SymPol™ Transceiver

Check for Samples: SN65HVD96

FEATURES

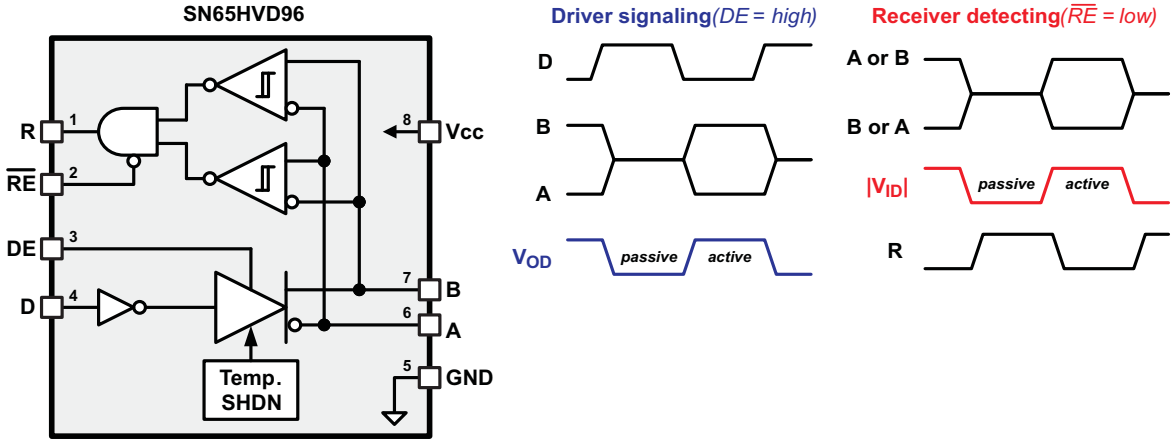
- **Communicate Without Errors on Normal or Reversed-Wire Bus Lines**
- **Up to 5 Mbps Signaling**
- **Industrial Temperature Range: –40°C to 85°C**
- **Symmetric Polarity Receiver**
- **Receiver Hysteresis > 100 mV**
- **Connect up to 32 Nodes Plus Parallel Terminators on one Bus, or Connect up to 200 Nodes on an Unterminated Bus**
- **Transient Protection**
  - **±12 kV Human Body Model on Bus Pins**
  - **±25 V Repetitive Transient Pulse on Bus Pins**
- **Additional Reliability Features:**
  - **Bus Standoff From –35 V to 40 V**
  - **Driver Output Short-Circuit Current Limit**
  - **Automatic Thermal Shutdown and Recovery**
- **Complies with ANSI/TIA-4963 Standard**

DESCRIPTION

The SN65HVD96 is specifically designed to meet the requirements for a transceiver which operates with no errors if the twisted-pair signal wires are connected normally or reversed. This allows for error free operation in applications where the signal wires may become inadvertently reversed during installation or maintenance. This feature is corrected internally so no intervention from the controller or operator is required. The SN65HVD96 complies with the requirements of ANSI/TIA-4963, *Electrical Characteristics of Reversible Balanced Voltage Digital Interface Circuits*.

Similar to RS-485, these transceivers can be used for point-to-point, multi-drop, or multi-point networks. Sympol™ devices are not backwards compatible with, but are an upgrade to, existing RS-485 networks. The pin-out is identical to the industry-standard SN75176 transceiver, allowing direct upgrade from RS-485 to SymPol. Current-limited differential outputs protect in case of driver contention on a party-line bus. High receiver input impedance allows connection of at least 32 nodes. Several fault tolerant features are integrated into the device to protect from operational hazards. Current limiting on the driver outputs protects against short-circuit faults, and operates independently on each driver output. An automatic thermal shutdown protects the driver circuits against over temperature conditions. The receiver output enters a deterministic failsafe state if the bus connection is left disconnected or if the bus wires are shorted together.

The small outline integrated circuit (SOIC) package saves board space compared to equivalent discrete implementations. These devices are fully characterized for operation over the industrial temperature range of –40°C to 85°C.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

Sympol is a trademark of Texas Instruments.

PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of the Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

Copyright © 2010–2011, Texas Instruments Incorporated

ABSOLUTE MAXIMUM RATINGS(1)

	VALUE	UNIT
Supply voltage, V_{CC}	–0.5 to 6	V
Voltage range at A or B	–35 to 40	V
Voltage range at logic pins (D, DE, $\overline{RE}$)	–0.3 to V_{CC}+0.3	V
Voltage input range, transient pulse, A and B, through 100Ω	±25	V
Voltage input transient pulse, A and B, per ISO 7637	±200	V
Differential voltage, $V_A – V_B$	–75 to +75	V
Electro-static discharge per JEDEC Std. 22 A114, A and B pins, Human Body Model	±12	kV
Electro-static discharge per JEDEC Std. 22 A114, all pins, Human Body Model	±5	kV
Electro-static discharge per JEDEC Std. 22 C101, all pins, Charged Device Model	±2	kV
Electro-static discharge per JEDEC Std. 22 A115, all pins, Machine Model	±200	V
Receiver output current	±20	mA
Junction temperature, T_J	170	°C
Continuous total power dissipation	(see Dissipation Rating Table)	

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

THERMAL INFORMATION

THERMAL METRIC(1)			SN65HVD96 8 PINS SOIC	UNITS
θ_{JA}	Junction-to-ambient thermal resistance(2)		124.5	°C/W
$\theta_{JC(top)}$	Junction-to-case(top) thermal resistance (3)		55.9	
θ_{JB}	Junction-to-board thermal resistance (4)		50.2	
ψ_{JT}	Junction-to-top characterization parameter (5)		4.9	
ψ_{JB}	Junction-to-board characterization parameter (6)		46.0	
$\theta_{JC(bottom)}$	Junction-to-case(bottom) thermal resistance (7)		n/a	
		TEST CONDITIONS		
P_d	Power Dissipation	VCC = 5.25 V, TJ = 150°C, RL = 300 Ω, CL = 50 pF (driver), CL = 15 pF (receiver), unterminated(8)	188	mW
		VCC = 5.25 V, TJ = 150°C, RL = 100 Ω, CL = 50 pF (driver), CL = 15 pF (receiver), RS-422 load(8)	251	
		VCC = 5.25 V, TJ = 150°C, RL = 54 Ω, CL = 50 pF (driver), CL = 15 pF (receiver), RS-485 load(8)	319	

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, SPRA953.
(2) The junction-to-ambient thermal resistance under natural convection is obtained in a simulation on a JEDEC-standard, high-K board, as specified in JESD51-7, in an environment described in JESD51-2a.
(3) The junction-to-case (top) thermal resistance is obtained by simulating a cold plate test on the package top. No specific JEDEC-standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.
(4) The junction-to-board thermal resistance is obtained by simulating in an environment with a ring cold plate fixture to control the PCB temperature, as described in JESD51-8.
(5) The junction-to-top characterization parameter, ψ_{JT}, estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining θ_{JA}, using a procedure described in JESD51-2a (sections 6 and 7).
(6) The junction-to-board characterization parameter, ψ_{JB}, estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining θ_{JA} , using a procedure described in JESD51-2a (sections 6 and 7).
(7) The junction-to-case (bottom) thermal resistance is obtained by simulating a cold plate test on the exposed (power) pad. No specific JEDEC standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.
(8) Driver and receiver enabled, 50% duty cycle square-wave signal at 5 Mbps.

Copyright © 2010–2011, Texas Instruments Incorporated

RECOMMENDED OPERATING CONDITIONS

		MIN	NOM	MAX	UNIT
V_{CC}	Supply voltage	4.75	5	5.25	V
V_I	Input voltage at any bus terminal (separately or common mode)(1)	–7		12	V
V_{IH}	High-level input voltage (Driver, driver enable, and receiver enable inputs)	2		V_{CC}	V
V_{IL}	Low-level input voltage (Driver, driver enable, and receiver enable inputs)	0		0.8	V
V_{ID}	Differential input voltage	–12		12	V
I_O	Output current, Driver	–70		70	mA
I_O	Output current, Receiver	–2		2	mA
R_L	Differential load resistance	54	60		Ω
$1/t_{UI}$	Signaling rate	0		5	Mbps
T_A	Operating free-air temperature	–40		85	°C

(1) The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.

ELECTRICAL CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
$\lvert V_{OD(ACT)}\rvert$	Driver differential output voltage magnitude (active)	RS-485 common-mode load, see Figure 2		1.5			V
		RS-485 differential load R_L = 54 Ω, C_L = Open, see Figure 3		1.5			
		RS-422 differential load R_L = 100 Ω, C_L = Open, see Figure 3		2			
$\lvert V_{OD(PAS)}\rvert$	Driver differential output voltage magnitude (passive)	RS-485 common-mode load, See Figure 2				50	mV
		RS-485 differential load R_L = 54 Ω, C_L = Open, see Figure 3				20	
		RS-422 differential load R_L = 100 Ω, C_L = Open, see Figure 3				25	
		No Load				50	
$V_{OC(SS)}$	Steady-state common-mode output voltage	Voc = (V_A + V_B) / 2, R_L = 54Ω		1	Vcc/2	3	V
ΔV_{OC}	Change in differential driver output common-mode voltage	$Voc_{(D=High)}$ – $Voc_{(D=Low)}$, R_L = 54Ω		–0.2		0.2	V
$V_{IT(ACT)}$	Active-going receiver differential input threshold	V_{ID} = V_A – V_B or V_{ID} = V_B – V_A			775	900	mV
$V_{IT(PASS)}$	Passive-going receiver differential input threshold			500	625		mV
V_{HYS}	Receiver differential input threshold hysteresis (VIT(ACT) - VIT(PASS))			100	150		mV
V_{OH}	Receiver high-level output voltage	–20 µA ≥ I_O ≥ –2 mA		2.4		3.7	V
V_{OL}	Receiver low-level output voltage	20 µA ≤ I_O ≤ 2 mA				0.4	V
I_I	Logic pins input current			–100		100	µA
I_{OZ}	Receiver output high-impedance current	V_O = 0 V or Vcc, $\overline{RE}$ at Vcc		–10		10	uA
I_{OS}	Driver short-circuit output current	–7 V < Vo < +12 V		–350		350	mA
I_I	Bus input current (passive driver)	Vcc = 4.75 to 5.25 V or Vcc=0V, DE at 0V, other bus pin at 0V	V_I = 12 V			1	mA
			V_I = –7 V	–0.8			mA
I_{CC}	Supply current (quiescent), no load					20	mA
R_{ID}	Differential input resistance	DE at OV, Vcm = Vcc/2		24	40	57	kΩ

Copyright © 2010–2011, Texas Instruments Incorporated

SWITCHING CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
DRIVER						
t_{rise} , t_{fall}	Driver differential output rise/fall time	R_L= 54 Ω, C_L= 50 pF, See Figure 3		15	30	ns
t_{pAP} , t_{pPA}	Driver propagation delay			40	80	ns
$t_{SK(P)}$	Driver differential output pulse skew, $\|t_{pAP} - t_{pPA}\|$			1	10	ns
t_{pZA}, t_{pAZ}	Driver enable/disable time	D = GND, R_L= 54 Ω, C_L= 50 pF, See Figure 4		50	80	ns
RECEIVER						
t_{rise}, t_{fall}	Receiver output rise/fall time	C_L= 15 pF, See Figure 5		8	15	ns
t_{PHL} , t_{PLH}	Receiver propagation delay time			70	90	ns
$t_{SK(P)}$	Receiver output pulse skew, $\|t_{PHL} - t_{PLH}\|$			5	15	ns
t_{PZL}, t_{PZH}, t_{PLZ}, t_{PHZ}	Receiver enable/disable time	See Figure 6		20	100	ns

FUNCTION TABLE

DRIVER	DE	D	V_{OD}	
	L or OPEN	X	Z	Driver Disabled (Passive)
	H	L	H	Driver Active
		H or Open	Z	Driver Passive
RECEIVER	$\overline{\text{RE}}$	V_{ID}	R	
	H or OPEN	X	Z	Receiver Disabled
	L	V_{ID} < –0.9 V	L	Active Bit Received
		–0.9 V < V_{ID} < –0.5	?	Indeterminate bus
		–0.5 V < V_{ID} < 0.5 V	H	Passive Bit Received
		0.5 V < V_{ID} < 0.9 V	?	Indeterminate bus
		0.9 V < V_{ID}	L	Active Bit Received
		Open, Short, Idle	H	Failsafe Condition

Copyright © 2010–2011, Texas Instruments Incorporated

DEVICE INFORMATION

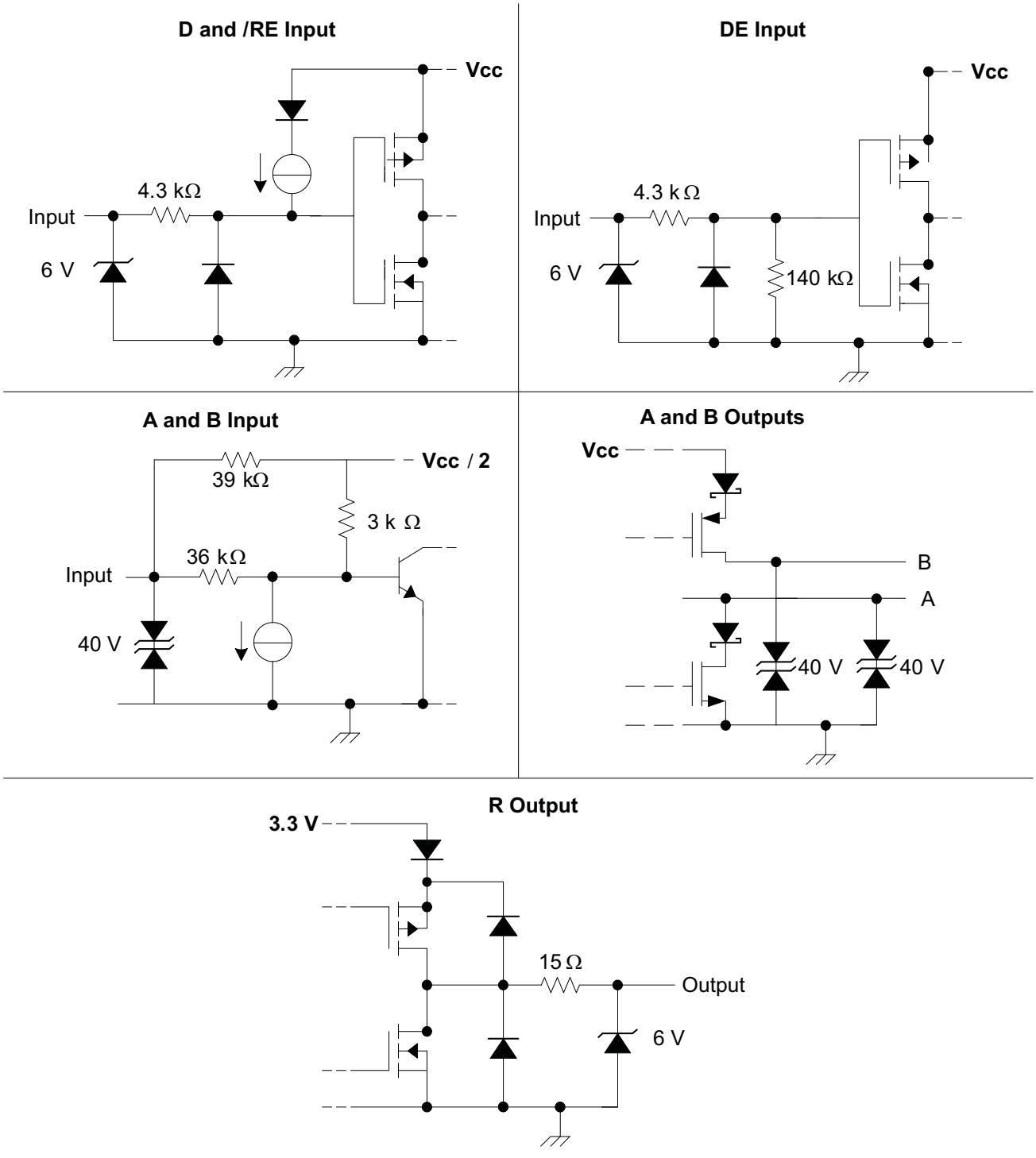
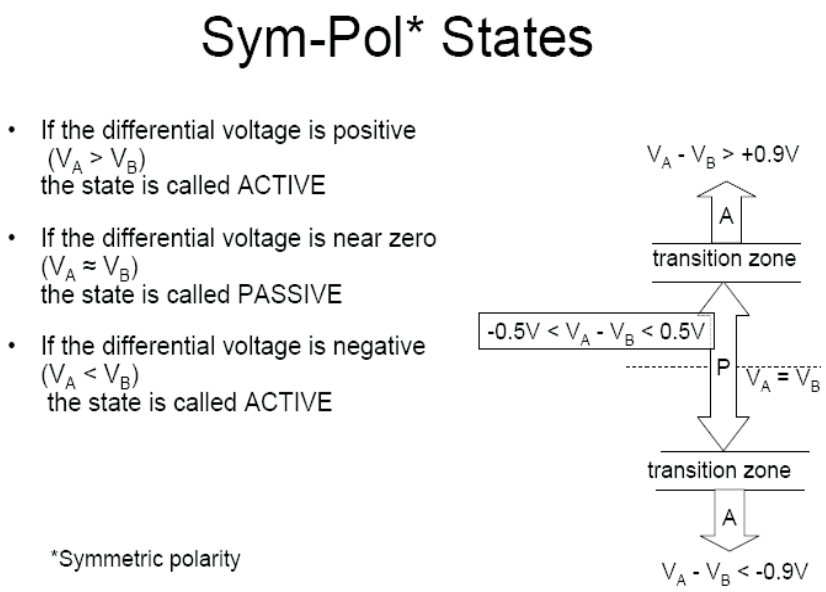
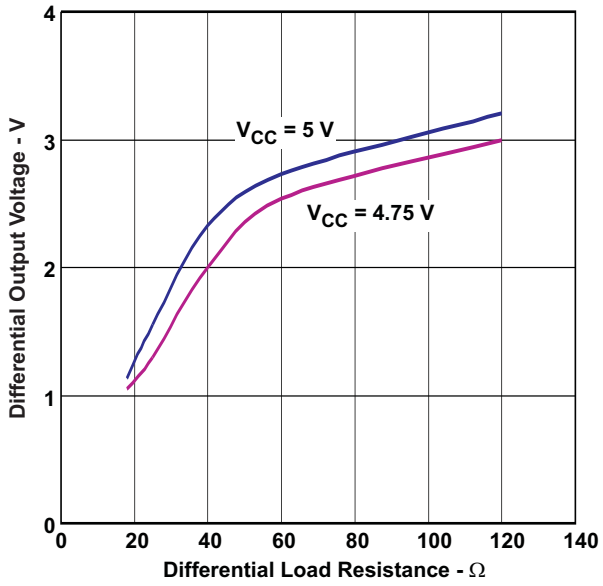


Figure 1. Equivalent Input and Output Schematic Diagrams

APPLICATION INFORMATION

Sympol™ States





Using Sympol to Achieve Immunity to Crossed Bus Wire

Many applications which use RS-422 or RS-485 are wired on-site by third-party installers. This opens the door to the possibility of miss-wiring, especially for far-flung networks with many stations (or nodes). Neither RS-422 nor RS-485 allows correct communications when the bus wires (typically a twisted-pair) are swapped.

The existing solutions for this case require active intervention, either by the installer or maintenance technician, or by an automated controller. Sympol offers a way to replace RS-422 or RS-485 networks with communication over the same bus lines. Due to the innovative nature of Sympol signaling levels, a Sympol network is immune to communication errors caused by crossed bus wires.

Signaling levels are similar to RS-422 and RS-485, so signaling rates, cable lengths, and noise immunity will be comparable.

Sympol is NOT interoperable with RS-422 or RS-485; that is, designers may not mix Sympol nodes with existing RS-485 nodes.

Copyright © 2010–2011, Texas Instruments Incorporated

Number of Nodes

The SN65HV96 specifications for bus-pin impedance are similar to a standard one unit-load (1 UL) RS-485 device. This allows designers to attach up to 32 nodes plus two parallel termination resistors on a single bus segment. In applications where the standard trunk-and-stub arrangement of RS-485 is not practical, or if mis-termination may occur during installation, it may be desirable to not use parallel termination on the bus lines. In these applications, the number of nodes allowed can be up to about 200, while still maintaining high driver output amplitude. The bus pin impedance is approximated as 12 kΩ, therefore 200 devices in parallel present differential loading similar to the 60 Ω termination resistance.

PARAMETER MEASUREMENT INFORMATION

Input generator rate is 100kbps, 50% duty-cycle, transition times less than 6 ns for all figures.

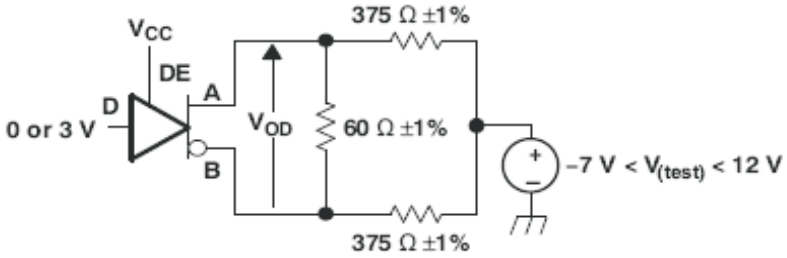


Figure 2. Measurement of Driver Differential Output Voltage With Common-Mode Load

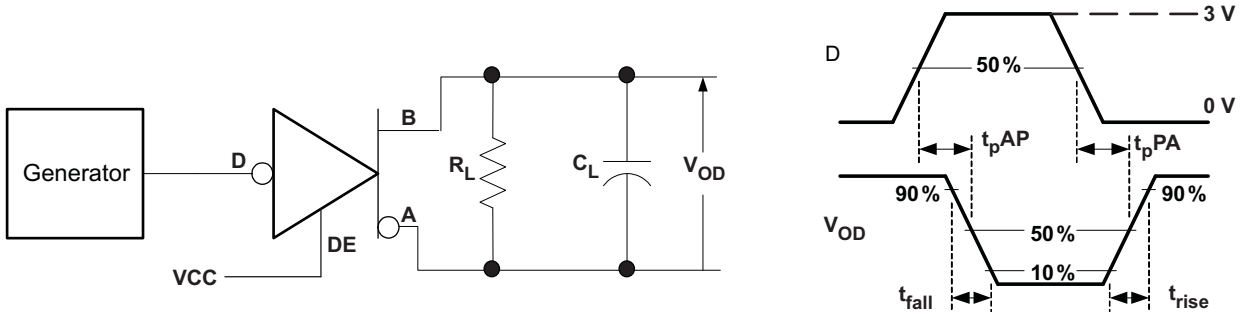


Figure 3. Measurements of Driver Differential Output Rise and Fall Times and Propagation delays

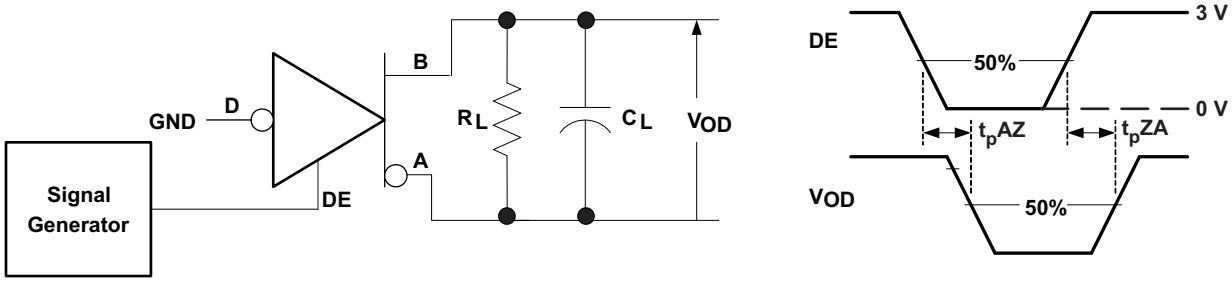


Figure 4. Measurements of Driver Enable and Disable Times With Active Output

PARAMETER MEASUREMENT INFORMATION (continued)

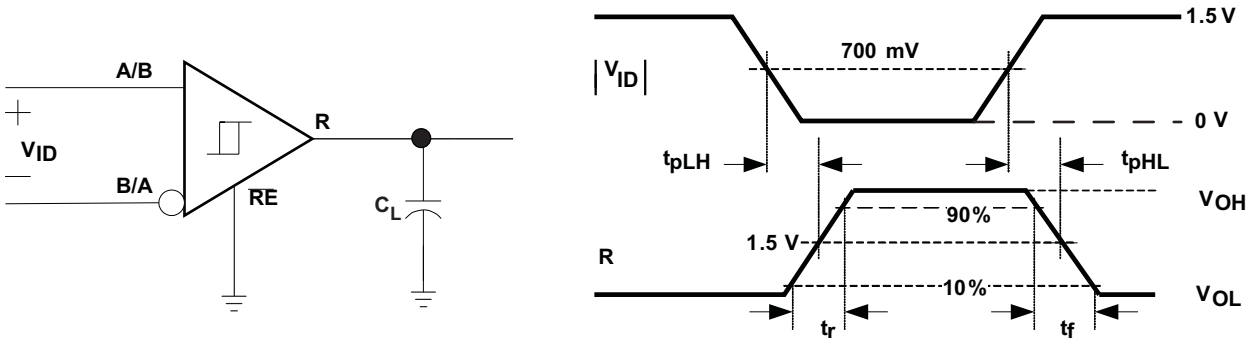


Figure 5. Measurement of Receiver Output Rise and Fall Times and Propagation Delays

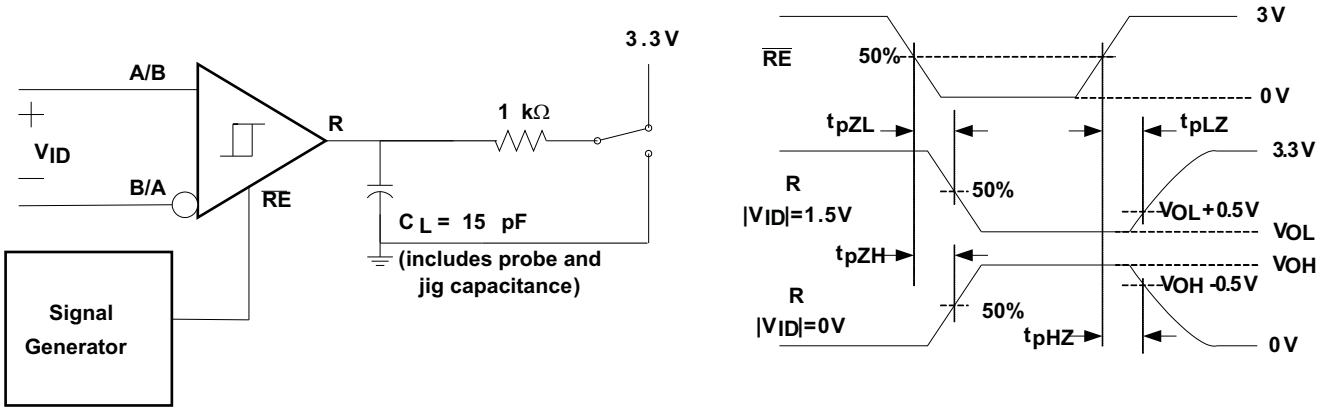


Figure 6. Measurement of Receiver Enable Times With Driver Disabled

Copyright © 2010–2011, Texas Instruments Incorporated

REVISION HISTORY

Changes from Original (June 2010) to Revision A **Page**

- Changed the 4th bullet in Features to 2 bulleted items 1
- Changed the 6th bullet in Features to read "Connect up to 32 Nodes Plus Parallel Terminators on one Bus, or Connect up to 200 Nodes on an Unterminated Bus" 1
- Deleted italics from party line and failsafe in second paragraph 1
- Added to protect after Several fault.....into the device sentence, second paragraph 1
- Changed in abs max table from 7V to 6V 2
- Deleted deleted 'dc' from the VALUE column in 2nd and 4th parameter 2
- Added commas after the name of the test specification, A224, 2 places, C101 and A115. Added the word pins after A and B in the first Human Body Model row 2
- Deleted 290 in the THERMAL Table from the first cell under TEST Conditions. Deleted 5V supply from all three cells. 2
- Added typical characteristics graph to Application Information Section 6
- Added section to Application Information titled Number of Nodes 7

Changes from Revision A (December 2010) to Revision B **Page**

- Changed revision A, December 2010 to Rev B, October 2011 1
- Added new ListItem to the FEATURES: 'Complies .....Standard' 1
- Added last sentence to the first paragraph of DESCRIPTION 1
- Added Differential voltage.....V row to the ABS MAX RATINGS table 2
- Added differential input resistance specification to Electrical Characteristics table. 3

Copyright © 2010–2011, Texas Instruments Incorporated

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
SN65HVD96D	Obsolete	Production	SOIC (D) | 8	-	-	Call TI	Call TI	-40 to 85	HVD96
SN65HVD96DR	Active	Production	SOIC (D) | 8	2500 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	HVD96
SN65HVD96DR.A	Active	Production	SOIC (D) | 8	2500 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	HVD96

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

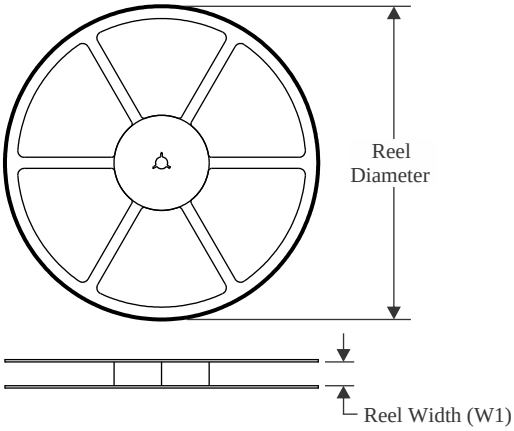
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

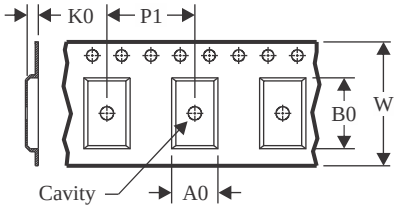
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION

REEL DIMENSIONS

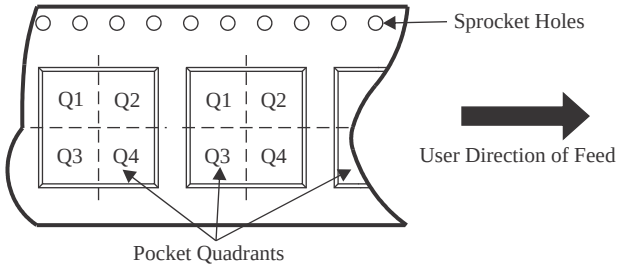


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

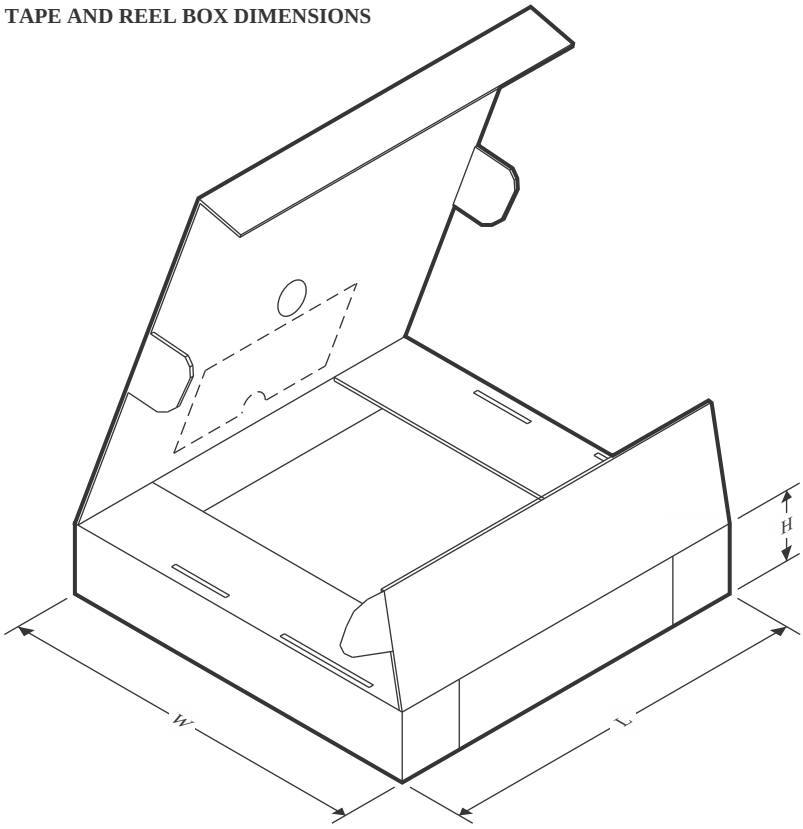
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

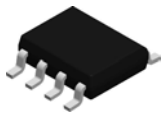
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
SN65HVD96DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
SN65HVD96DR	SOIC	D	8	2500	356.0	356.0	35.0

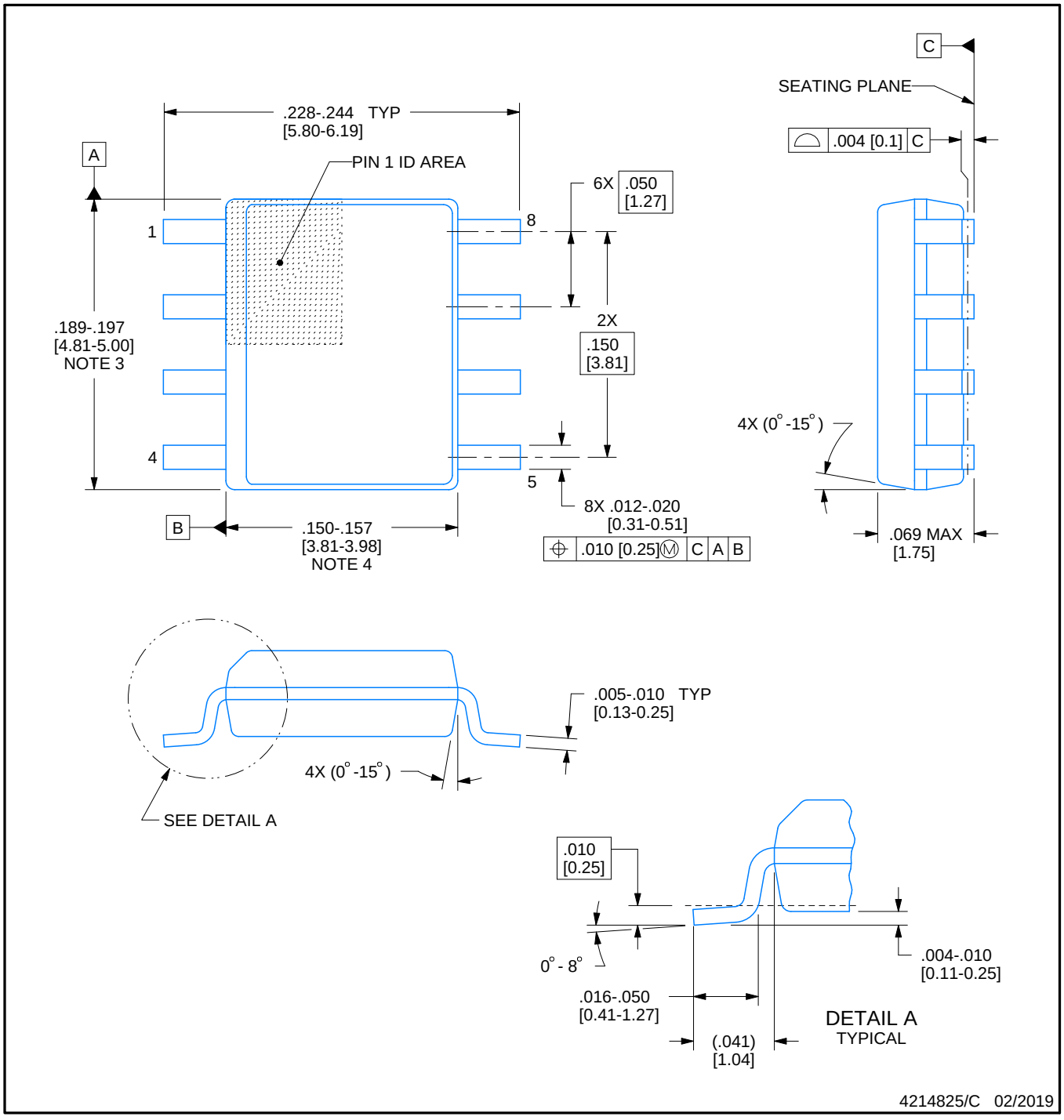


PACKAGE OUTLINE

D0008A

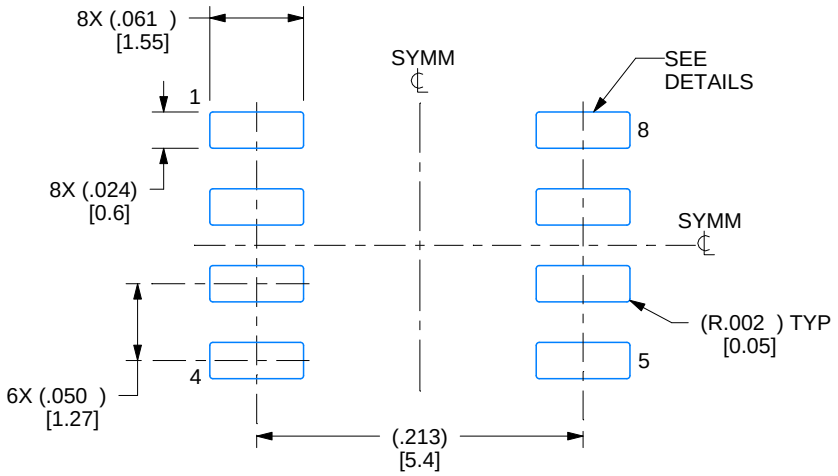
SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT

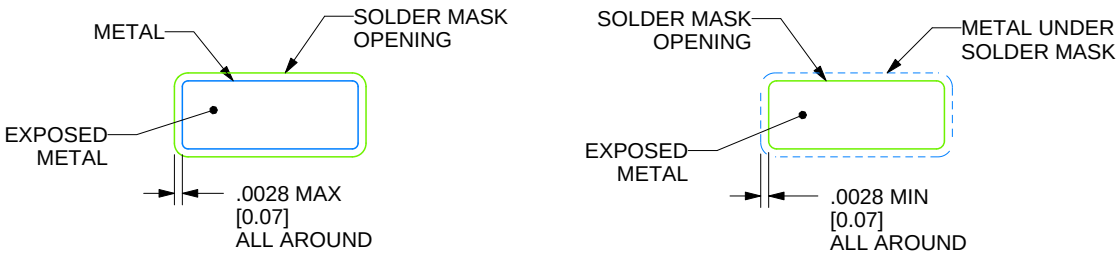


NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:8X



SOLDER MASK DETAILS

4214825/C 02/2019

NOTES: (continued)

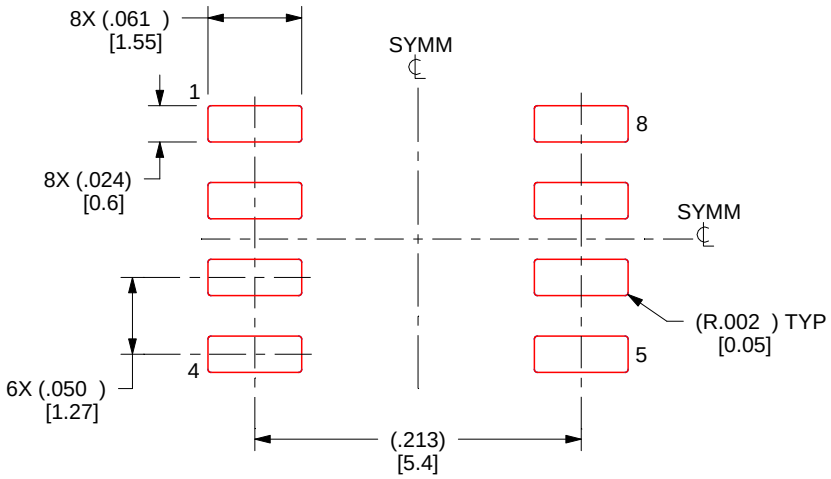
6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE
BASED ON .005 INCH [0.125 MM] THICK STENCIL
SCALE:8X

4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES “AS IS” AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI’s products are provided subject to TI’s Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI’s provision of these resources does not expand or otherwise alter TI’s applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2025, Texas Instruments Incorporated