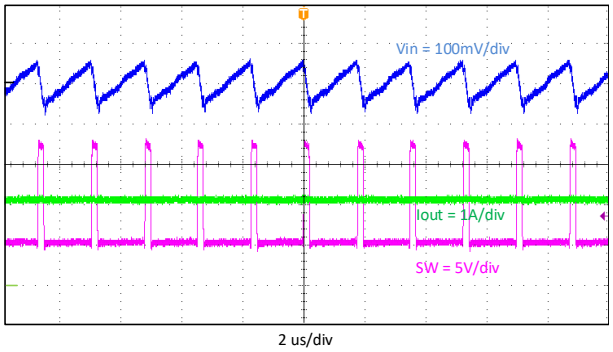

Figure 9-4. Input Voltage Ripple I_{out} = 2 A

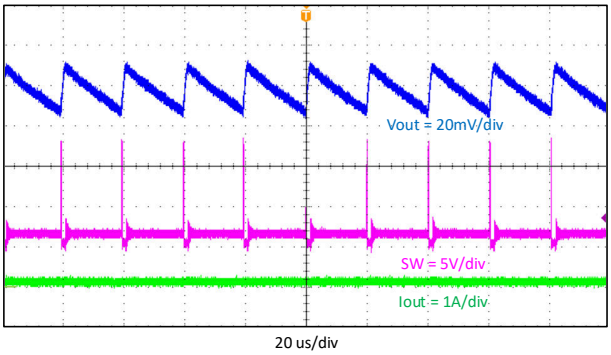

Figure 9-5. Output Voltage Ripple, I_{out} = 0.01 A

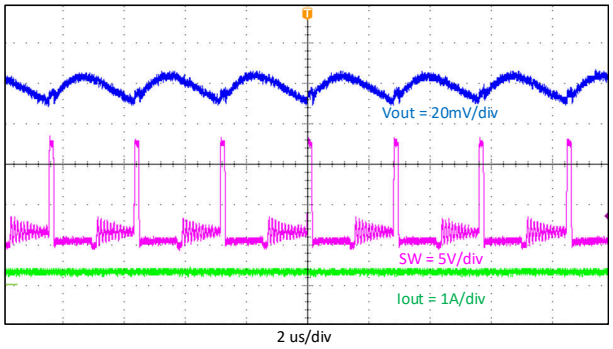

Figure 9-6. Output Voltage Ripple, I_{out} = 0.2 A

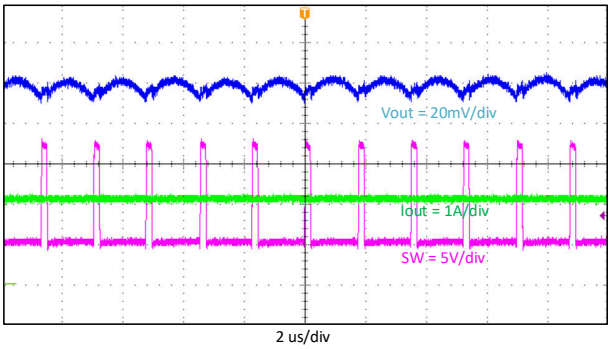

Figure 9-7. Output Voltage Ripple, I_{out} = 2 A

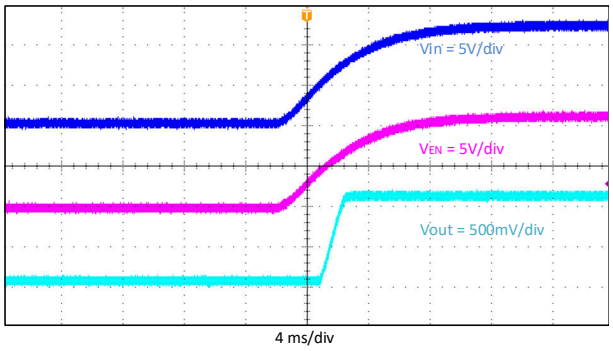

Figure 9-8. Start-up Relative to VIN

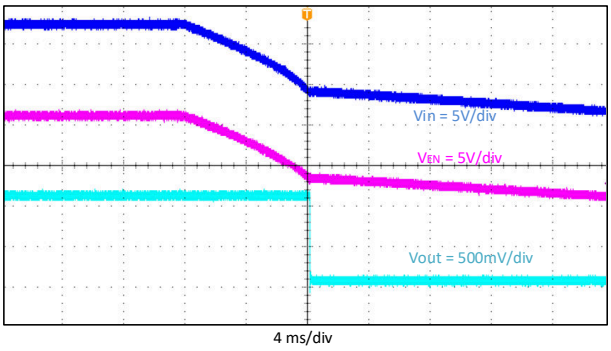

Figure 9-9. Shutdown Relative to VIN

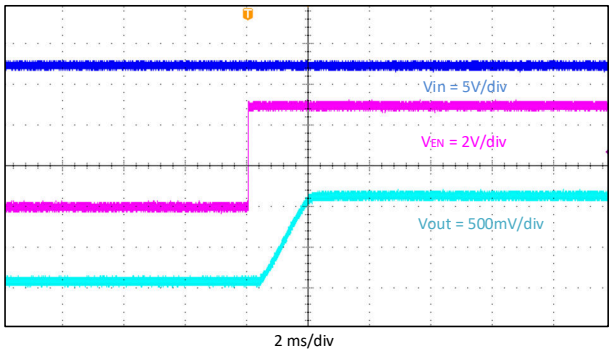

Figure 9-10. Start-up Relative to EN

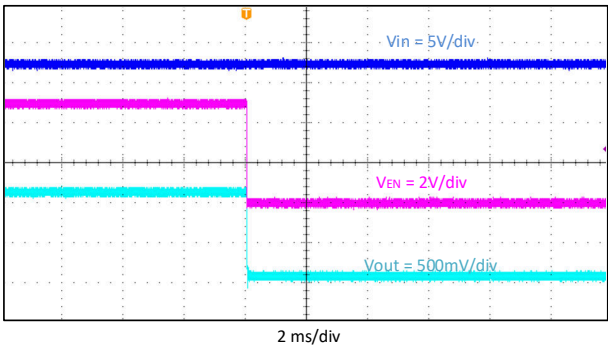

Figure 9-11. Shutdown Relative to EN

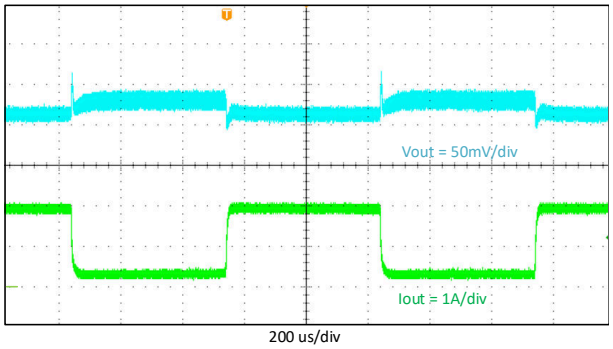

Figure 9-12. Transient Response, 0.2 to 1.8 A

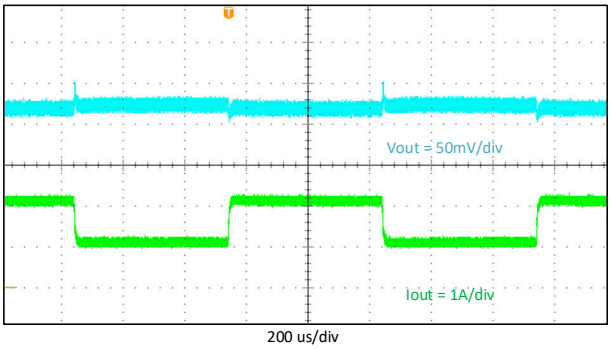

Figure 9-13. Transient Response, 1 to 2 A

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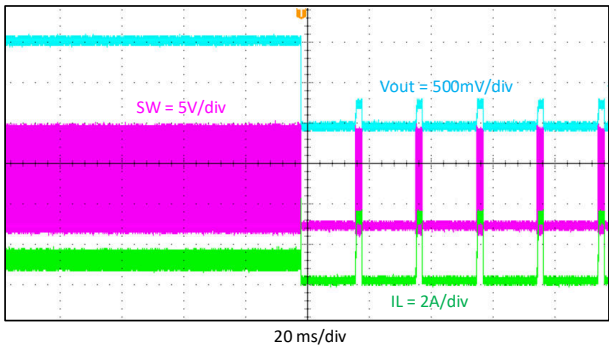

Figure 9-14. OC

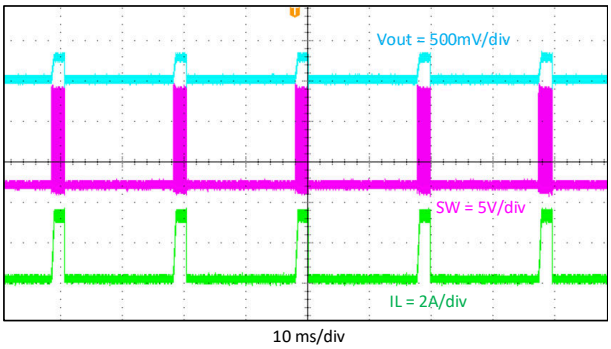

Figure 9-15. Hiccup, I_{out} = 5 A

10 Power Supply Recommendations

The TPS562202S is designed to operate from input supply voltage in the range of 4.3 V to 17 V. Buck converters require the input voltage to be higher than the output voltage for proper operation. The maximum recommended operating duty cycle is 75%. Using that criteria, the minimum recommended input voltage is VO / 0.75.

11 Layout

11.1 Layout Guidelines

1. VIN and GND traces should be as wide as possible to reduce trace impedance. The wide areas are also of advantage from the view point of heat dissipation.
2. The input capacitor and output capacitor should be placed as close to the device as possible to minimize trace impedance.
3. Provide sufficient vias for the input capacitor and output capacitor.
4. Keep the SW trace as physically short and wide as practical to minimize radiated emissions.
5. Do not allow switching current to flow under the device.
6. A separate VOUT path should be connected to the upper feedback resistor.
7. Make a Kelvin connection to the GND pin for the feedback path.
8. Voltage feedback loop should be placed away from the high-voltage switching trace, and preferably has ground shield.
9. The trace of the FB node should be as small as possible to avoid noise coupling.
10. The GND trace between the output capacitor and the GND pin should be as wide as possible to minimize its trace impedance.

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11.2 Layout Example

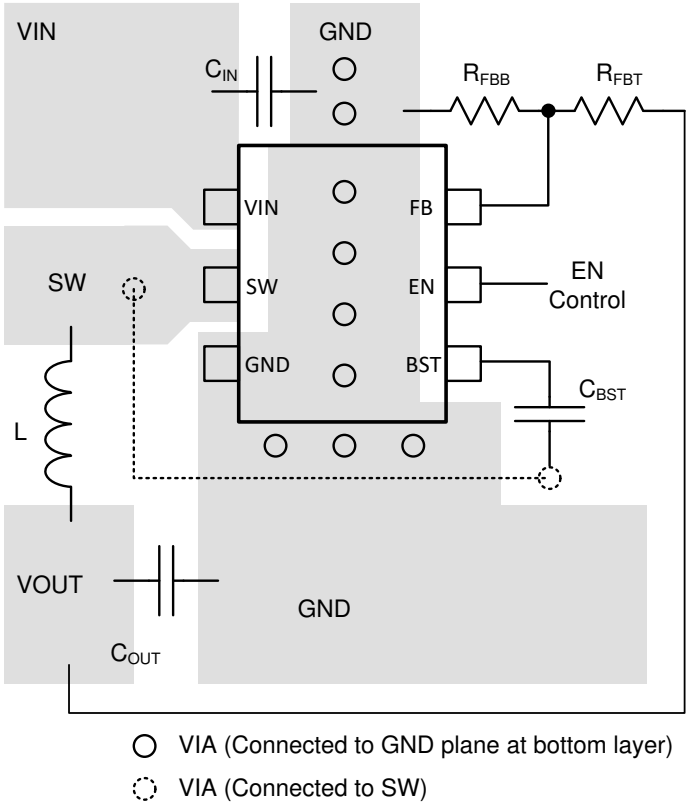

Figure 11-1. TPS562202S Layout

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12 Device and Documentation Support

12.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

12.2 Support Resources

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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12.4 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

12.5 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TPS562202SDRLR	Active	Production	SOT-5X3 (DRL) | 6	4000 | LARGE T&R	Yes	Call TI | Sn	Level-1-260C-UNLIM	-40 to 125	S202
TPS562202SDRLR.A	Active	Production	SOT-5X3 (DRL) | 6	4000 | LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	S202

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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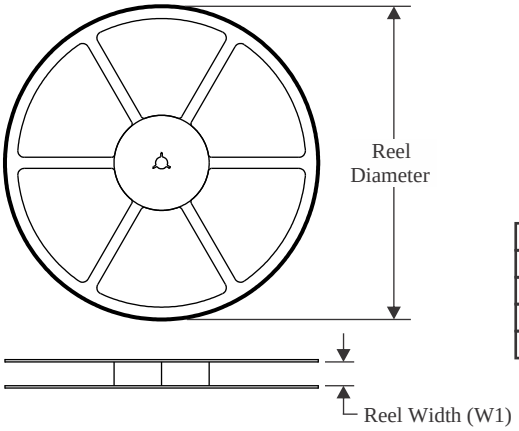
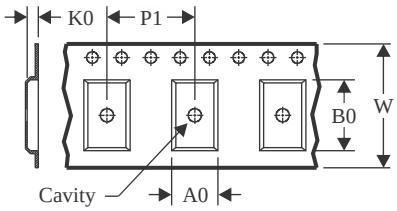
TAPE AND REEL INFORMATION

REEL DIMENSIONS

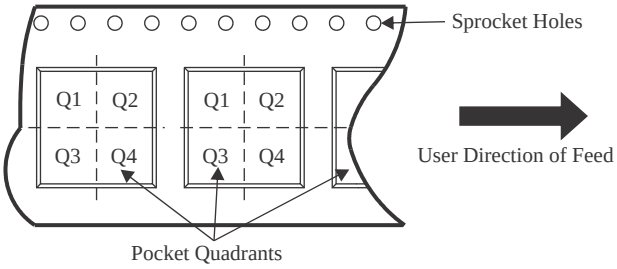


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

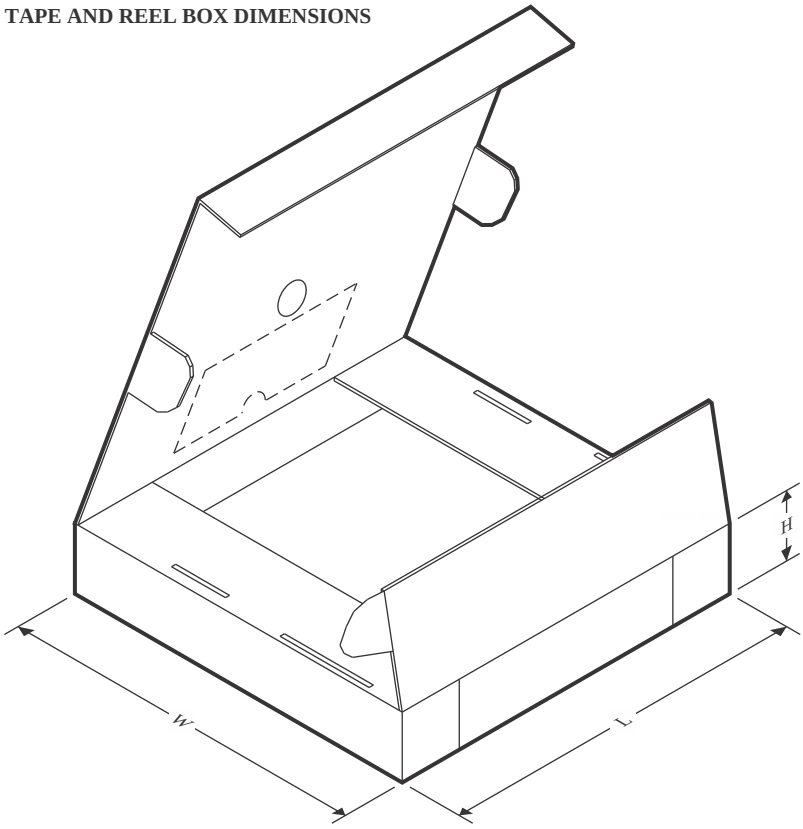
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

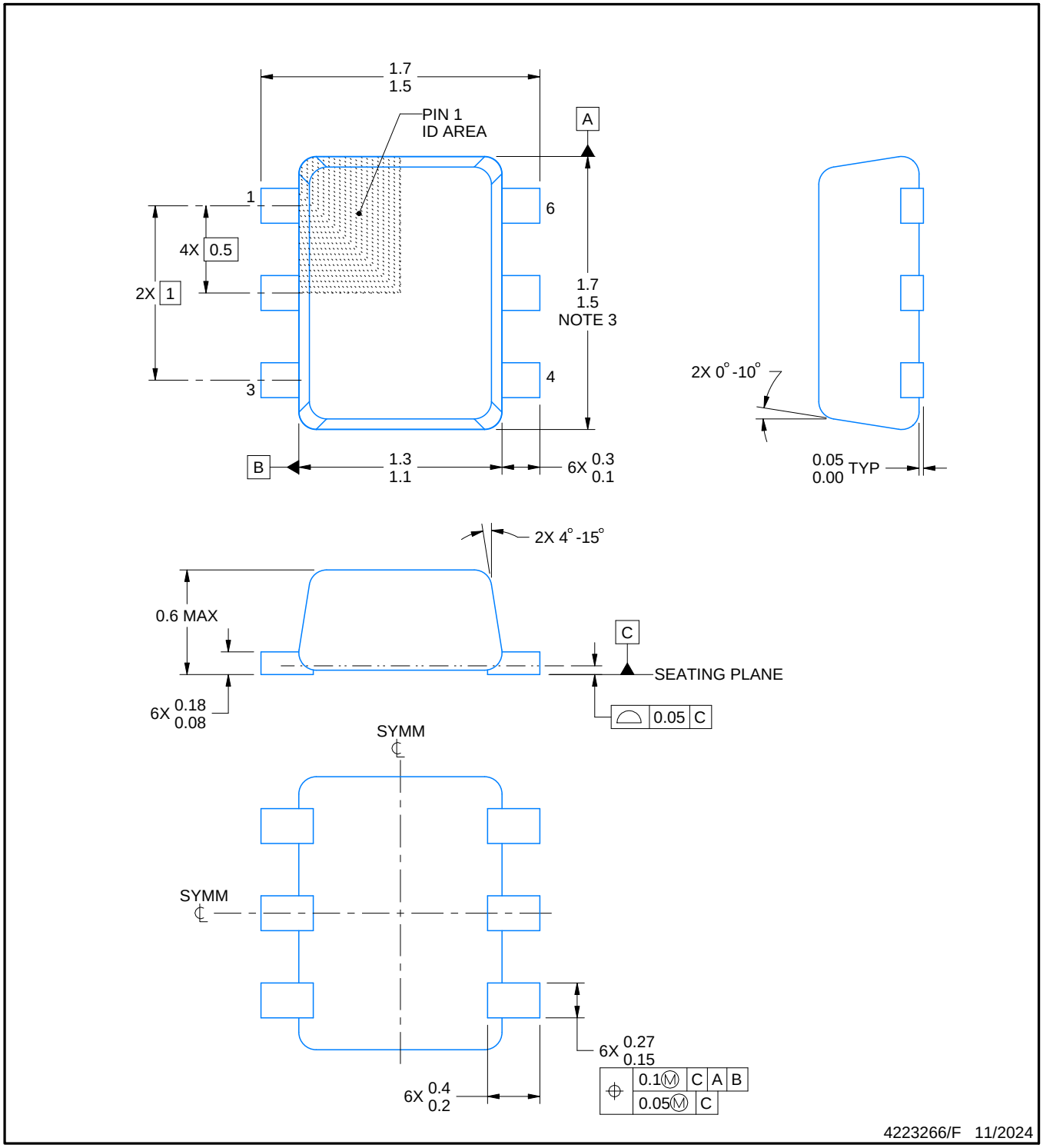
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS562202SDRLR	SOT-5X3	DRL	6	4000	180.0	8.4	1.8	1.8	0.75	4.0	8.0	Q3

TAPE AND REEL BOX DIMENSIONS



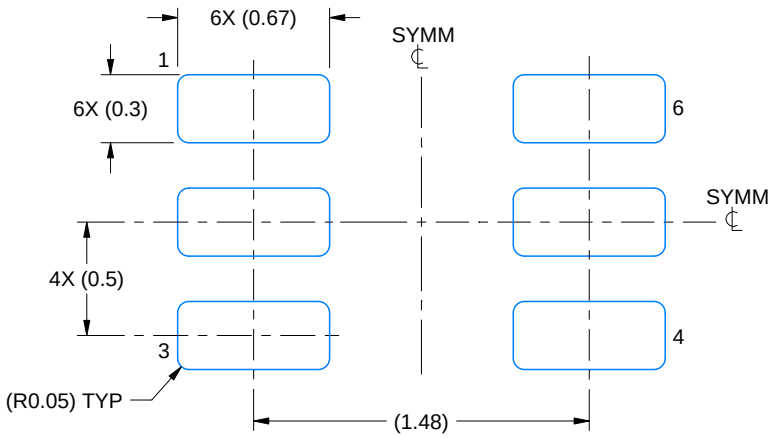
*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS562202SDRLR	SOT-5X3	DRL	6	4000	210.0	185.0	35.0

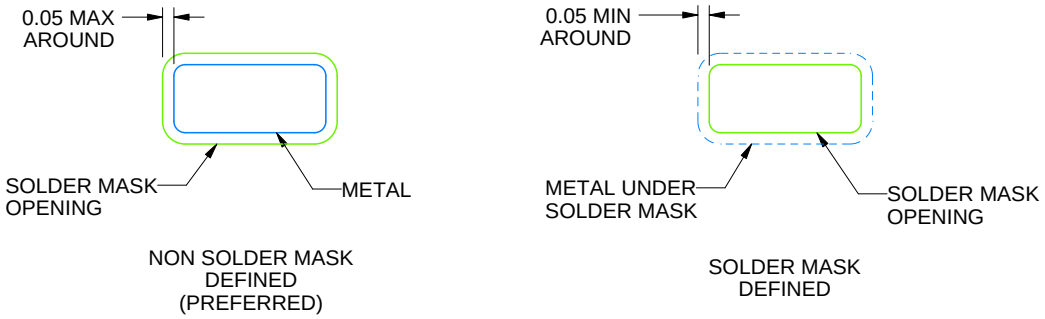


NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. Reference JEDEC registration MO-293 Variation UAAD



LAND PATTERN EXAMPLE
SCALE:30X

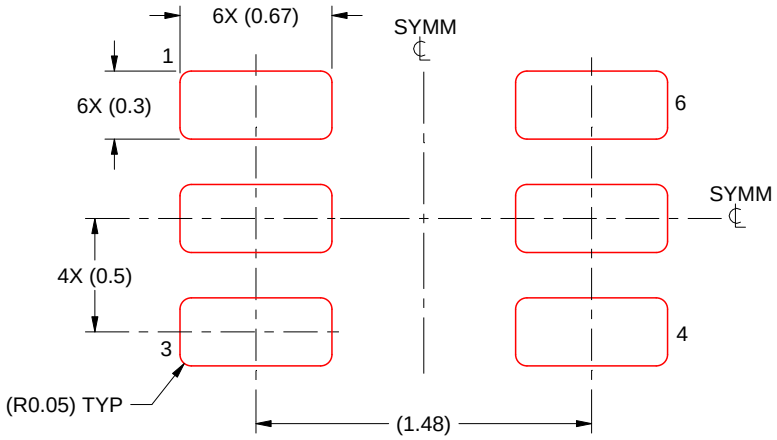


SOLDERMASK DETAILS

4223266/F 11/2024

NOTES: (continued)

5. Publication IPC-7351 may have alternate designs.
6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
7. Land pattern design aligns to IPC-610, Bottom Termination Component (BTC) solder joint inspection criteria.



SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE:30X

4223266/F 11/2024

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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