

EEPROM Serial 16-Kb Microwire - Automotive Grade 1, Wettable Flank UDFN Package

NV93C86WF

Description

The NV93C86WF is an EEPROM Serial 16-Kb Microwire Automotive Grade 1 device, which is configured as either registers of 16 bits (ORG pin at V_{CC}) or 8 bits (ORG pin at GND) in a Wettable Flank UDFN Package. Each register can be written (or read) serially by using the DI (or DO) pin. The NV93C86 is manufactured using onsemi's advanced CMOS EEPROM floating gate technology. The device is designed to endure 1,000,000 program/erase cycles and has a data retention of 100 years. The device is available in 8-pin UDFN package.

Features

- Automotive AEC-Q100 Grade 1 (–40°C to +125°C) Qualified
- High Speed Operation: 2 MHz
- Low Power CMOS Technology
- 2.5 V to 5.5 V Operation
- Selectable x8 or x16 Memory Organization
- Self-timed Write Cycle with Auto-clear
- Hardware and Software Write Protection
- Power-up Inadvertent Write Protection
- Sequential Read
- Program Enable (PE) Pin
- 1,000,000 Program/Erase Cycles
- 100 Year Data Retention
- UDFN-8 Wettable Flank Package
- These Devices are Pb-Free, Halogen Free/BFR Free, and RoHS Compliant

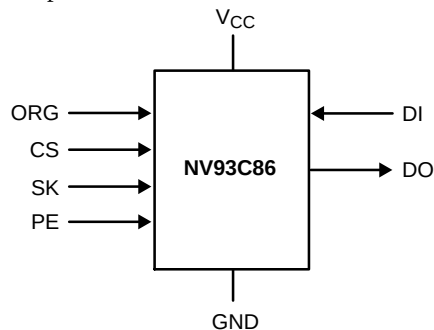


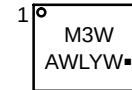
Figure 1. Functional Symbol

Note: When the ORG pin is connected to V_{CC}, the x16 organization is selected. When it is connected to ground, the x8 pin is selected. If the ORG pin is left unconnected, then an internal pull-up device will select the x16 organization.



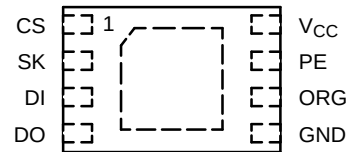
UDFN8
MU SUFFIX
CASE 517DH

MARKING DIAGRAM



M3W = Specific Device Code
A = Assembly Location
WL = Wafer Lot
Y = Year
W = Work Week
▪ = Pb-Free Package

PIN CONFIGURATION



UDFN-8

PIN FUNCTION

Pin Name	Function
CS	Chip Select
SK	Clock Input
DI	Serial Data Input
DO	Serial Data Output
V _{CC}	Power Supply
GND	Ground
ORG	Memory Organization
PE	Program Enable

ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 6 of this data sheet.

Table 1. ABSOLUTE MAXIMUM RATINGS

Parameters	Ratings	Units
Storage Temperature	-65 to +150	°C
Voltage on Any Pin with Respect to Ground (Note 1)	-0.5 to +6.5	V

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

1. The DC input voltage on any pin should not be lower than -0.5 V or higher than $V_{CC} + 0.5$ V. During transitions, the voltage on any pin may undershoot to no less than -1.5 V or overshoot to no more than $V_{CC} + 1.5$ V, for periods of less than 20 ns.

Table 2. RELIABILITY CHARACTERISTICS (Note 2)

Symbol	Parameter	Min	Units
N_{END} (Note 3)	Endurance	1,000,000	Program / Erase Cycles
T_{DR}	Data Retention	100	Years

2. These parameters are tested initially and after a design or process change that affects the parameter according to appropriate AEC-Q100 and JEDEC test methods.
3. Block Mode, $V_{CC} = 5$ V, 25°C.

Table 3. D.C. OPERATING CHARACTERISTICS

($V_{CC} = +2.5$ V to +5.5 V, $T_A = -40^\circ\text{C}$ to +125°C unless otherwise specified.)

Symbol	Parameter	Test Conditions	Min	Max	Units
I_{CC1}	Supply Current (Write)	Write, $V_{CC} = 5.0$ V		2	mA
I_{CC2}	Supply Current (Read)	Read, DO open, $f_{SK} = 2$ MHz, $V_{CC} = 5.0$ V		500	μA
I_{SB1}	Standby Current (x8 Mode)	$V_{IN} = \text{GND or } V_{CC}$ $CS = \text{GND, ORG} = \text{GND}$		5	μA
I_{SB2}	Standby Current (x16 Mode)	$V_{IN} = \text{GND or } V_{CC}$ $CS = \text{GND, ORG} = \text{Float or } V_{CC}$		3	μA
I_{LI}	Input Leakage Current	$V_{IN} = \text{GND to } V_{CC}$		2	μA
I_{LO}	Output Leakage Current	$V_{OUT} = \text{GND to } V_{CC}$ $CS = \text{GND}$		2	μA
V_{IL1}	Input Low Voltage	$4.5 \text{ V} \leq V_{CC} < 5.5 \text{ V}$	-0.1	0.8	V
V_{IH1}	Input High Voltage	$4.5 \text{ V} \leq V_{CC} < 5.5 \text{ V}$	2	$V_{CC} + 1$	V
V_{IL2}	Input Low Voltage	$2.5 \text{ V} \leq V_{CC} < 4.5 \text{ V}$	0	$V_{CC} \times 0.2$	V
V_{IH2}	Input High Voltage	$2.5 \text{ V} \leq V_{CC} < 4.5 \text{ V}$	$V_{CC} \times 0.7$	$V_{CC} + 1$	V
V_{OL1}	Output Low Voltage	$4.5 \text{ V} \leq V_{CC} < 5.5 \text{ V}$, $I_{OL} = 2.1$ mA		0.4	V
V_{OH1}	Output High Voltage	$4.5 \text{ V} \leq V_{CC} < 5.5 \text{ V}$, $I_{OH} = -400$ μA	2.4		V
V_{OL2}	Output Low Voltage	$2.5 \text{ V} \leq V_{CC} < 4.5 \text{ V}$, $I_{OL} = 1$ mA		0.2	V
V_{OH2}	Output High Voltage	$2.5 \text{ V} \leq V_{CC} < 4.5 \text{ V}$, $I_{OH} = -100$ μA	$V_{CC} - 0.2$		V

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

Table 4. PIN CAPACITANCE (Note 4)

Symbol	Test	Conditions	Min	Typ	Max	Units
C_{OUT}	Output Capacitance (DO)	$V_{OUT} = 0$ V			5	pF
C_{IN}	Input Capacitance (CS, SK, DI, ORG)	$V_{IN} = 0$ V			5	pF

Table 5. POWER-UP TIMING (Notes 4, 5)

Symbol	Parameter	Max	Units
t_{PUR}	Power-up to Read Operation	1	ms
t_{PUW}	Power-up to Write Operation	1	ms

Table 6. A.C. TEST CONDITIONS

Input Rise and Fall Times	≤ 50 ns	
Input Pulse Voltages	0.4 V to 2.4 V	$4.5 \text{ V} \leq V_{CC} \leq 5.5 \text{ V}$
Timing Reference Voltages	0.8 V, 2.0 V	$4.5 \text{ V} \leq V_{CC} \leq 5.5 \text{ V}$
Input Pulse Voltages	$0.2 V_{CC}$ to $0.7 V_{CC}$	$2.5 \text{ V} \leq V_{CC} \leq 4.5 \text{ V}$
Timing Reference Voltages	$0.5 V_{CC}$	$2.5 \text{ V} \leq V_{CC} \leq 4.5 \text{ V}$
Output Load	Current Source I_{OLmax}/I_{OHmax} ; $CL = 100$ pF	

4. These parameters are tested initially and after a design or process change that affects the parameter.
5. t_{PUR} and t_{PUW} are the delays required from the time V_{CC} is stable until the specified operation can be initiated.
6. The input levels and timing reference points are shown in the "A.C. Test Conditions" table.

Table 7. A.C. CHARACTERISTICS ($V_{CC} = +2.5 \text{ V}$ to $+5.5 \text{ V}$, $T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$, unless otherwise specified.)

Symbol	Parameter	Min	Max	Units
t_{CSS}	CS Setup Time	50		ns
t_{CSH}	CS Hold Time	0		ns
t_{DIS}	DI Setup Time	100		ns
t_{DIH}	DI Hold Time	100		ns
t_{PD1}	Output Delay to 1		0.25	μs
t_{PD0}	Output Delay to 0		0.25	μs
t_{HZ} (Note 7)	Output Delay to High-Z		100	ns
t_{EW}	Program/Erase Pulse Width		5	ms
t_{CSMIN}	Minimum CS Low Time	0.25		μs
t_{SKHI}	Minimum SK High Time	0.25		μs
t_{SKLOW}	Minimum SK Low Time	0.25		μs
t_{SV}	Output Delay to Status Valid		0.25	μs
SK_{MAX}	Maximum Clock Frequency	DC	2000	kHz

7. This parameter is tested initially and after a design or process change that affects the parameter.

Table 8. INSTRUCTION SET

Instruction	Start Bit	Opcode	Address		Data		Comments
			x8	x16	x8	x16	
READ	1	10	A10-A0	A9-A0			Read Address AN- A0
ERASE	1	11	A10-A0	A9-A0			Clear Address AN- A0
WRITE	1	01	A10-A0	A9-A0	D7-D0	D15-D0	Write Address AN- A0
EWEN	1	00	11XXXXXXXX	11XXXXXXXX			Write Enable
EWDS	1	00	00XXXXXXXX	00XXXXXXXX			Write Disable
ERALL	1	00	10XXXXXXXX	10XXXXXXXX			Clear All Addresses
WRALL	1	00	01XXXXXXXX	01XXXXXXXX	D7-D0	D15-D0	Write All Addresses

DEVICE OPERATION

The NV93C86 is a 16,384-bit nonvolatile memory intended for use with industry standard microprocessors. The NV93C86 can be organized as either registers of 16 bits or 8 bits. When organized as X16, seven 13-bit instructions control the reading, writing and erase operations of the device. When organized as X8, seven 14-bit instructions control the reading, writing and erase operations of the device. The NV93C86 operates on a single power supply and will generate on chip, the high voltage required during any write operation.

Instructions, addresses, and write data are clocked into the DI pin on the rising edge of the clock (SK). The DO pin is normally in a high impedance state except when reading data from the device, or when checking the ready/busy status after a write operation.

The ready/busy status can be determined after the start of a write operation by selecting the device (CS high) and polling the DO pin; DO low indicates that the write operation is not completed, while DO high indicates that the device is ready for the next instruction. If necessary, the DO pin may be placed back into a high impedance state during chip select by shifting a dummy "1" into the DI pin. The DO pin will enter the high impedance state on the falling edge of the clock (SK). Placing the DO pin into the high impedance state is recommended in applications where the DI pin and the DO pin are to be tied together to form a common DI/O pin.

The format for all instructions sent to the device is a logical "1" start bit, a 2-bit (or 4-bit) opcode, 10-bit address (an additional bit when organized X8) and for write operations a 16-bit data field (8-bit for X8 organizations).

Note: The Write, Erase, Write all and Erase all instructions require PE = 1. If PE is left floating, 93C86 is in Program Enabled mode. For Write Enable and Write Disable instruction PE = don't care.

Read

Upon receiving a READ command and an address (clocked into the DI pin), the DO pin of the NV93C86 will come out of the high impedance state and, after sending an initial dummy zero bit, will begin shifting out the data addressed (MSB first). The output data bits will toggle on the rising edge of the SK clock and are stable after the specified time delay (t_{PD0} or t_{PD1}).

After the initial data word has been shifted out and CS remains asserted with the SK clock continuing to toggle, the device will automatically increment to the next address and shift out the next data word in a sequential READ mode. As long as CS is continuously asserted and SK continues to toggle, the device will keep incrementing to the next address automatically until it reaches to the end of the address space, then loops back to address 0. In the sequential READ mode, only the initial data word is preceeded by a dummy zero bit. All subsequent data words will follow without a dummy zero bit.

Write

After receiving a WRITE command, address and the data, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN} . The falling edge of CS will start the self clocking clear and data store cycle of the memory location specified in the instruction. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the NV93C86 can be determined by selecting the device and polling the DO pin. Since this device features Auto-Clear before write, it is NOT necessary to erase a memory location before it is written into.

The timing diagram illustrates the relationship between four signals: SK (Serial Clock), DI (Data Input), CS (Chip Select), and DO (Data Output). The signals are shown as waveforms over time, with specific timing parameters labeled:

- SK (Serial Clock):** A square wave signal. Timing parameters include t_{SKHI} (high pulse width), t_{SKLOW} (low pulse width), and t_{CSH} (high-to-low transition time).
- DI (Data Input):** A signal that is valid during specific intervals. Timing parameters include t_{DIS} (input setup time before SK high) and t_{DIH} (input hold time after SK high).
- CS (Chip Select):** A signal that is active low. Timing parameters include t_{CSS} (setup time before SK high) and t_{CSMIN} (minimum pulse width).
- DO (Data Output):** A signal that is valid during specific intervals. Timing parameters include t_{DIS} (output delay time after SK high) and t_{PD0}, t_{PD1} (output delay times after SK high).

The diagram illustrates the timing of an SPI interface. The signals are:

- SK (Serial Clock):** A periodic clock signal.
- CS (Chip Select):** A signal that goes high before the first data transfer and returns low after the last.
- DI (Data Input):** Shows the address bits A_N to A_0 being shifted in. The first two bits are 1, followed by 0, and then the address bits. The rest of the shift register is filled with data bytes (represented by hexagons).
- DO (Data Output):** Shows the output data. The first byte is a "Dummy 0". Subsequent bytes are the data for addresses $\text{Address} + 1$, $\text{Address} + 2$, and $\text{Address} + n$.

5

Erase

Upon receiving an ERASE command and address, the CS (Chip Select) pin must be deasserted for a minimum of t_{CSMIN} . The falling edge of CS will start the self clocking clear cycle of the selected memory location. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the NV93C86 can be determined by selecting the device and polling the DO pin. Once cleared, the content of a cleared location returns to a logical “1” state.

Erase/Write Enable and Disable

The NV93C86 powers up in the write disable state. Any writing after power-up or after an EWDS (write disable) instruction must first be preceded by the EWEN (write enable) instruction. Once the write instruction is enabled, it will remain enabled until power to the device is removed, or the EWDS instruction is sent. The EWDS instruction can be used to disable all NV93C86 write and clear instructions, and will prevent any accidental writing or clearing of the device. Data can be read normally from the device regardless of the write enable/disable status.

Erase All

Upon receiving an ERAL command, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN} . The falling edge of CS will start the self clocking clear cycle of all memory locations in the device. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the NV93C86 can be determined by selecting the device and polling the DO pin. Once cleared, the contents of all memory bits return to a logical “1” state.

Write All

Upon receiving a WRAL command and data, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN} . The falling edge of CS will start the self clocking data write to all memory locations in the device. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the NV93C86 can be determined by selecting the device and polling the DO pin. It is not necessary for all memory locations to be cleared before the WRAL command is executed.

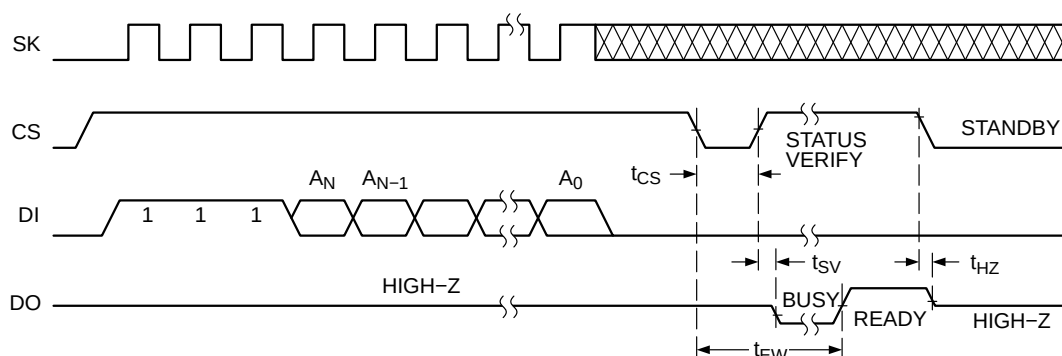


Figure 5. Erase Instruction Timing

ORDERING INFORMATION

Device Order Number	Specific Device Marking	Package Type	Temperature Range	Shipping [†]
NV93C86BMUW3VTBG	M3W	UDFN-8 (2x3 mm) Wettable Flank	V = Auto Grade 1 (-40°C to +125°C)	Tape & Reel, 3,000 Units / Reel

[†]For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

8. All packages are RoHS-compliant (Lead-free, Halogen-free).

9. The standard lead finish is NiPdAu.

10. For additional package and temperature options, please contact your nearest onsemi Sales office.

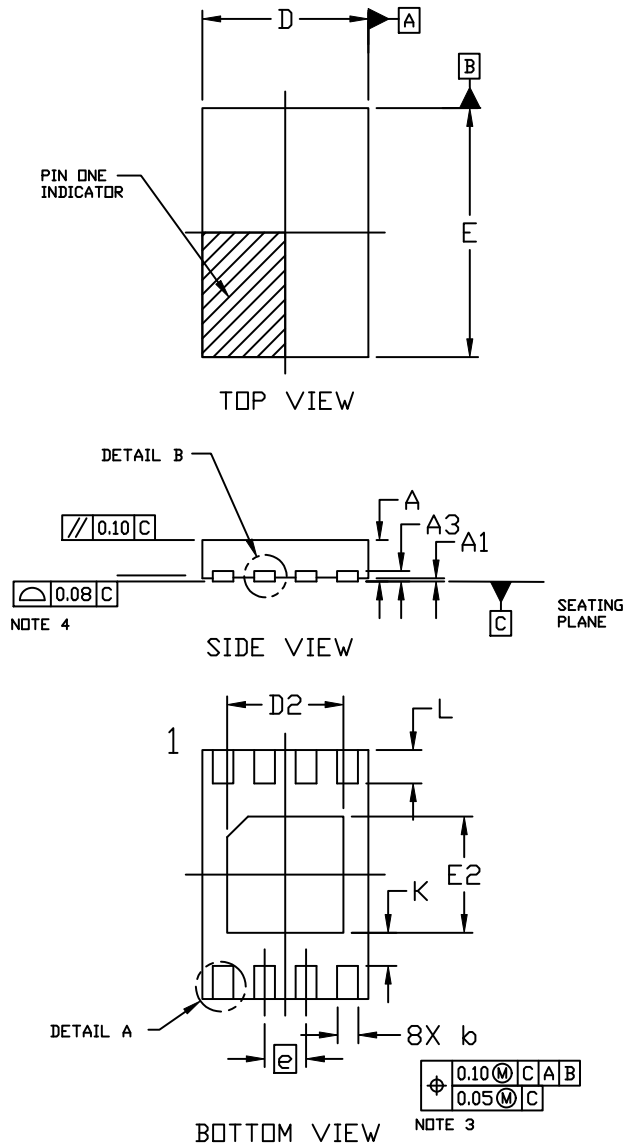
11. For detailed information and a breakdown of device nomenclature and numbering systems, please see the onsemi Device Nomenclature document, TND310/D, available at www.onsemi.com



SCALE 2:1

UDFN8 2x3, 0.5P
CASE 517DH
ISSUE A

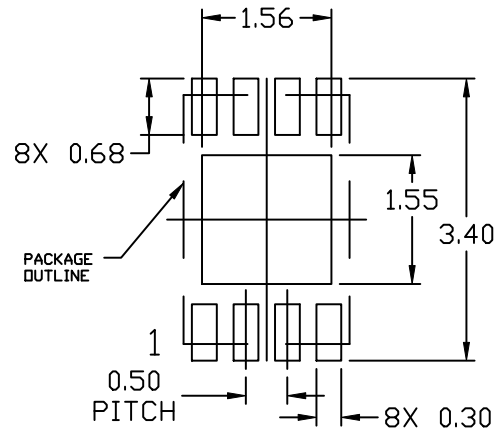
DATE 10 DEC 2020



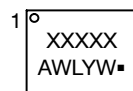
NOTES:

1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M,1994.
2. CONTROLLING DIMENSION: MILLIMETERS
3. DIMENSION b APPLIES TO PLATED TERMINAL AND IS MEASURED BETWEEN 0.15 AND 0.25MM FROM THE TERMINAL TIP.
4. COPLANARITY APPLIES TO THE EXPOSED PAD AS WELL AS THE TERMINALS.

DIM	MILLIMETERS		
	MIN.	NDM.	MAX.
A	0.45	0.50	0.55
A1	0.00	---	0.05
A3	0.13 REF		
b	0.20	0.25	0.30
D	1.90	2.00	2.10
D2	1.30	1.40	1.50
E	2.90	3.00	3.10
E2	1.30	1.40	1.50
e	0.50 BSC		
K	0.40 REF		
L	0.30	0.40	0.50


RECOMMENDED MOUNTING FOOTPRINT*

- * For additional information on our Pb-Free strategy and soldering details, please download the DN Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

GENERIC MARKING DIAGRAM*


XXXXX = Specific Device Code
A = Assembly Location
WL = Wafer Lot
Y = Year
W = Work Week
▪ = Pb-Free Package

*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot "▪", may or may not be present. Some products may not follow the Generic Marking.

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