

TPS6521855 Power Management IC (PMIC) for AM64x Arm®Cortex®-A53 Processors

1 Features

- Three Adjustable Step-Down Converters With Integrated Switching FETs (DCDC1, DCDC2, and DCDC3):
 - DCDC1: 1.1-V Default, up to 1.8 A
 - DCDC2: 1.0-V Default, up to 1.8 A
 - DCDC3: 1.8-V Default, up to 1.8 A
 - VIN Range From 2.7 V to 5.5 V
 - Adjustable Output Voltage Range 0.85 V to 1.675 V (DCDC1 and DCDC2)
 - Adjustable Output Voltage Range 0.9 V to 3.4 V (DCDC3)
 - Power Save Mode at Light Load Current
 - 100% Duty Cycle for Lowest Dropout
 - Active Output-Discharge When Disabled
- One Adjustable Buck-Boost Converter With Integrated Switching FETs (DCDC4):
 - DCDC4: 2.5-V Default, up to 1.6 A
 - VIN Range from 2.7 V to 5.5 V
 - Adjustable Output Voltage Range from 1.175 V to 3.4 V
 - Active Output-Discharge When Disabled
- Two Low-Quiescent Current, High Efficiency Step-Down Converters for Battery Backup Domain (DCDC5, DCDC6)
 - DCDC5: 1-V Output
 - DCDC6: 1.8-V Output
 - VIN Range from 2.2 V to 5.5 V
 - Supplied From System Power or Coin-Cell Backup Battery
- Adjustable General-Purpose LDO (LDO1)
 - LDO1: 3.3-V Default up to 400 mA
 - VIN Range from 1.8 V to 5.5 V
 - Adjustable Output Voltage Range from 0.9 V to 3.4 V
 - Active Output-Discharge When Disabled
- Low-Voltage Load Switch (LS1) With 350-mA Current Limit
 - VIN Range From 1.2 V to 3.6 V
 - 110-mΩ (Max) Switch Impedance at 1.35 V
- 5-V Load Switch (LS2) With 100-mA or 500-mA Selectable Current Limit
 - VIN Range From to 5.5 V
 - 500-mΩ (Max) Switch Impedance at 5 V
- High-Voltage Load Switch (LS3) With 100-mA or 500-mA Selectable Current Limit
 - VIN Range From 1.8 V to 10 V
 - 500-mΩ (Max) Switch Impedance
- Supervisor With Built-in Supervisor Function Monitors

- DCDC1, DCDC2 $\pm 4\%$ Tolerance
- DCDC3, DCDC4 $\pm 5\%$ Tolerance
- LDO1 $\pm 5\%$ Tolerance
- Protection, Diagnostics, and Control:
 - Undervoltage Lockout (UVLO)
 - Always-on Push-Button Monitor
 - Overtemperature Warning and Shutdown
 - Separate Power-Good Output for Backup and Main Supplies
 - I²C Interface (Address 0x24) (See [Timing Requirements](#) for I²C Operation at 400 kHz)

2 Applications

- [Grid Infrastructure](#)
- [Appliances](#)
- [Human-Machine Interface \(HMI\)](#)
- [Industrial Automation](#)
- [Electronic Point of Sale \(ePOS\)](#)
- [Test and Measurement](#)
- [Personal Navigation](#)
- [Industrial Communications](#)
- [Connected Industrial Drives](#)

3 Description

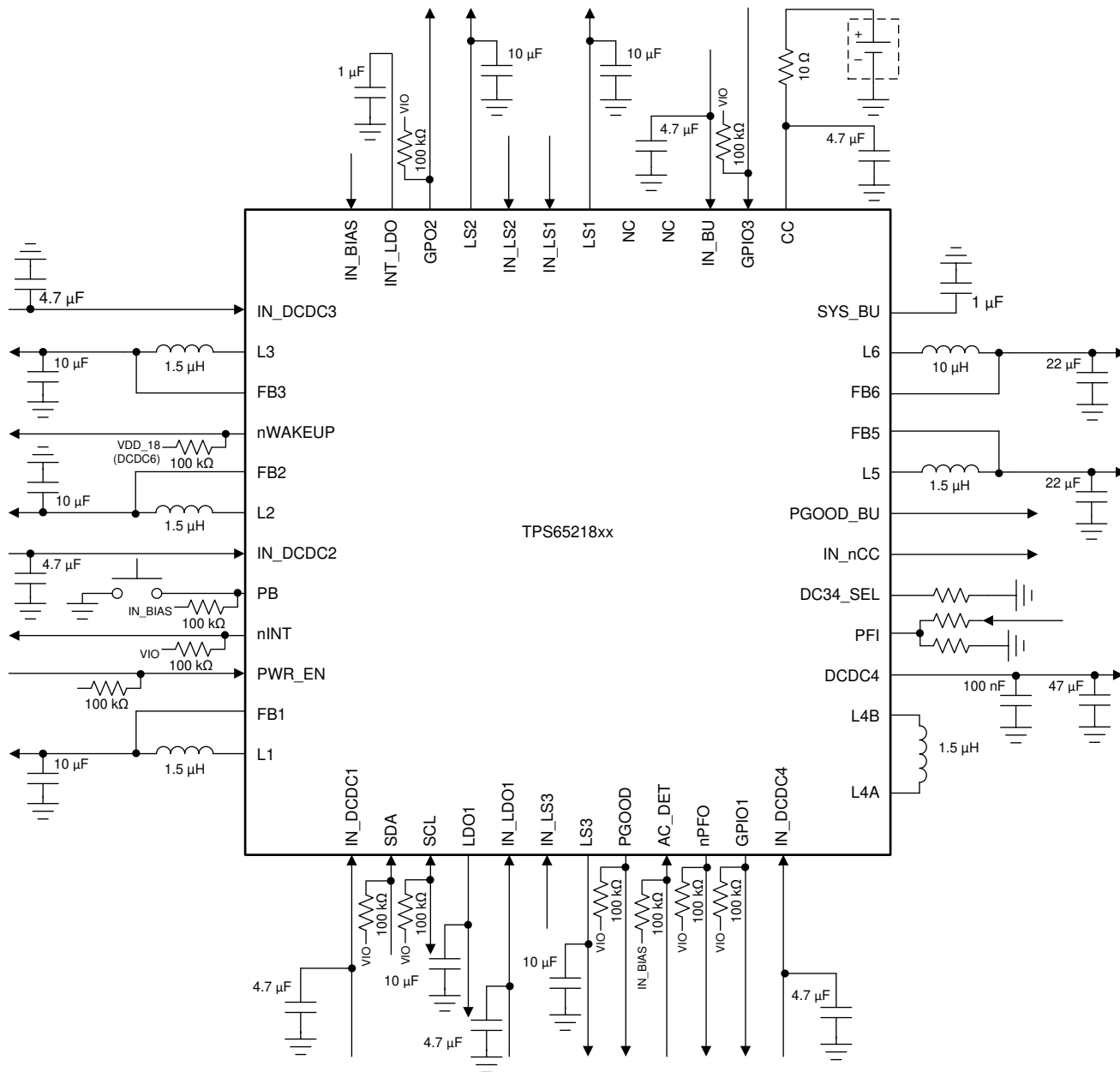
The TPS6521855 is a single chip, power-management IC (PMIC) specifically designed to support the AM64x line of processors in both portable (Li-Ion battery) and nonportable (5-V adapter) applications. The device is characterized across a –40°C to +105°C temperature range, making it suitable for various industrial applications.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPS6521855	VQFN (48)	6.00 mm × 6.00 mm
TPS6521855	HTQFP (48)	7.00 mm × 7.00 mm

- (1) For all available packages, see the orderable addendum at the end of the data sheet.





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Figure 3-1. Simplified Schematic

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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision * (May 2021) to Revision A (August 2021)	Page
• Added DCDC2 default voltage information.....	1
• Removed 1.2 from DCDC3 default voltage.....	1
• Changed DCDC4 default voltage from 1.8-V to 2.5-V.....	1
• Changed Reset for 5-0 in Table 7-23 from 0x0Fh to Fh for formatting standardization.....	44

5 Pin Configuration and Functions

Figure 5-1 shows the 48-pin RSL Plastic Quad Flatpack No-Lead.

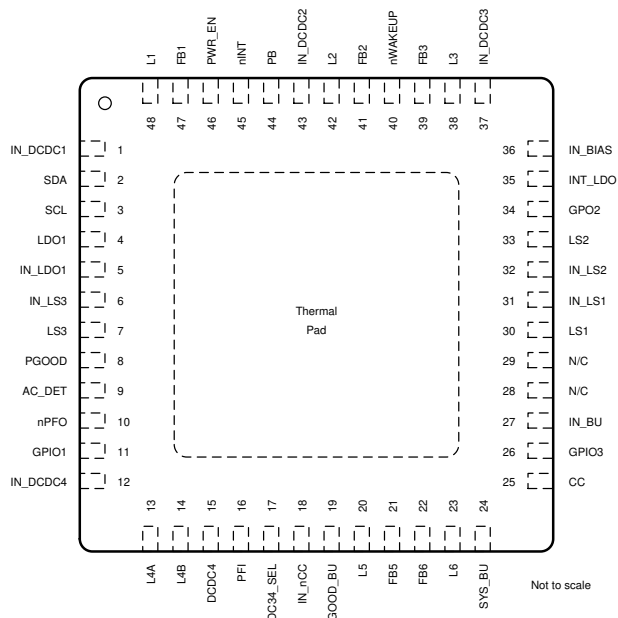


Figure 5-1. 48-Pin RSL VQFN With Exposed Thermal Pad (Top View, 6 mm × 6 mm × 1 mm With 0.4-mm Pitch)

Table 5-1. Pin Functions

PIN NO.	PIN NAME	TYPE	DESCRIPTION
1	IN_DCDC1	P	Input supply pin for DCDC1.
2	SDA	I/O	Data line for the I ² C interface. Connect to pullup resistor.
3	SCL	I	Clock input for the I ² C interface. Connect to pullup resistor.
4	LDO1	O	Output voltage pin for LDO1. Connect to capacitor.
5	IN_LDO1	P	Input supply pin for LDO1.
8	PGOOD	O	Power-good output (configured as open drain). Pulled low when either DCDC1-4 or LDO1 are out of regulation. Load switches and DCDC5-6 do not affect PGOOD pin.
9	AC_DET	I	AC monitor input and enable for DCDC1-4, LDO1 and load switch. See Section 7.4.1 for details. Tie pin to IN_BIAS if not used.
10	nPFO	O	Power-fail comparator output, deglitched (open drain). Pin is pulled low when PFI input is below power-fail threshold.
11	GPIO1	I/O	Pin configured as DDR reset-input (driving GPO2) or as general-purpose, open-drain output. See Section 7.3.1.11 for more information.
12	IN_DCDC4	P	Input supply pin for DCDC4.
13	L4A	P	Switch pin for DCDC4. Connect to inductor.
14	L4B	P	Switch pin for DCDC4. Connect to inductor.
15	DCDC4	P	Output voltage pin for DCDC4. Connect to capacitor.
16	PFI	I	Power-fail comparator input. Connect to resistor divider.
17	DC34_SEL	I	Power-up default selection pin for DCDC3 or DCDC4. Power-up default is programmed by a resistor connected to ground. See Section 7.3.1.10 for resistor options.
18	IN_nCC	O	Output pin indicates if DCDC5 and DCDC6 are powered from main supply (IN_BU) or coin-cell battery (CC). Pin is push-pull output. Pulled low when PMIC is powered from coin cell battery. Pulled high when PMIC is powered from main supply (IN_BU).

Table 5-1. Pin Functions (continued)

PIN		TYPE	DESCRIPTION
NO.	NAME		
19	PGOOD_BU	O	Power-good, push-pull output for DCDC5 and DCDC6. Pulled low when either DCDC5 or DCDC6 is out of regulation. Pulled high (to DCDC6 output voltage) when both rails are in regulation.
20	L5	P	Switch pin for DCDC5. Connect to inductor.
21	FB5	I	Feedback voltage pin for DCDC5. Connect to output capacitor.
22	FB6	I	Feedback voltage pin for DCDC6. Connect to output capacitor.
23	L6	P	Switch pin for DCDC6. Connect to inductor.
24	SYS_BU	P	System voltage pin for battery-backup supply power path. Connect to 1-μF capacitor. Connecting any external load to this pin is not recommended.
25	CC	P	Coin cell battery input. Serves as the supply to DCDC5 and DCDC6 if no voltage is applied to IN_BU. Tie this pin to ground if it is not in use.
26	GPIO3	I/O	Pin can be configured as warm reset (negative edge) for DCDC1 and DCDC2 or as a general-purpose, open-drain output. See Section 7.3.1.11 for more details.
27	IN_BU	P	Default input supply pin for battery backup supplies (DCDC5 and DCDC6).
28	N/C	—	No connect. Leave pin floating.
29	N/C		
30	LS1	O	Output voltage pin for load switch 1. Connect to capacitor.
31	IN_LS1	P	Input supply pin for load switch 1.
32	IN_LS2	P	Input supply pin for load switch 2.
33	LS2	O	Output voltage pin for load switch 2. Connect to capacitor.
34	GPO2	O	Pin configured as DDR reset signal (controlled by GPIO1) or as general-purpose output. Buffer can be configured as push-pull or open-drain.
35	INT_LDO	P	Internal bias voltage. Connect to a 1-μF capacitor. TI does not recommended connecting any external load to this pin.
36	IN_BIAS	P	Input supply pin for reference system.
37	IN_DCDC3	P	Input supply pin for DCDC3.
38	L3	P	Switch pin for DCDC3. Connect to inductor.
39	FB3	I	Feedback voltage pin for DCDC3. Connect to output capacitor.
40	nWAKEUP	O	Signal to SOC to indicate a power on event (active low, open-drain output).
41	FB2	I	Feedback voltage pin for DCDC2. Connect to output capacitor.
42	L2	P	Switch pin for DCDC2. Connect to inductor.
43	IN_DCDC2	P	Input supply pin for DCDC2.
44	PB	I	Push-button monitor input. Typically connected to a momentary switch to ground (active low). See Section 7.4.1 for details.
45	nINT	O	Interrupt output (active low, open drain). Pin is pulled low if an interrupt bit is set. The pin returns to Hi-Z state after the bit causing the interrupt has been read. Interrupts can be masked.
46	PWR_EN	I	Power enable input for DCDC1-4, LDO1 and load switches. See Section 7.4.1 for details.
47	FB1	I	Feedback voltage pin for DCDC1. Connect to output capacitor.
48	L1	P	Switch pin for DCDC1. Connect to inductor.
—	Thermal Pad	P	Power ground and thermal relief. Connect to ground plane.

6 Specifications

6.1 Absolute Maximum Ratings

Operating under free-air temperature range (unless otherwise noted).⁽¹⁾

		MIN	MAX	UNIT
Supply voltage	IN_BIAS, IN_LDO1, IN_LS2, IN_DCDC1, IN_DCDC2, IN_DCDC3, IN_DCDC4	–0.3	7	V
	IN_LS1, CC	–0.3	3.6	
	IN_LS3	–0.3	11.2	
	IN_BU	–0.3	5.8	
Input voltage	All pins unless specified separately	–0.3	7	V
Output voltage	All pins unless specified separately	–0.3	7	V
Source or sink current	GPO2		6	mA
	PGOOD_BU, IN_nCC		1	
Sink current	PGOOD, nWAKEUP, nINT, nPFO, SDA, GPIO1, GPIO3		6	mA
T _A	Operating ambient temperature	–40	105	°C
T _J	Junction temperature	–40	125	°C
T _{stg}	Storage temperature	–65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

		VALUE	UNIT
V _(ESD)	Electrostatic discharge		
	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±2000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
 (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted).

		MIN	NOM	MAX	UNIT
Supply voltage, IN_BIAS		2.7		5.5	V
Input voltage for DCDC1, DCDC2, DCDC3, and DCDC4		2.7		5.5	V
Supply voltage, IN_BU		2.2		5.5	V
Supply voltage, CC		2.2		3.3	V
Input voltage for LDO1		1.8		5.5	V
Input voltage for LS1		1.2		3.6	V
Input voltage for LS2		3		5.5	V
Input voltage for LS3		1.8		10	V
Output voltage for DCDC1		0.85		1.675	V
Output voltage for DCDC2		0.85		1.675	V
Output voltage for DCDC3		0.9		3.4	V
Output voltage for DCDC4		1.175		3.4	V
Output voltage for DCDC5			1		V
Output voltage for DCDC6			1.8		V
Output voltage for LDO1		0.9		3.4	V
Output current for DCDC1, DCDC2, and DCDC3		0		1.8	A
Output current for DCDC4	VIN_DCDC4 = 2.8 V			1	A
	VIN_DCDC4 = 3.6 V			1.3	
	VIN_DCDC4 = 5 V			1.6	
Output current for DCDC5 and DCDC6		0		25	mA
Output current for LDO1		0		400	mA
Output current for LS1		0		300	mA
Output current for LS2		0		920	mA
Output current for LS3	VIN_LS3 > 2.3 V	0		900	mA
	VIN_LS3 ≤ 2.3 V	0		475	

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS6521855		UNIT
		RSL (VQFN)	PHP (HTQFP)	
		48 PINS	48 PINS	
R _{θJC(top)}	Junction-to-case (top)	17.2	13.3	°C/W
R _{θJB}	Junction-to-board	5.8	7.9	°C/W
R _{θJA}	Thermal resistance, junction-to-ambient. JEDEC 4-layer, high-K board.	30.6	26.7	°C/W
Ψ _{JT}	Junction-to-package top	0.2	0.3	°C/W
Ψ _{JB}	Junction-to-board	5.6	7.8	°C/W
R _{θJC(bot)}	Junction-to-case (bottom)	1.5	0.7	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

6.5 Electrical Characteristics

Over operating free-air temperature range (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
INPUT VOLTAGE AND CURRENTS						
V _{IN_BIAS}	Input supply voltage range	Normal operation	2.7		5.5	V
		EEPROM programming	4.5		5.5	
	Deglitch time			5		ms
I _{OFF}	OFF state current, total current into IN_BIAS, IN_DCDCx, IN_LDO1, IN_LSx, IN_BU	V _{IN} = 3.6 V; All rails disabled. T _J = 0°C to 85°C		5		μA
I _{SUSPEND}	SUSPEND current, total current into IN_BIAS, IN_DCDCx, IN_LDO1, IN_LSx, IN_BU	V _{IN} = 3.6 V; DCDC3 enabled, low-power mode, no load. All other rails disabled. T _J = 0°C to 105°C		220		μA
SYS_BU						
V _{SYS_BU}	SYS_BU voltage range	Powered from V _{IN_BU} or V _{CC}	2.2		5.5	V
C _{SYS_BU}	Recommended SYS_BU capacitor	Ceramic, X5R or X7R, see Table 8-3 .		1		μF
	Tolerance	Ceramic, X5R or X7R, rated voltage ≥ 6.3 V	–20%		20%	
INT_LDO						
V _{INT_LDO}	Output voltage			2.5		V
	DC accuracy	I _{OUT} < 10 mA	–2%		2%	
I _{OUT}	Output current range	Maximum allowable external load	0		10	mA
I _{LIMIT}	Short circuit current limit	Output shorted to GND		23		mA
t _{HOLD}	Hold-up time	Measured from V _{INT_LDO} = to V _{INT_LDO} = 1.8 V All rails enabled before power off, IN_BIAS tied to IN_DCDC1-4, IN_LDO1 V _{IN_BIAS} = 2.8 V to 0 V in < No external load on INT_LDO C _{INT_LDO} = , see Table 8-3 .		150		ms
C _{OUT}	Nominal output capacitor value	Ceramic, X5R or X7R, see Table 8-3 .	0.1	1	22	μF
	Tolerance	Ceramic, X5R or X7R, rated voltage ≥ 6.3 V	–20%		20%	
DCDC1 (1.1-V BUCK)						
V _{IN_DCDC1}	Input voltage range	V _{IN_BIAS} > V _{UVLO}	2.7		5.5	V
V _{DCDC1}	Output voltage range	Adjustable through I ² C	0.85		1.675	V
	DC accuracy	2.7 V ≤ V _{IN} ≤ 5.5 V; 0 A ≤ I _{OUT} ≤ 1.8 A	–2%		2%	
I _{OUT}	Continuous output current	V _{IN_DCDC1} > 2.7 V			1.8	A
I _Q	Quiescent current	Total current from I _{N_DCDC1} pin; Device not switching, no load		25	50	μA
R _{DS(ON)}	High-side FET on resistance	V _{IN_DCDC1} = 3.6 V		230	355	mΩ
	Low-side FET on resistance	V _{IN_DCDC1} = 3.6 V		90	145	
I _{LIMIT}	High-side current limit	V _{IN_DCDC1} = 3.6 V		2.8		A
	Low-side current limit	V _{IN_DCDC1} = 3.6 V		3.1		

6.5 Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted).

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT	
V _{PG}	Power-good threshold	V _{OUT} falling	STRICT = 0b	88.5%	90%	91.5%		
			STRICT = 1b	96%	96.5%	97%		
	Hysteresis	V _{OUT} rising	STRICT = 0b	3.8%	4.1%	4.4%		
			STRICT = 1b	0.25%				
	Deglitch	V _{OUT} falling	STRICT = 0b	1			ms	
			STRICT = 1b	50			μs	
		V _{OUT} rising	STRICT = 0b	10			μs	
			STRICT = 1b	10			μs	
	Time-out				5			ms
V _{OV}	Overvoltage detection threshold	V _{OUT} rising, STRICT = 1b		103%	103.5%	104%		
	Hysteresis	V _{OUT} falling, STRICT = 1b		0.25%				
	Deglitch	V _{OUT} rising, STRICT = 1b		50			μs	
I _{INRUSH}	Inrush current	V _{IN_DCDC1} = 3.6 V; C _{OUT} = 10 μF to 100 μF			500			mA
R _{DIS}	Discharge resistor				150	250	350	Ω
L	Nominal inductor value	See Table 8-2 .			1	1.5	2.2	μH
	Tolerance				–30%			30%
C _{OUT}	Output capacitance value	Ceramic, X5R or X7R, see Table 8-3 .			10	22	100 ⁽⁸⁾	μF
DCDC2 (1.1-V BUCK)								
V _{IN_DCDC2}	Input voltage range	V _{IN_BIAS} > V _{UVLO}		2.7		5.5	V	
V _{DCDC2}	Output voltage range	Adjustable through I ² C		0.85		1.675	V	
	DC accuracy	2.7 V ≤ V _{IN} ≤ 5.5 V; 0 A ≤ I _{OUT} ≤ 1.8 A		–2%			2%	
I _{OUT}	Continuous output current	V _{IN_DCDC2} > 2.7 V					1.8	A
I _Q	Quiescent current	Total current from I _{N_DCDC2} pin; device not switching, no load		25			50	μA
R _{DS(ON)}	High-side FET on resistance	V _{IN_DCDC2} = 3.6 V		230			355	mΩ
	Low-side FET on resistance	V _{IN_DCDC2} = 3.6 V		90			145	
I _{LIMIT}	High-side current limit	V _{IN_DCDC2} = 3.6 V		2.8			A	
	Low-side current limit	V _{IN_DCDC2} = 3.6 V		3.1				
V _{PG}	Power-good threshold	V _{OUT} falling	STRICT = 0b	88.5%	90%	91.5%		
			STRICT = 1b	96%	96.5%	97%		
	Hysteresis	V _{OUT} rising	STRICT = 0b	3.8%	4.1%	4.4%		
			STRICT = 1b	0.25%				
	Deglitch	V _{OUT} falling	STRICT = 0b	1			ms	
			STRICT = 1b	50			μs	
		V _{OUT} rising	STRICT = 0b	10			μs	
			STRICT = 1b	10			μs	
	Time-out	Occurs at enable of DCDC2 and after DCDC2 register write (register 0x17).			5			ms
V _{OV}	Overvoltage detection threshold	V _{OUT} rising, STRICT = 1b		103%	103.5%	104%		
	Hysteresis	V _{OUT} falling, STRICT = 1b		0.25%				
	Deglitch	V _{OUT} rising, STRICT = 1b		50			μs	
I _{INRUSH}	Inrush current	V _{IN_DCDC2} = 3.6 V; C _{OUT} = 10 μF to 100 μF			500			mA
R _{DIS}	Discharge resistor				150	250	350	Ω
L	Nominal inductor value	See Table 8-2 .			1	1.5	2.2	μH
	Tolerance				–30%			30%

6.5 Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted).

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
C _{OUT}	Output capacitance value	Ceramic, X5R or X7R, see Table 8-3 .		10	22	100 ⁽⁸⁾	μF
DCDC3 (1.2-V BUCK)							
V _{IN_DCDC3}	Input voltage range	V _{IN_BIAS} > V _{UVLO}		2.7		5.5	V
V _{DCDC3}	Output voltage range	Adjustable through I ² C		0.9		3.4	V
	DC accuracy	2.7 V ≤ V _{IN} ≤ 5.5 V; 0 A ≤ I _{OUT} ≤ 1.8 A, V _{IN_DCDC3} ≥ (V _{DCDC3} + 700 mV)		–2%		2%	
I _{OUT}	Continuous output current	V _{IN_DCDC3} > 2.7 V				1.8	A
I _Q	Quiescent current	Total current from IN_DCDC3 pin; Device not switching, no load			25	50	μA
R _{DS(ON)}	High-side FET on resistance	V _{IN_DCDC3} = 3.6 V			230	345	mΩ
	Low-side FET on resistance	V _{IN_DCDC3} = 3.6 V			100	150	
I _{LIMIT}	High-side current limit	V _{IN_DCDC3} = 3.6 V			2.8		A
	Low-side current limit	V _{IN_DCDC3} = 3.6 V			3		
V _{PG}	Power-good threshold	V _{OUT} falling	STRICT = 0b	88.5%	90%	91.5%	
			STRICT = 1b	95%	95.5%	96%	
	Hysteresis	V _{OUT} rising	STRICT = 0b	3.8%	4.1%	4.4%	
			STRICT = 1b		0.25%		
	Deglitch	V _{OUT} falling	STRICT = 0b		1		ms
			STRICT = 1b		50		μs
		V _{OUT} rising	STRICT = 0b		10		μs
			STRICT = 1b		10		μs
	Time-out	Occurs at enable of DCDC3 and after DCDC3 register write (register 0x18).			5		ms
V _{OV}	Overvoltage detection threshold	V _{OUT} rising, STRICT = 1b		104%	104.5%	105%	
	Hysteresis	V _{OUT} falling, STRICT = 1b			0.25%		
	Deglitch	V _{OUT} rising, STRICT = 1b			50		μs
I _{INRUSH}	Inrush current	V _{IN_DCDC3} = 3.6 V; C _{OUT} = 10 μF to 100 μF				500	mA
R _{DIS}	Discharge resistor			150	250	350	Ω
L	Nominal inductor value	See Table 8-2 .		1.0	1.5	2.2	μH
	Tolerance			–30%		30%	
C _{OUT}	Output capacitance value	Ceramic, X5R or X7R, see Table 8-3 .		10	22	100	μF
DCDC4 (3.3-V BUCK-BOOST) / ANALOG AND I/O							
V _{IN_DCDC4}	Input voltage operating range	V _{IN_BIAS} > V _{UVLO} , –40°C to +105°C		2.8		5.5	V
V _{DCDC4}	Output voltage range	Adjustable through I ² C		1.175		3.4	V

6.5 Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted).

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
V _{DCDC4}	DC accuracy	4.2 V ≤ V _{IN} ≤ 5.5 V; 3 V < V _{OUT} ≤ 3.4 V 0 A ≤ I _{OUT} ≤ 1.6 A		−2%		2%	
		3.3 V ≤ V _{IN} ≤ 4.2 V; 3 V < V _{OUT} ≤ 3.4 V 0 A ≤ I _{OUT} ≤ 1.3 A		−2%		2%	
		2.8 V ≤ V _{IN} ≤ 3.3 V; 3 V < V _{OUT} ≤ 3.4 V 0 A ≤ I _{OUT} ≤ 1 A		−2%		2%	
		2.8 V ≤ V _{IN} ≤ 5.5 V; 1.65 V < V _{OUT} ≤ 3 V 0 A ≤ I _{OUT} ≤ 1 A		−2%		2%	
		2.8 V ≤ V _{IN} ≤ 5.5 V; 1.175 V < V _{OUT} ≤ 1.65 V 0 A ≤ I _{OUT} ≤ 1 A		−2.5%		2.5%	
Output voltage ripple		PFM mode enabled; 4.2 V ≤ V _{IN} ≤ 5.5 V; 0 A ≤ I _{OUT} ≤ 1.6 A V _{OUT} = 3.3 V				150	mV _{pp}
Minimum duty cycle in step-down mode						18%	
I _{OUT}	Continuous output current	V _{IN_DCDC4} = 2.8 V, V _{OUT} = 3.3 V				1	A
		V _{IN_DCDC4} = 3.6 V, V _{OUT} = 3.3 V				1.3	
		V _{IN_DCDC4} = 5 V, V _{OUT} = 3.3 V				1.6	
I _Q	Quiescent current	Total current from IN_DCDC4 pin; Device not switching, no load.			25	50	μA
f _{SW}	Switching frequency				2400		kHz
R _{DS(ON)}	High-side FET on resistance	V _{IN_DCDC3} = 3.6 V	IN_DCDC4 to L4A		166		mΩ
			L4B to DCDC4		149		
	Low-side FET on resistance	V _{IN_DCDC3} = 3.6 V	L4A to GND		142	190	
			L4B to GND		144	190	
I _{LIMIT}	Average switch current limit	V _{IN_DCDC4} = 3.6 V			3000		mA
V _{PG}	Power-good threshold	V _{OUT} falling	STRICT = 0b	88.5%	90%	91.5%	
			STRICT = 1b	95%	95.5%	96%	
	Hysteresis	V _{OUT} rising	STRICT = 0b	3.8%	4.1%	4.4%	
			STRICT = 1b		0.25%		
	Deglitch	V _{OUT} falling	STRICT = 0b		1		ms
			STRICT = 1b		50		μs
		V _{OUT} rising	STRICT = 0b		10		μs
			STRICT = 1b		10		μs
	Time-out	Occurs at enable of DCDC4 and after DCDC4 register write (register 0x19)			5		ms
V _{OV}	Overvoltage detection threshold	V _{OUT} rising, STRICT = 1b		104%	104.5%	105%	
	Hysteresis	V _{OUT} falling, STRICT = 1b			0.25%		
	Deglitch	V _{OUT} rising, STRICT = 1b			50		μs
I _{INRUSH}	Inrush current	V _{IN_DCDC4} = 3.3 V ≤ V _{INDCDC4} ≤ 5.5 V; 40 μF ≤ C _{OUT} ≤ 100 μF				500	mA
R _{DIS}	Discharge resistor			150	250	350	Ω
L	Nominal inductor value	See Table 8-2 .		1.2	1.5	2.2	μH
	Tolerance			−30%		30%	

6.5 Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
C _{OUT}	Output capacitance value	Ceramic, X5R or X7R, see Table 8-3 .	40	80	100	μF
V _{CC}	DCDC5 and DCDC6 input voltage range.	V _{IN_BU} = 0 V	2.2		3.3	V
V _{IN_BU}	DCDC5 and DCDC6 input voltage range ⁽¹⁾		2.2		5.5	V
t _{RISE}	V _{CC} , V _{IN_BU} rise time	V _{CC} = 0 V to 3.3 V, V _{IN_BU} = 0 V to 5.5 V	30			μs
R _{DS(ON)}	Power path switch impedance	CC to SYS_BU V _{CC} = 2.4 V, V _{IN_BU} = 0 V		14.5		Ω
	Power path switch impedance	IN_BU to SYS_BU V _{IN_BU} = 3.6 V		10.5		
Reverse leakage current	Out of CC pin; V _{CC} = 1.5 V; V _{IN_BU} = 5.5 V; over full temperature range			500		
R _{CC}	Acceptable CC source impedance	I _{OUT, DCDC5} < 10 μA; I _{OUT, DCDC6} < 10 μA			1000	Ω
I _Q	Quiescent current	Average current into CC pin; RECOVERY or OFF state; V _{IN_BU} = 0 V; V _{CC} = 2.4 V; DCDC5 and DCDC6 enabled, no load T _J = 25°C		350		nA
Q _{INRUSH}	Inrush charge	V _{IN_BIAS} = decaying; CC = 3 V; C _{SYS_BU} = 1 μF; SYS_BU = 2.3 V to 3 V; CC _{series_resist} = 10 Ω C _{CC} = 4.7 μF		720		nC
DCDC5 (1-V BATTERY BACKUP SUPPLY)						
V _{DCDC5}	Output voltage			1		V
	DC accuracy	2.7 V ≤ V _{IN_BU} ≤ 5.5 V;	–2.5%		2.5%	
		2.7 V ≤ V _{IN_BU} ≤ 5.5 V 1.5 μA ≤ I _{OUT} ≤ 25 mA 0°C ≤ T _A < 105°C	–2%		2%	
		2.2 V ≤ V _{CC} ≤ 3.3 V; V _{IN_BU} = 0; 1.5 μA ≤ I _{OUT} ≤ 100 μA	–2.5%		2.5%	
	Output voltage ripple	L = 10 μH; C _{OUT} = 22 μF; 100-μA load, occurs during band-gap sampling			32 ⁽⁹⁾	mV _{pp}
I _{OUT}	Continuous output current	2.2 V ≤ V _{CC} ≤ 3.3 V V _{IN_BU} = 0 V		10	100	μA
		2.7 V ≤ V _{IN_BU} ≤ 5.5 V			25	mA
R _{DS(ON)}	High-side FET on resistance	V _{IN_BU} = 2.8 V		2.5	3.5	Ω
	Low-side FET on resistance	V _{IN_BU} = 2.8 V		2	3	
I _{LIMIT}	High-side current limit	V _{IN_BU} = 2.8 V		50		mA
V _{PG}	Power-good threshold	V _{OUT} falling	79%	85%	91%	
	Hysteresis	V _{OUT} rising		6%		
L	Nominal inductor value	Chip inductor, see Table 8-3 .	4.7	10	22	μH
	Tolerance		–30%		30%	
C _{OUT}	Output capacitance value	Ceramic, X5R or X7R, see Table 8-3 .	20 ⁽¹⁰⁾		47	μF
	Tolerance		–20%		20%	
DCDC6 (1.8-V BATTERY BACKUP SUPPLY)						
V _{DCDC6}	Output voltage			1.8		V
V _{DCDC6}	DC accuracy	2.7 V ≤ V _{IN_BU} ≤ 5.5 V; 1 μA ≤ I _{OUT} ≤ 25 mA	–2%		2%	
		2.2 V ≤ V _{CC} ≤ 3.3 V, V _{IN_BU} = 0; 1 μA ≤ I _{OUT} ≤ 100 μA	–2%		2%	
V _{DCDC6}	Output voltage ripple	L = 10 μH; C _{OUT} = 22 μF; 100-μA load			30 ⁽⁹⁾	mV _{pp}

6.5 Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
I _{OUT}	Continuous output current	2.2 V ≤ V _{CC} ≤ 3.3 V V _{IN_BU} = 0 V		10	100	μA
		2.7 V ≤ V _{IN_BU} ≤ 5.5 V			25	mA
R _{DS(ON)}	High-side FET on resistance	V _{IN_BU} = 3 V		2.5	3.5	Ω
	Low-side FET on resistance	V _{IN_BU} = 3 V		2	3	
I _{LIMIT}	High-side current limit	V _{IN_BU} = 3 V		50		mA
V _{PG}	Power-good threshold	V _{OUT} falling	87%	91%	95%	
	Hysteresis	V _{OUT} rising		3%		
L	Nominal inductor value	Chip inductor, see Table 8-3	4.7	10	22	μH
	Tolerance		–30%		30%	
C _{OUT}	Output capacitance value	Ceramic, X5R or X7R, see Table 8-3	20 ⁽¹⁰⁾		47	μF
	Tolerance		–20%		20%	

6.5 Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted).

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT	
LDO1 (1.8-V LDO)								
V _{IN_LDO1}	Input voltage range	V _{IN_BIAS} > V _{UVLO}		1.8		5.5	V	
I _Q	Quiescent current	No load			35		μA	
V _{OUT}	Output voltage range	Adjustable through I ² C		0.9		3.4	V	
	DC accuracy	V _{OUT} + 0.2 V ≤ V _{IN} ≤ 5.5 V; 0 A ≤ I _{OUT} ≤ 200 mA		−2%		2%		
I _{OUT}	Output current range	V _{IN_LDO1} − V _{DO} = V _{OUT}		0		200	mA	
		V _{IN_LDO1} > 2.7 V, V _{OUT} = 1.8 V		0		400		
I _{LIMIT}	Short circuit current limit	Output shorted to GND		445	550		mA	
V _{DO}	Dropout voltage	I _{OUT} = 100 mA, V _{IN} = 3.6 V				200	mV	
V _{PG}	Power-good threshold	V _{OUT} falling	STRICT = 0b	86%	90%	94%		
			STRICT = 1b	95%	95.5%	96%		
		Hysteresis, V _{OUT} rising	STRICT = 0b	3%	4%	5%		
			STRICT = 1b	0.25%				
	Deglitch	V _{OUT} falling	STRICT = 0b	1			ms	
			STRICT = 1b	50			μs	
		V _{OUT} rising	STRICT = 0b	10			μs	
			STRICT = 1b	10			μs	
	Time-out	Occurs at enable of LDO and after LDO register write (register 0x1B)			5			ms
V _{OV}	Overvoltage detection threshold	V _{OUT} rising, STRICT = 1b		104%	104.5%	105%		
	Hysteresis	V _{OUT} falling, STRICT = 1b		0.25%				
	Deglitch	V _{OUT} rising, STRICT = 1b		50			μs	
		V _{OUT} falling, STRICT = 1b		1			ms	
R _{DIS}	Discharge resistor			150	250	380	Ω	
C _{OUT}	Output capacitance value	Ceramic, X5R or X7R					100 μF	
LOAD SWITCH 1 (LS1)								
V _{IN_LS1}	Input voltage range	V _{IN_BIAS} > V _{UVLO}		1.2		3.6	V	
R _{DS(ON)}	Static on resistance	V _{IN_LS1} = 3.3 V, I _{OUT} = 300 mA, over full temperature range					110	mΩ
		V _{IN_LS1} = 1.8 V, I _{OUT} = 300 mA, DDR2, LPDDR, MDDR at 266 MHz over full temperature range					110	
		V _{IN_LS1} = 1.5 V, I _{OUT} = 300 mA, DDR3 at 333 MHz over full temperature range					110	
		V _{IN_LS1} = 1.35 V, I _{OUT} = 300 mA, DDR3L at 333 MHz over full temperature range					110	
		V _{IN_LS1} = 1.2 V, I _{OUT} = 200 mA, LPDDR2 at 333 MHz over full temperature range					150	
I _{LIMIT}	Short circuit current limit	Output shorted to GND		350			mA	
t _{BLANK}	Interrupt blanking time	Output shorted to GND until interrupt is triggered.			15		ms	
R _{DIS}	Internal discharge resistor at output ⁽²⁾	LS1DCHRG = 1		150	250	380	Ω	
T _{OTS}	Overtemperature shutdown ⁽³⁾			125	132	139	°C	
	Hysteresis			10				
C _{OUT}	Nominal output capacitance value	Ceramic, X5R or X7R, see Table 8-3 .		10		100	μF	

6.5 Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
LOAD SWITCH 2 (LS2)						
V _{IN_LS2}	Input voltage range	V _{IN_BIAS} > V _{UVLO}			5.5	V
V _{UVLO}	Undervoltage lockout	Measured at IN_LS2. Supply falling ⁽⁴⁾	2.48	2.6	2.7	V
	Hysteresis	Input voltage rising		170		mV
R _{DS(ON)}	Static on resistance	V _{IN_LS2} = 5 V, I _{OUT} = 500 mA, over full temperature range			500	mΩ
I _{LIMIT}	Short circuit current limit	Output shorted to GND; V _{IN_LS2} ≥ 4 V	LS2ILIM[1:0] = 00b	94	126	mA
			LS2ILIM[1:0] = 01b	188	251	
			LS2ILIM[1:0] = 10b	465	631	
			LS2ILIM[1:0] = 11b	922	1290	
I _{LEAK}	Reverse leakage current	V _{LS2} > V _{IN_LS2} + 1 V		12	30	μA
t _{BLANK}	Interrupt blanking time	Output shorted to GND until interrupt is triggered		15		ms
R _{DIS}	Internal discharge resistor at output ⁽²⁾	LS2DCHRG = 1b	150	250	380	Ω
T _{OTS}	Overtemperature shutdown ⁽⁴⁾		125	132	139	°C
	Hysteresis			10		
C _{OUT}	Nominal output capacitance value	Ceramic, X5R or X7R, see Table 8-3.	1		100	μF
LOAD SWITCH 3 (LS3)						
V _{IN_LS3}	Input voltage range	V _{IN_BIAS} > V _{UVLO}	1.8		10	V
R _{DS(ON)}	Static on resistance	V _{IN_LS3} = 9 V, I _{OUT} = 500 mA, over full temperature range			440	mΩ
		V _{IN_LS3} = 5 V, I _{OUT} = 500 mA, over full temperature range			526	
		V _{IN_LS3} = 2.8 V, I _{OUT} = 200 mA, over full temperature range			656	
		V _{IN_LS3} = 1.8 V, I _{OUT} = 200 mA, over full temperature range			910	
I _{LIMIT}	Short circuit current limit	V _{IN_LS3} > 2.3 V, Output shorted to GND	LS3ILIM[1:0] = 00b	98	126	mA
			LS3ILIM[1:0] = 01b	194	253	
			LS3ILIM[1:0] = 10b	475	738	
			LS3ILIM[1:0] = 11b	900	1234	
		V _{IN_LS3} ≤ 2.3 V, Output shorted to GND	LS3ILIM[1:0] = 00b	98	126	
			LS3ILIM[1:0] = 01b	194	253	
			LS3ILIM[1:0] = 10b	475	738	
t _{BLANK}	Interrupt blanking time	Output shorted to GND until interrupt is triggered.		15		ms
R _{DIS}	Internal discharge resistor at output ⁽²⁾	LS3DCHRG = 1	650	1000	1500	Ω
T _{OTS}	Overtemperature shutdown ⁽⁴⁾		125	132	139	°C
	Hysteresis			10		°C
C _{OUT}	Nominal output capacitance value	Ceramic, X5R or X7R, see Table 8-3.	1	100	220	μF
BACKUP BATTERY MONITOR						
V _{TH}	Comparator threshold	Ideal level		3		V
		Good level		2.6		V
		Low level		2.3		V
	Accuracy		–3%		3%	

6.5 Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
R _{LOAD}	Load impedance	Applied from CC to GND during comparison.	70	100	130	kΩ
t _{DLY}	Measurement delay	R _{LOAD} is connected during delay time. Measurement is taken at the end of delay.		600		ms
I/O LEVELS AND TIMING CHARACTERISTICS						
PG _{DLY}	PGOOD delay time	PGDLY[1:0] = 00b		10		ms
		PGDLY[1:0] = 01b		20		
		PGDLY[1:0] = 10b		50		
		PGDLY[1:0] = 11b		150		
t _{DG}	PB input	Rising edge		100		ms
		Falling edge		50		ms
	AC_DET input	Rising edge		100		μs
		Falling edge		10		ms
	PWR_EN input	Rising edge		10		ms
		Falling edge		100		μs
	GPIO1	Rising edge		1		ms
		Falling edge		1		ms
	GPIO3	Rising edge		5		μs
		Falling edge		5		μs
t _{RESET}	Reset time	PB input held low	TRST = 0b	8		s
			TRST = 1b	15		
V _{IH}	High level input voltage	SCL, SDA, GPIO1, and GPIO3		1.3		V
		AC_DET, PB		0.66 × IN_BIAS		
		PWR_EN		1.3		
V _{IL}	Low level input voltage	SCL, SDA, PWR_EN, AC_DET, PB, GPIO1, and GPIO3	0		0.4	V
V _{OH}	High level output voltage	GPO2; I _{SOURCE} = 5 mA; GPO2_BUF = 1	V _{IN_LS1} – 0.3		V _{IN_LS1}	V
		PGOOD_BU; I _{SOURCE} = 100 μA	V _{DCDC6} – 10 mV			
V _{OL}	Low level output voltage	nWAKEUP, nINT, SDA, PGOOD, GPIO1, GPO2, and GPIO3; I _{SINK} = 2 mA	0		0.3	V
		nPFO; I _{SINK} = 2 mA	0		0.35	
		PGOOD_BU; I _{SINK} = 100 μA	0		0.3	
V _{PFI}	Power-fail comparator threshold	Input falling		800		mV
	Hysteresis	Input rising		40		mV
	Accuracy		–4%		4%	
	Deglitch	Input falling		25		μs
		Input rising		10		ms
I _{DC34_SEL}	DC34_SEL bias current	Enabled only at power-up.	9.05	10	11.93	μA

6.5 Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{DC34_SEL}	DCDC3 and DCDC4 power-up default selection thresholds	Threshold 1		100		mV
		Threshold 2		163		
		Threshold 3		275		
		Threshold 4		400		
		Threshold 5		575		
		Threshold 6		825		
		Threshold 7		1200		
R _{DC34_SEL}	DCDC3 and DCDC4 power-up default selection resistor values	Setting 0	0	0	7.7	kΩ
		Setting 1	11.8	12.1	12.4	
		Setting 2	19.5	20	20.5	
		Setting 3	30.9	31.6	32.3	
		Setting 4	44.4	45.3	46.3	
		Setting 5	64.8	66.1	67.3	
		Setting 6	93.6	95.3	97.2	
		Setting 7	146	150		
I _{BIAS}	Input bias current	SCL, SDA, GPIO1 ⁽⁵⁾ , GPIO3 ⁽⁵⁾ ; V _{IN} = 3.3 V		0.01	1	μA
		PB, AC_DET, PFI; V _{IN} = 3.3 V			500	nA
I _{LEAK}	Pin leakage current	nINT, nWAKEUP, nPFO, PGOOD, PWR_EN, GPIO1 ⁽⁶⁾ , GPO2 ⁽⁷⁾ , GPIO3 ⁽⁶⁾ V _{OUT} = 3.3 V			500	nA
OSCILLATOR						
f _{OSC}	Oscillator frequency			2400		kHz
	Frequency accuracy	T _J = -40°C to +105°C	-12%		12%	
OVERTEMPERATURE SHUTDOWN						
T _{OTS}	Overtemperature shutdown	Increasing junction temperature	135	145	155	°C
	Hysteresis	Decreasing junction temperature		20		
T _{WARN}	High-temperature warning	Increasing junction temperature	90	100	110	°C
	Hysteresis	Decreasing junction temperature		15		

- (1) IN_BU has priority over CC input.
- (2) Discharge function disabled by default.
- (3) Switch is temporarily turned OFF if temperature exceeds OTS threshold.
- (4) Switch is temporarily turned OFF if input voltage drops below UVLO threshold.
- (5) Configured as input.
- (6) Configured as output.
- (7) Configured as open-drain output.
- (8) 500-μF of remote capacitance can be supported for DCDC1 and DCDC2.
- (9) For PHP package: 160 mVpp at -40°C, and 120 mVpp from 25°C to 105°C.
- (10) For PHP package: 40 μF.

6.6 Timing Requirements

			MIN	NOM	MAX	UNIT
f _{SCL}	Serial clock frequency			100		kHz
				400		
t _{HD;STA}	Hold time (repeated) START condition. After this period, the first clock pulse is generated.	SCL = 100 kHz	4			μs
		SCL = 400 kHz	600			ns
t _{LOW}	LOW period of the SCL clock	SCL = 100 kHz	4.7			μs
		SCL = 400 kHz	1.3			
t _{HIGH}	HIGH period of the SCL clock	SCL = 100 kHz	4			μs
		SCL = 400 kHz ⁽¹⁾	1			
t _{SU;STA}	Set-up time for a repeated START condition	SCL = 100 kHz	4.7			μs
		SCL = 400 kHz	600			ns
t _{HD;DAT}	Data hold time	SCL = 100 kHz	0		3.45	μs
		SCL = 400 kHz	0		900	ns
t _{SU;DAT}	Data set-up time	SCL = 100 kHz	250			ns
		SCL = 400 kHz	100			
t _r	Rise time of both SDA and SCL signals	SCL = 100 kHz			1000	ns
		SCL = 400 kHz			300	
t _f	Fall time of both SDA and SCL signals	SCL = 100 kHz			300	ns
		SCL = 400 kHz			300	
t _{SU;STO}	Set-up time for STOP condition	SCL = 100 kHz	4			μs
		SCL = 400 kHz	600			ns
t _{BUF}	Bus free time between STOP and START condition	SCL = 100 kHz	4.7			μs
		SCL = 400 kHz	1.3			
t _{SP}	Pulse width of spikes which must be suppressed by the input filter	SCL = 100 kHz	— ⁽²⁾		— ⁽²⁾	ns
		SCL = 400 kHz	0		50	
C _b	Capacitive load for each bus line	SCL = 100 kHz			400	pF
		SCL = 400 kHz			400	

(1) The SCL duty cycle at 400 kHz must be > 40%.

(2) The inputs of I²C devices in Standard-mode do not require spike suppression.

6.7 Typical Characteristics

At $T_J = 25^\circ\text{C}$ unless otherwise noted.

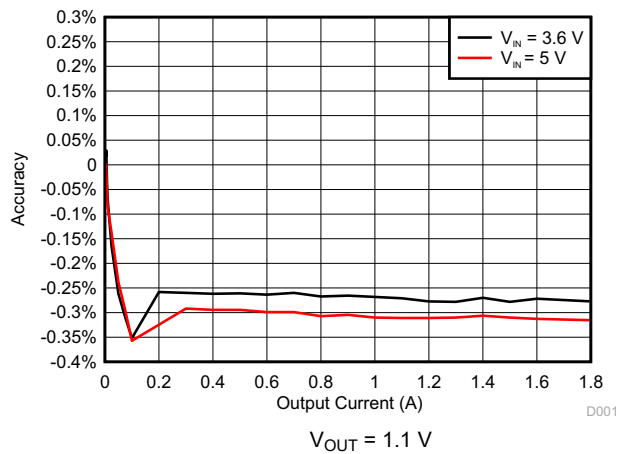


Figure 6-1. DCDC1 Accuracy

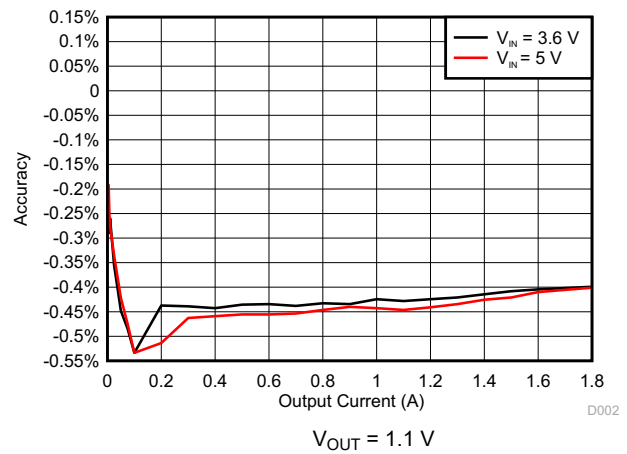


Figure 6-2. DCDC2 Accuracy

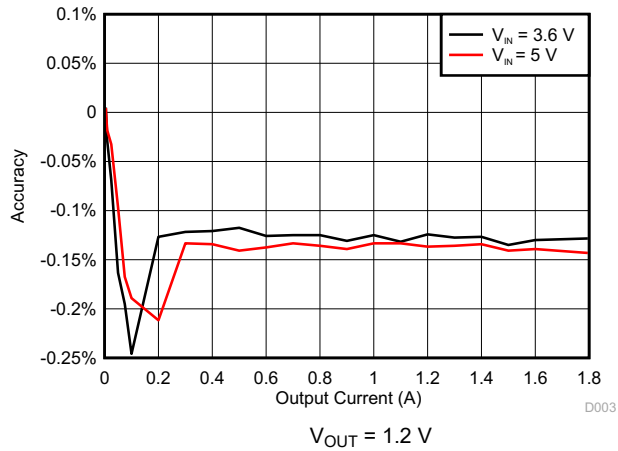


Figure 6-3. DCDC3 Accuracy

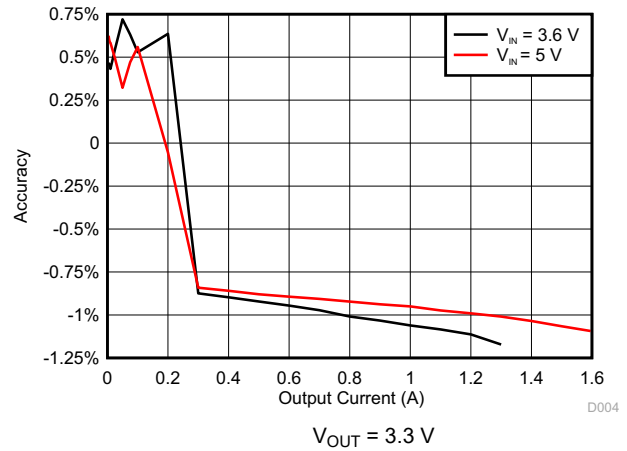


Figure 6-4. DCDC4 Accuracy

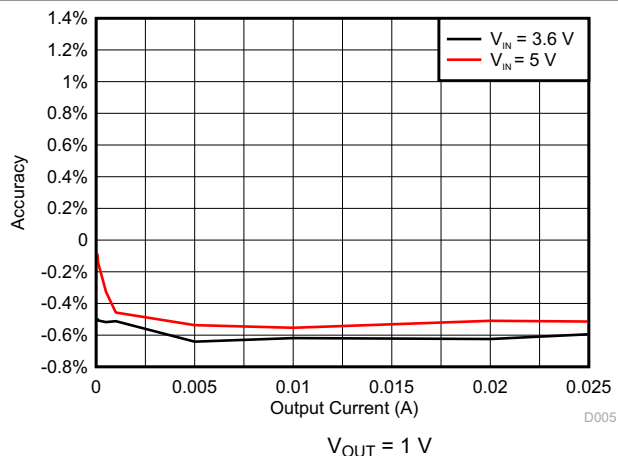


Figure 6-5. DCDC5 Accuracy

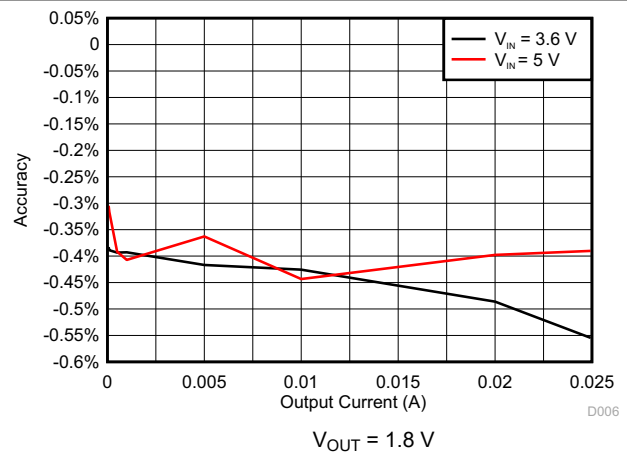


Figure 6-6. DCDC6 Accuracy

7 Detailed Description

7.1 Overview

The TPS6521855 provides three step-down converters, three load switches, three general-purpose I/Os, two battery backup supplies, one buck-boost converter, and one LDO. The system can be supplied by a regulated 5-V supply. The device is characterized across a -40°C to $+105^{\circ}\text{C}$ temperature range, which makes it suitable for various industrial applications.

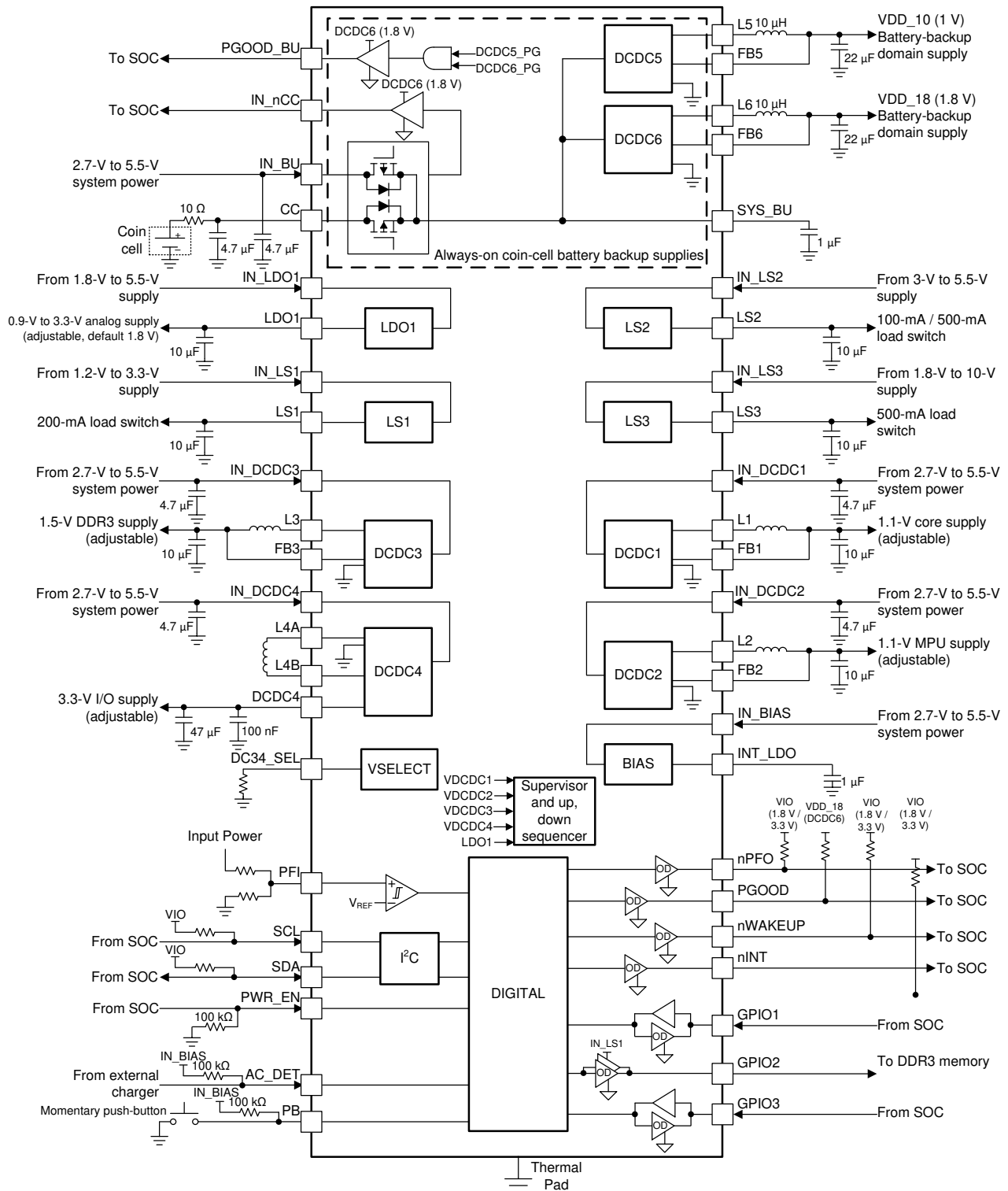
The I²C interface provides comprehensive features for using TPS6521855. All rails, load switches, and GPIOs can be enabled and disabled. Voltage thresholds for the UVLO and supervisor can be customized. Power-up and power-down sequences can also be programmed through I²C. Interrupts for overtemperature, overcurrent, and undervoltage can be monitored for the load-switches (LSx).

The integrated voltage supervisor monitors DCDC 1-4 and LDO1. It has two settings; the standard settings only monitor for undervoltage, while the strict settings implement tight tolerances on both undervoltage and overvoltage. A power-good signal is provided to report the regulation state of the five rails.

The three hysteretic step-down converters can each supply up to 1.8 A of current. The default output voltages for each converter can be adjusted through the I²C interface. DCDC1 and DCDC2 features dynamic voltage scaling with an adjustable slew rate. The step-down converters operate in a low power mode at light load, and can be forced into power mode (PWM) operation for noise sensitive applications.

The battery backup supplies consist of two low power step-down converters optimized for very light loads and are monitored with a separate power-good signal (PGOOD_BU). The converters can be configured to operate as always-on supplies with the addition of a coin cell battery. The state of the battery can be monitored over I²C.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Wake-Up and Power-Up and Power-Down Sequencing

The TPS6521855 has a predefined power-up and power-down sequence, which does not change in a typical application. The user can define custom sequences with I²C. The power-up sequence is defined by a series of ten strobes and nine delay times. Each output rail is assigned to a strobe to determine the order of enabling rails. A single rail is assigned to only one strobe, but multiple rails can be assigned to the same strobe. The delay times between strobes are between 2 ms and 5 ms.

7.3.1.1 Power-Up Sequencing

When the power-up sequence initiates, STROBE 1 occurs, and any rail assigned to this strobe is enabled. After a delay time of DLY1, STROBE 2 occurs and the rail assigned to this strobe is powered up. The sequence continues until all strobes occur and all DLYx times execute. Strobe assignments and delay times are defined in the SEQx registers, and are changed under I²C control. The power-up sequence executes if one of the following events occurs:

- From the OFF state:
 - The push-button (PB) is pressed (falling edge on PB) *or*
 - The AC_DET pin is pulled low (falling edge) *or*
 - The PWR_EN is asserted (driven to high-level) *or*
 - The main power is connected (IN_BIAS) and AC_DET is grounded *and*
 - The device is not in undervoltage lockout (UVLO) or overtemperature shutdown (OTS).
- From the PRE_OFF state:
 - The PB is pressed (falling edge on PB) *or*
 - The AC_DET pin is pulled low (falling edge) *or*
 - The PWR_EN is asserted (driven to high-level) *and*
 - The device is not in UVLO or OTS.
- From the SUSPEND state:
 - The PB is pressed (falling edge on PB) *or*
 - The AC_DET pin is pulled low (falling edge) *or*
 - The PWR_EN pin is pulled high (level sensitive) *and*
 - The device is not in UVLO or OTS.

When a power-up event is detected, the device enters a WAIT_PWR_EN state and triggers the power-up sequence. The device remains in WAIT_PWR_EN as long as the PWR_EN and either the PB or AC_DET pin are held low. If both, the PB and AC_DET return to logic-high state and the PWR_EN pin has not been asserted within 20 s of entering WAIT_PWR_EN state, the power-down sequence is triggered and the device returns to OFF state. Once PWR_EN is asserted, the device advances to ACTIVE state, which is functionally equivalent to WAIT_PWR_EN. However, the AC_DET pin is ignored and power-down is controlled by the PWR_EN pin only.

Rails not assigned to a strobe (SEQ = 0000b) are not affected by power-up and power-down sequencing and remain in their current ON or OFF state regardless of the sequencer. A rail can be enabled and disabled at any time by setting the corresponding enable bit in the ENABLEx register, with the exception that the ENABLEx register cannot be accessed while the sequencer is active. Enable bits always reflect the current enable state of the rail. For example, the sequencer sets and resets the enable bits for the rails under its control.

Note

The power-up sequence is defined by strobes and delay times, and can be triggered by the PB, AC_DET (not shown, same as PB), or PWR_EN pin.

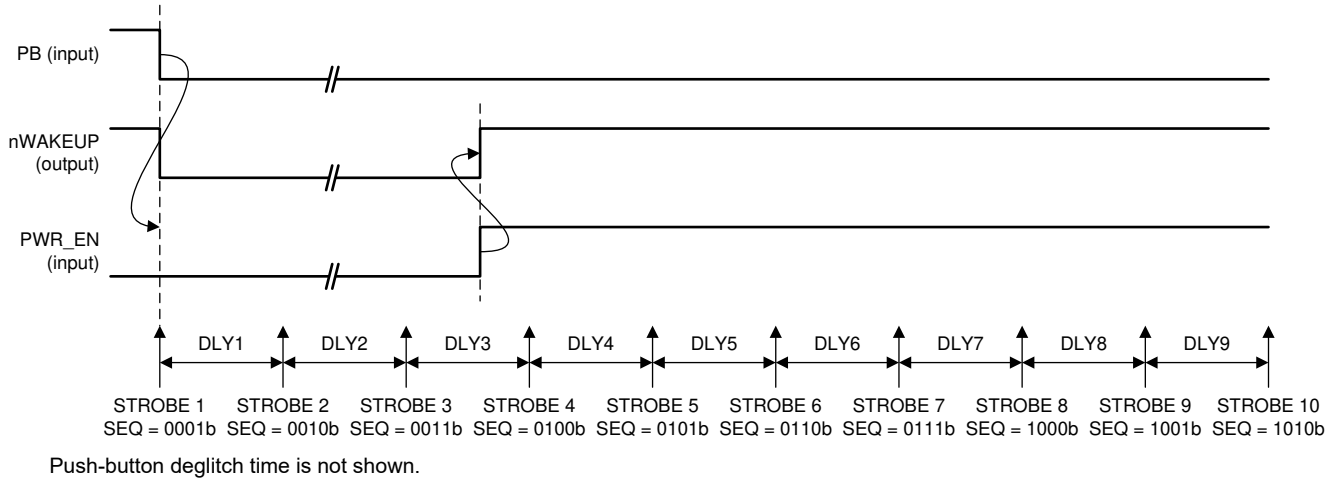


Figure 7-1. Power-Up Sequences from OFF or SUSPEND State; PB is Power-Up Event

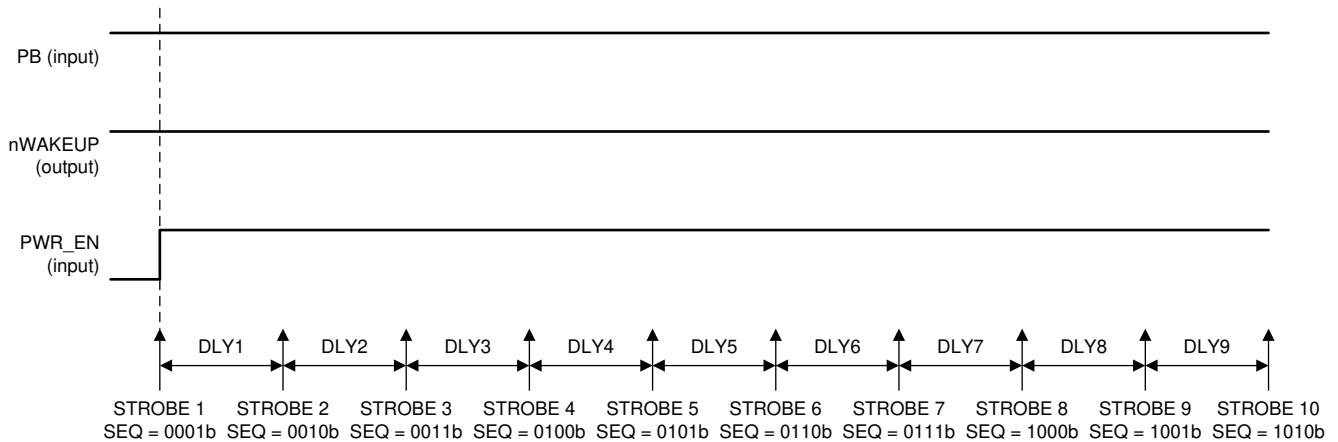


Figure 7-2. Power-Up Sequences from SUSPEND State; PWR_EN is Power-Up Event

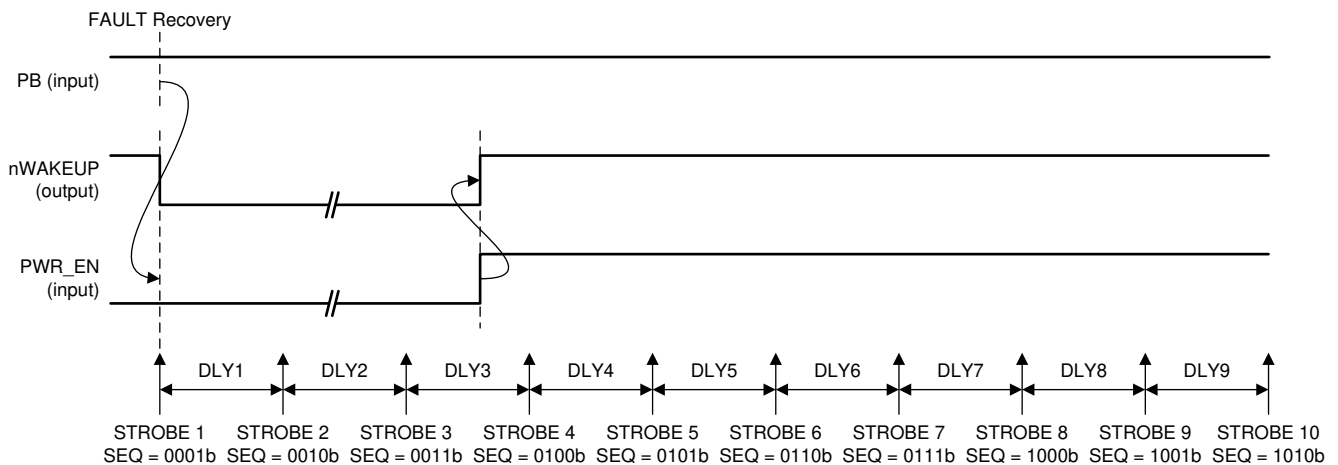


Figure 7-3. Power-Up Sequences from RECOVERY State

7.3.1.2 Power-Down Sequencing

By default, the power-down sequence follows the reverse of the power-up sequence. When the power-down sequence is triggered, STROBE 10 occurs and any rail assigned to STROBE 10 is shut down and its discharge circuit is enabled. After a delay time of DLY9, STROBE 9 occurs and any rail assigned to it is shut down and its discharge circuit is enabled. The sequence continues until all strobos occur and all DLYx times execute. The DLYx times are extended by a factor of 10x to provide ample time for discharge, and preventing output voltages from crossing during shut-down. The DLYFCTR bit is applied globally to all power-down delay times. Regardless of the DLYx and DLYFCTR settings, the PMIC enters OFF, SUSPEND, or RECOVERY state 500 ms after the power-down sequence initiates, to ensure that the discharge circuits remain enabled for a minimum of 150 ms before the next power-up sequence starts.

A power-down sequence executes if one of the following events occurs:

- The device is in the WAIT_PWR_EN state, the PB and AC_DET pins are high, PWR_EN is low, and the 20-s timer has expired.
- The device is in the ACTIVE state and the PWR_EN pin is pulled low.
- The device is in the WAIT_PWR_EN, ACTIVE, or SUSPEND state and the push-button is held low for > 8 s (15 s if TRST = 1b).
- A fault occurs in the device (OTS, UVLO, PGOOD failure).

When transitioning from ACTIVE to SUSPEND state, the rails not controlled by the power-down sequencer maintains the same ON/OFF state in SUSPEND state that it had in ACTIVE state. This allows for the selected power rails to remain powered up when in the SUSPEND state.

When transitioning to the OFF or RECOVERY state, rails not under sequencer control are shut-down as follows:

- DCDC1, DCDC2, DCDC3, DCDC4, LDO1, and LS1 shut down at the beginning of the power-down sequence, if not under sequencer control (SEQ = 0b).
- LS2 and LS3 shut down as the state machine enters an OFF or RECOVERY state; 500 ms after the power-down sequence is triggered.

If the supply voltage on IN_BIAS drops below 2.5 V, the digital core is reset and all power rails are shut down instantaneously and are pulled low to ground by their internal discharge circuitry (DCDC1-4, and LDO1). The amount of time the discharge circuitry remains active is a function of the INT_LDO hold up time (see [Section 7.3.1.5](#) for more details).

7.3.1.3 Strobe 1 and Strobe 2

STROBE 1 and STROBE 2 are dedicated to DCDC5 and DCDC6 which are *always-on*; powered up as soon as the device exits the OFF state, and ON in any other state. STROBE 1 and STROBE 2 options are available only for DCDC5 and DCDC6, not for any other rails.

STROBE 1 and STROBE 2 occur in every power-up sequence, regardless if the rail is already powered up. If the rail is not to be powered up, its respective strobe setting must be set to 0x00.

When a power-down sequence initiates, STROBE 1 and STROBE 2 occur only if the FSEAL bit is 0b. Otherwise, both strobos are omitted and DCDC5 and DCDC6 maintain state.

Note

The power-down sequence follows the reverse of the power-up sequence. STROBE2 and STROBE1 are executed only if FSEAL bit is 0b.

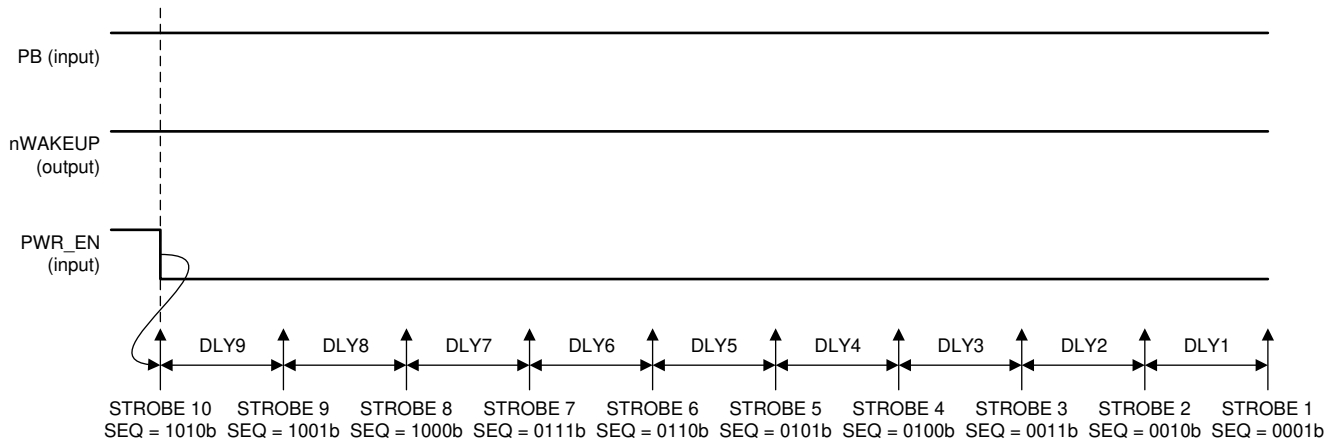
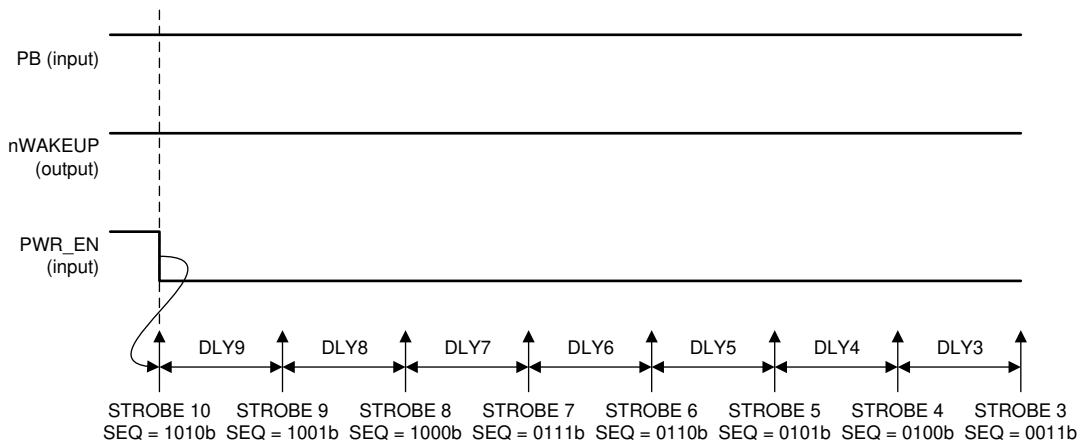
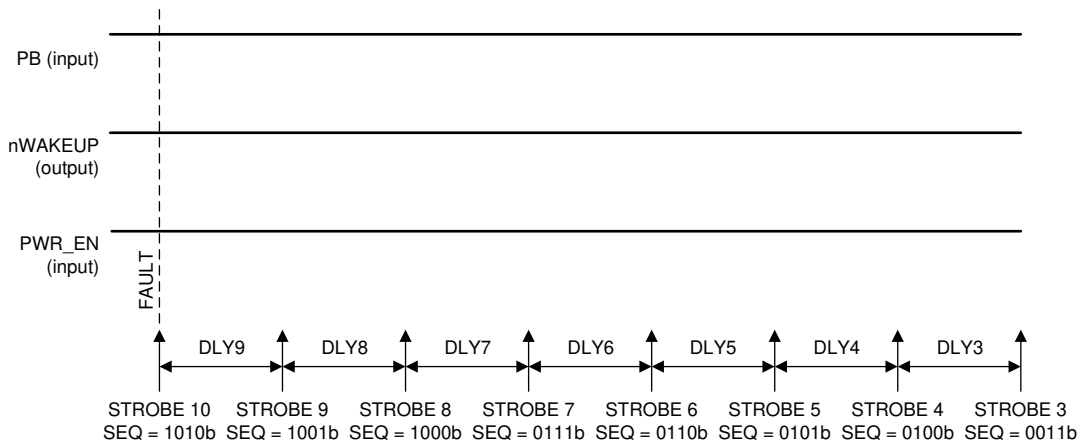


Figure 7-4. Power-Down Sequences to OFF State; PWR_EN is Power-Down Event; FSEAL = 0b



STROBE2 and STROBE1 are not shown.

Figure 7-5. Power-Down Sequences to SUSPEND State; PWR_EN is Power-Down Event; FSEAL = 1b



STROBE2 and STROBE1 are not shown.

Figure 7-6. Power-Down Sequences to RECOVERY State; TSD or UV is Power-Down Event; FSEAL = 1b

7.3.1.4 Supply Voltage Supervisor and Power-Good (PGOOD)

Power-good (PGOOD) is an open-drain output of the built-in voltage supervisor that monitors DCDC1, DCDC2, DCDC3, DCDC4, and LDO1. The output is Hi-Z when all enabled rails are in regulation and driven low when one or more rails encounter a fault which brings the output voltage outside the specified tolerance range. In a typical application PGOOD drives the reset signal of the SOC.

The supervisor has two modes of operation, controlled by the STRICT bit. With the STRICT bit set to 0, all enabled rails of the five regulators are monitored for undervoltage only with relaxed thresholds and deglitch times. With the STRICT bit set to 1, all enabled rails of the five regulators are monitored for undervoltage and overvoltage with tight limits and short deglitch times. [Table 7-1](#) summarizes these details.

Table 7-1. Supervisor Characteristics Controlled by the STRICT Bit

PARAMETER		STRICT = 0b (TYP)	STRICT = 1b (TYP)
Undervoltage monitoring	Threshold (output falling)	90%	96.5% (DCDC1 and DCDC2) 95.5% (DCDC3, DCDC4, and LDO1)
	Deglitch (output falling)	1 ms	50 μ s
	Deglitch (output rising)	10 μ s	10 μ s
Overvoltage monitoring	Threshold (output falling)	N/A	103.5% (DCDC1 and DCDC2) 104.5% (DCDC3, DCDC4, and LDO1)
	Deglitch (output falling)	N/A	1 ms
	Deglitch (output rising)	N/A	50 μ s

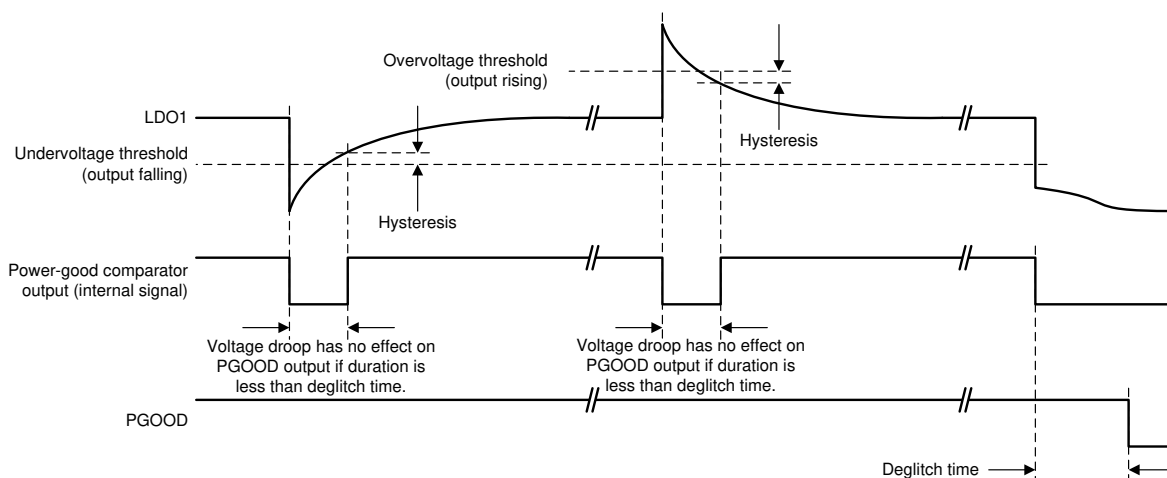
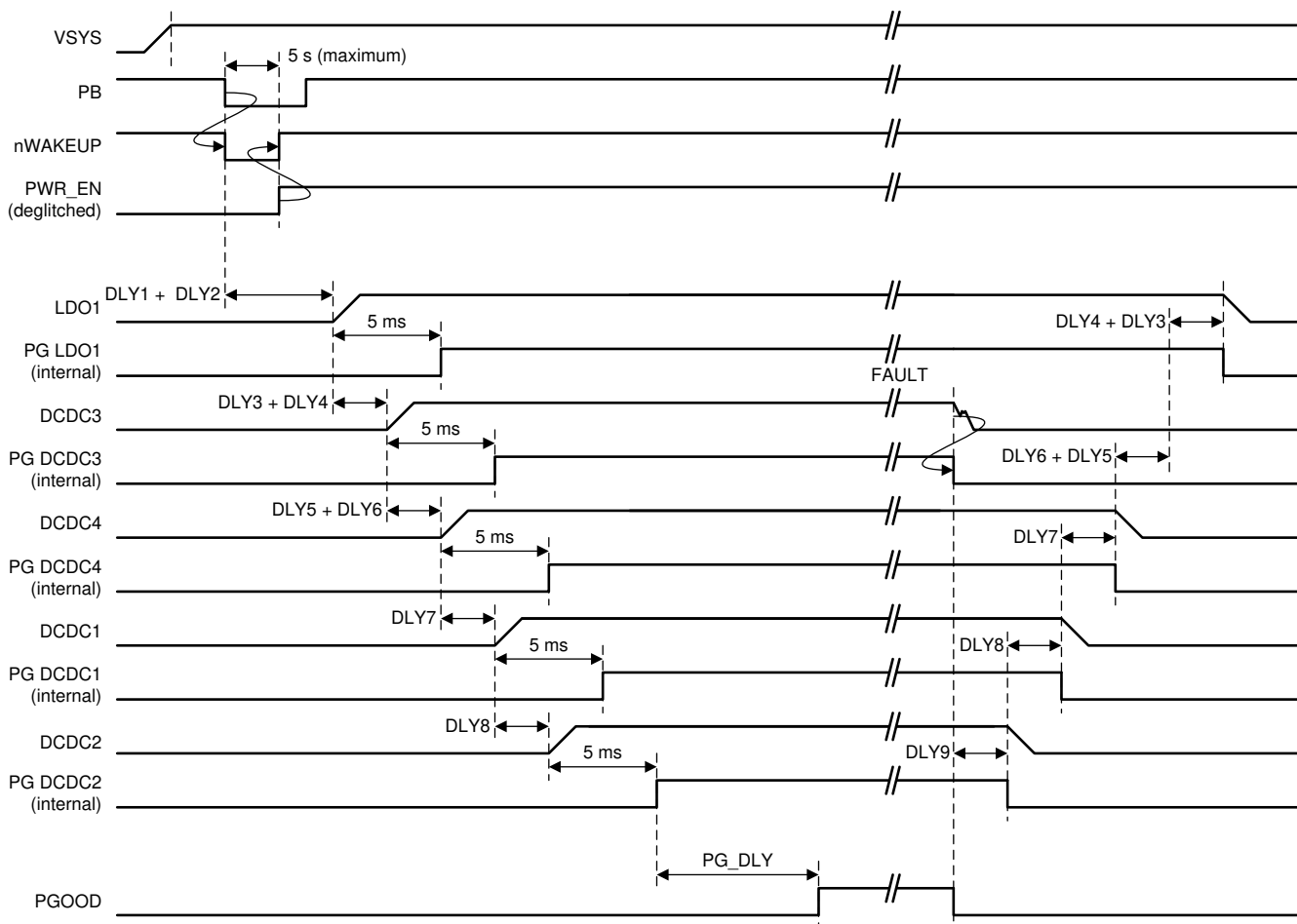


Figure 7-7. Definition of Undervoltage, Overvoltage Thresholds, Hysteresis, and Deglitch Times

The following rules apply to the PGOOD output:

- The power-up default state for THE PGOOD is low. When all rails are disabled, the PGOOD output is driven low.
- Only enabled rails are monitored. Disabled rails are ignored.
- Power-good monitoring of a particular rail starts 5 ms after the rail is enabled and is continuously monitored thereafter. This allows the rail to power-up.
- The PGOOD is delayed by PGDLY time after the sequencer is finished and the last rail is enabled.
- If an enabled rail is continuously outside the monitoring threshold for longer than the deglitch time, then the PGOOD is pulled low, and all rails are shut-down following the power-down sequence. PGDLY does not apply.
- Disabling a rail manually by resetting the DCx_EN or LDO1_EN bit has no effect on the PGOOD pin. If all rails are disabled, the PGOOD is driven low as the last rail is disabled.
- If the power-down sequencer is triggered, PGOOD is driven low.
- The PGOOD is driven low in the SUSPEND state, regardless of the number of rails that are enabled.

Figure 7-8 shows a typical power-up sequence and PGOOD timing.



A. Sequence shown for TPS65218D0 variant. For other TPS65218xx variants, refer to registers SEQ1-7 in [Section 7.5.4](#) for factory-programmed sequence order and timing.

Figure 7-8. Typical Power-Up Sequence of the Main Output Rails

7.3.1.5 Internal LDO (INT_LDO)

The internal LDO (INT_LDO) provides a regulated voltage to the internal digital core and analog circuitry. The internal LDO has a nominal output voltage of 2.5 V and can support up to 10 mA of external load.

When system power fails, the UVLO comparator triggers the power-down sequence. If system power drops below 2.3 V, the digital core is reset and all remaining power rails are shut down instantaneously and are pulled low to ground by their internal discharge circuitry (DCDC1-4 and LDO1).

The internal LDO reverse blocks to prevent the discharging of the output capacitor (C_{INT_LDO}) on the INT_LDO pin. The remaining charge on the INT_LDO output capacitor provides a supply for the power rail discharge circuitry to ensure the outputs are discharged to ground even if the system supply has failed. The amount of hold-up time specified in [Section 6.5](#) is a function of the output capacitor value (C_{INT_LDO}) and the amount of external load on the INT_LDO pin, if any. The design allows for enough hold-up time to sufficiently discharge DCDC1-4, and LDO1 to ensure proper processor power-down sequencing.

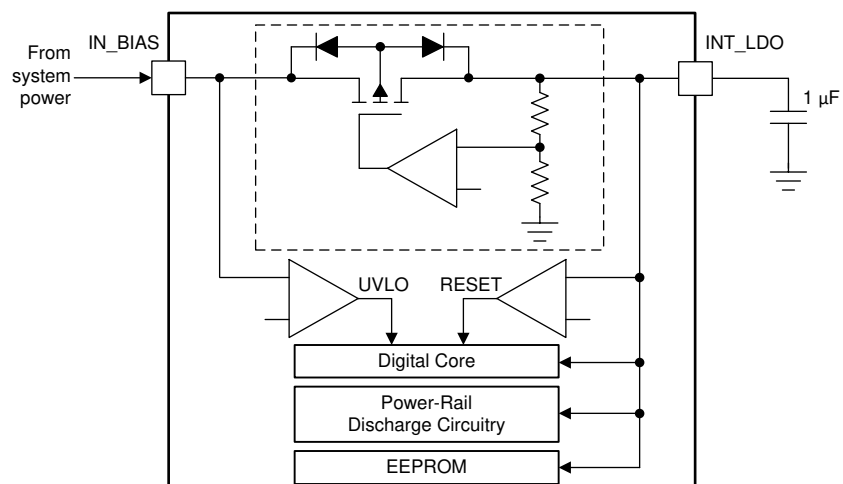


Figure 7-9. Internal LDO and UVLO Sensing

7.3.1.6 Current Limited Load Switches

The TPS6521855 provides three current limited load switches with individual inputs, outputs, and enable control. Each switch provides the following control and diagnostic features:

- The ON or OFF state of the switch is controlled by the corresponding LSx_EN bit in the ENABLE register.
- LS1 can be controlled by the sequencer or through I²C communication.
- LS2 and LS3 can *only* be controlled through I²C communication. The sequencer has no control over LS2 and LS3.
- Each switch has an active discharge function, disabled by default, and enabled through the LSxDCHRG bit. When enabled, the switch output is discharged to ground whenever the switch is disabled.
- When the PFI input drops below the power-fail threshold (the power-fail comparator trips), the load switches are automatically disabled to shed system load. This function must be individually enabled for each switch through the corresponding LSxnPFO bit. The switches do not turn back on automatically as the system voltage recovers, and must be manually re-enabled.
- An interrupt (LSx_I) issues whenever a load switch actively limits the output current, such as when the output load exceeds the current limit value. The switch remains ON and provides current to the load according to the current-limit setting.
- All three load switches have local overtemperature sensors which disable the corresponding switch if the power dissipation and junction temperature exceeds the safe operating value. The switch automatically recovers once the temperature drops below the OTS threshold value minus hysteresis. The LSx_F (fault) interrupt bit is set while the switch is held OFF by the OTS function.

7.3.1.6.1 Load Switch 1 (LS1)

LS1 is a non-reverse blocking, low-voltage (< 3.6 V), low-impedance switch intended to support DDRx self-refresh mode by cutting off the DDRx supply to the SOC DDRx interface during SUSPEND mode. In a typical application, the input of LS1 is tied to the output of DCDC3 while the output of LS1 is connected to the memory-interface supply pin of the SOC. LS1 can be controlled by the internal sequencer, just as any power rail.

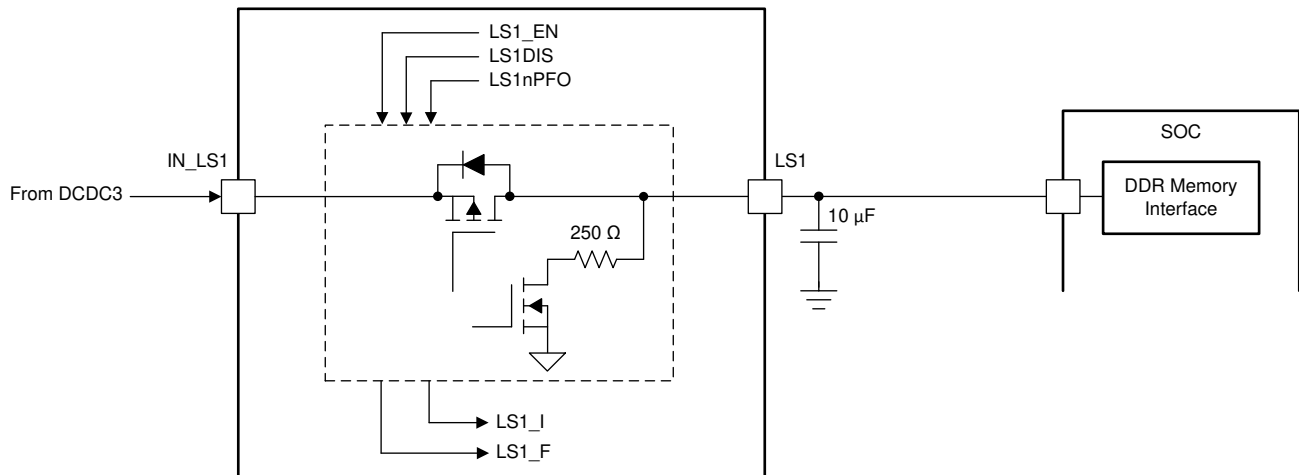


Figure 7-10. Typical Application of Load Switch 1

7.3.1.6.2 Load Switch 2 (LS2)

LS2 is a reverse-blocking, 5 V, low-impedance switch. Load switch 2 provides four different current limit values (100/200/500/1000 mA) that are selectable through LS2ILIM[1:0] bits. Overcurrent is reported through the LS2_I interrupt.

LS2 has its own input-undervoltage protection which forces the switch OFF if the switch input voltage (V_{IN_LS2}) is < 2.7 V. Similar to OTS, the LS2_F interrupt is set when the switch is held OFF by the local UVLO function, and the switch recovers automatically when the input voltage rises above the UVLO threshold.

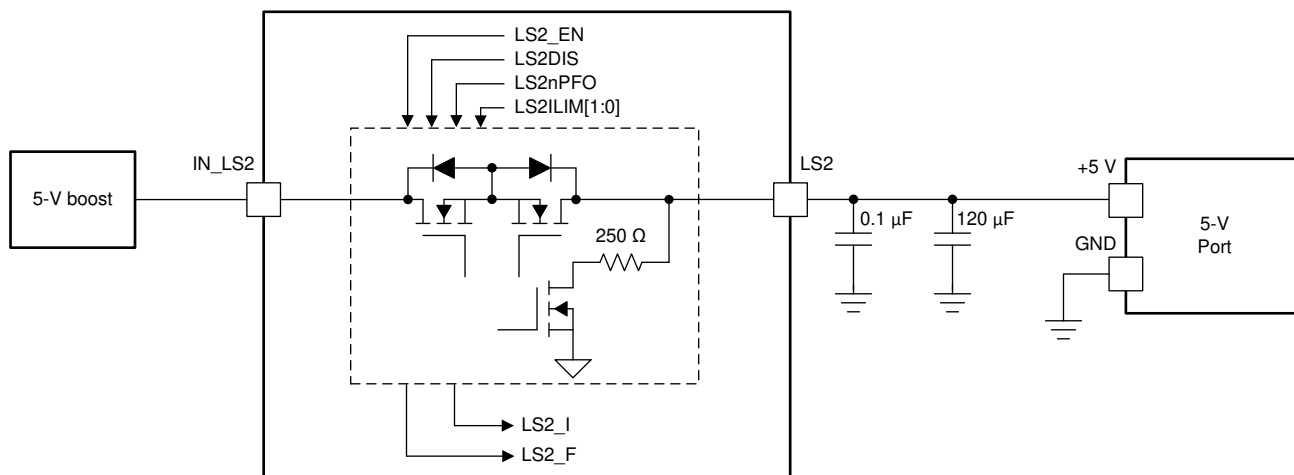


Figure 7-11. Typical Application of Load Switch 2

7.3.1.6.3 Load Switch 3 (LS3)

LS3 is a non-reverse blocking, medium-voltage (< 10 V), low-impedance switch that can be used to provide 1.8-V to 10-V power to an auxiliary port. LS3 has four selectable current limit values that are selectable through LS3ILIM[1:0].

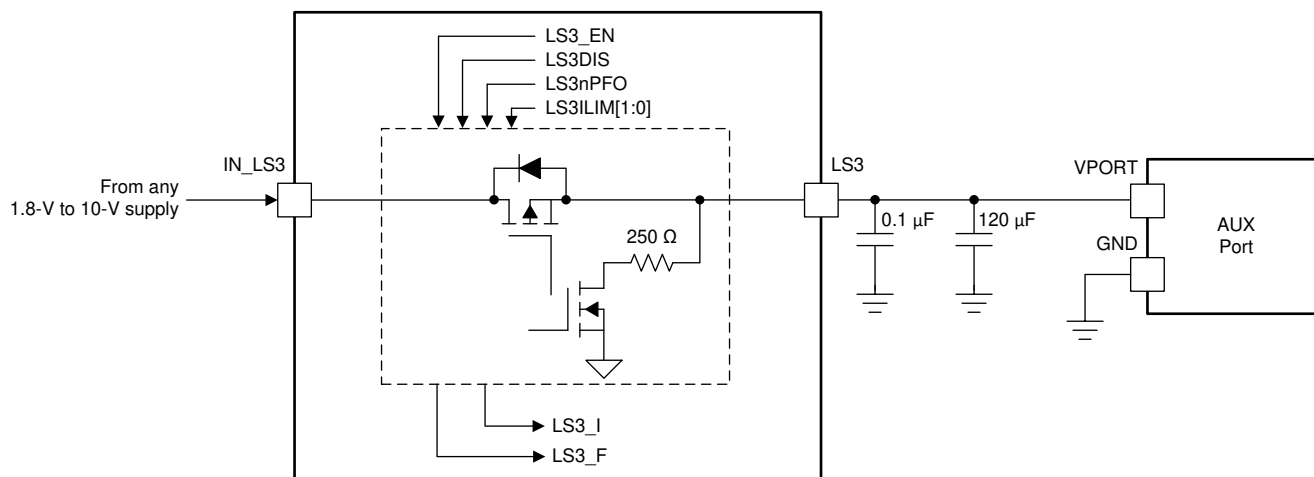


Figure 7-12. Typical Application of Load Switch 3

7.3.1.7 LDO1

LDO1 is a general-purpose LDO intended to provide power to analog circuitry on the SOC. LDO1 has an input voltage range from 1.8 V to 5.5 V, and can be connected either directly to the system power or the output of a DCDC converter. The output voltage is programmable in the range of 0.9 V to 3.4 V with a default of 1.8 V. LDO1 supports up to 200 mA at the minimum specified headroom voltage, and up to 400 mA at the typical operating condition of $V_{OUT} = 1.8$ V, $V_{IN_LDO1} > 2.7$ V.

7.3.1.8 UVLO

Depending on the slew rate of the input voltage into the IN_BIAS pin, the power rails of TPS6521855 will be enabled at either V_{ULVO} or $V_{ULVO} + V_{HYS}$.

If the slew rate of the IN_BIAS voltage is greater than 30 V/s, then TPS6521855 will power up at V_{ULVO} . Once the input voltage rises above this level, the input voltage may drop to the V_{ULVO} level before the PMIC shuts down. In this scenario, if the input voltage were to fall below V_{ULVO} but above 2.55 V, the input voltage would have to recover above V_{ULVO} in less than 5 ms for the device to remain active.

If the slew rate of the IN_BIAS voltage is less than 30 V/s, then TPS6521855 will power up at $V_{ULVO} + V_{HYS}$. Once the input voltage rises above this level, the input voltage may drop to the V_{ULVO} level before the PMIC shuts down. In this scenario, if the input voltage were to fall below V_{ULVO} but above 2.5 V, the input voltage would have to recover above $V_{ULVO} + V_{HYS}$ in less than 5 ms for the device to remain active.

In either slew rate scenario, if the input voltage were to fall below 2.5 V, the digital core is reset and all remaining power rails are shut down instantaneously and are pulled low to ground by their internal discharge circuitry (DCDC1-4 and LDO1).

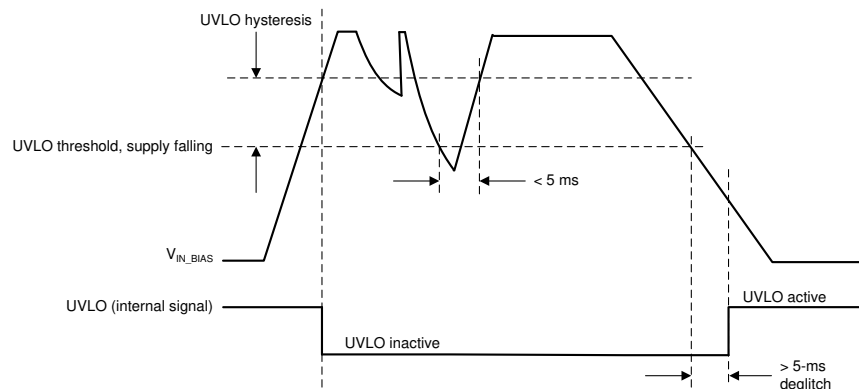


Figure 7-13. Definition of UVLO and Hysteresis

After the UVLO triggers, the internal LDO blocks current flow from its output capacitor back to the IN_BIAS pin, allowing the digital core and the discharge circuits to remain powered for a limited amount of time to properly shut-down and discharge the output rails. The hold-up time is determined by the value of the capacitor connected to INT_LDO. See [Section 7.3.1.5](#) for more details.

7.3.1.9 Power-Fail Comparator

The power-fail comparator notifies the system host if the system supply voltage drops and the system is at risk of shutting down. The comparator has an internal 800-mV threshold and the trip-point is adjusted by an external resistor divider.

By default, the power-fail comparator has no impact on any of the power rails or load switches. Load switches are configured individually, to be disabled when the PFI comparator trips to shed system load and extend hold-up time as described in [Section 7.3.1.6](#). The power-fail comparator also triggers the power-down sequencer, such that all or selective rails power-down when the system voltage fails. To tie the power-fail comparator into the power-down sequence, the OFFnPFO bit in the CONTROL register must be set to 1.

The power-fail comparator cannot be monitored by software, such that no interrupt or status bit is associated to this function.

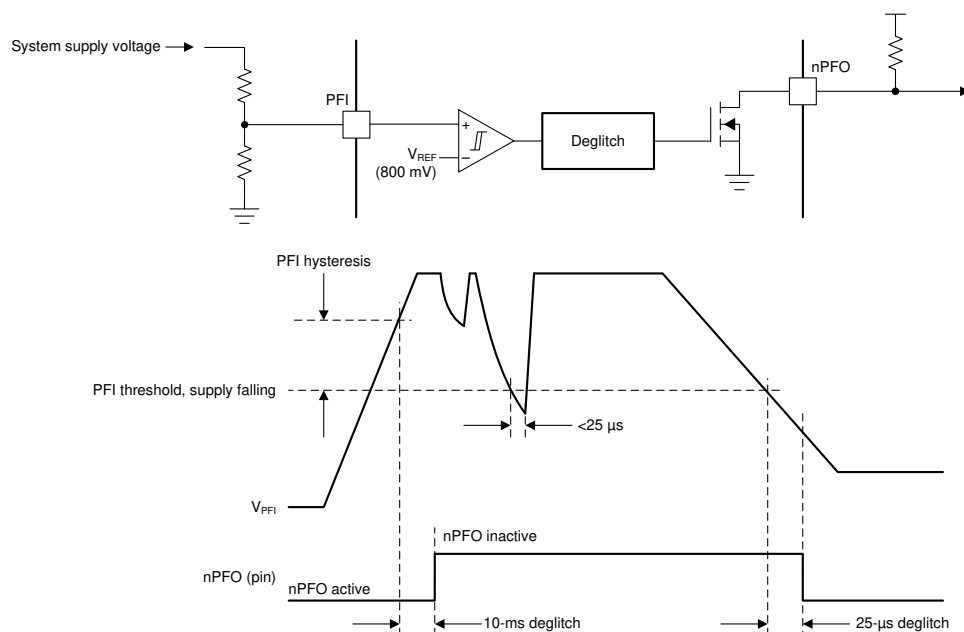


Figure 7-14. Power-Fail Comparator Simplified Circuit and Timing Diagram

7.3.1.10 DCDC3 and DCDC4 Power-Up Default Selection

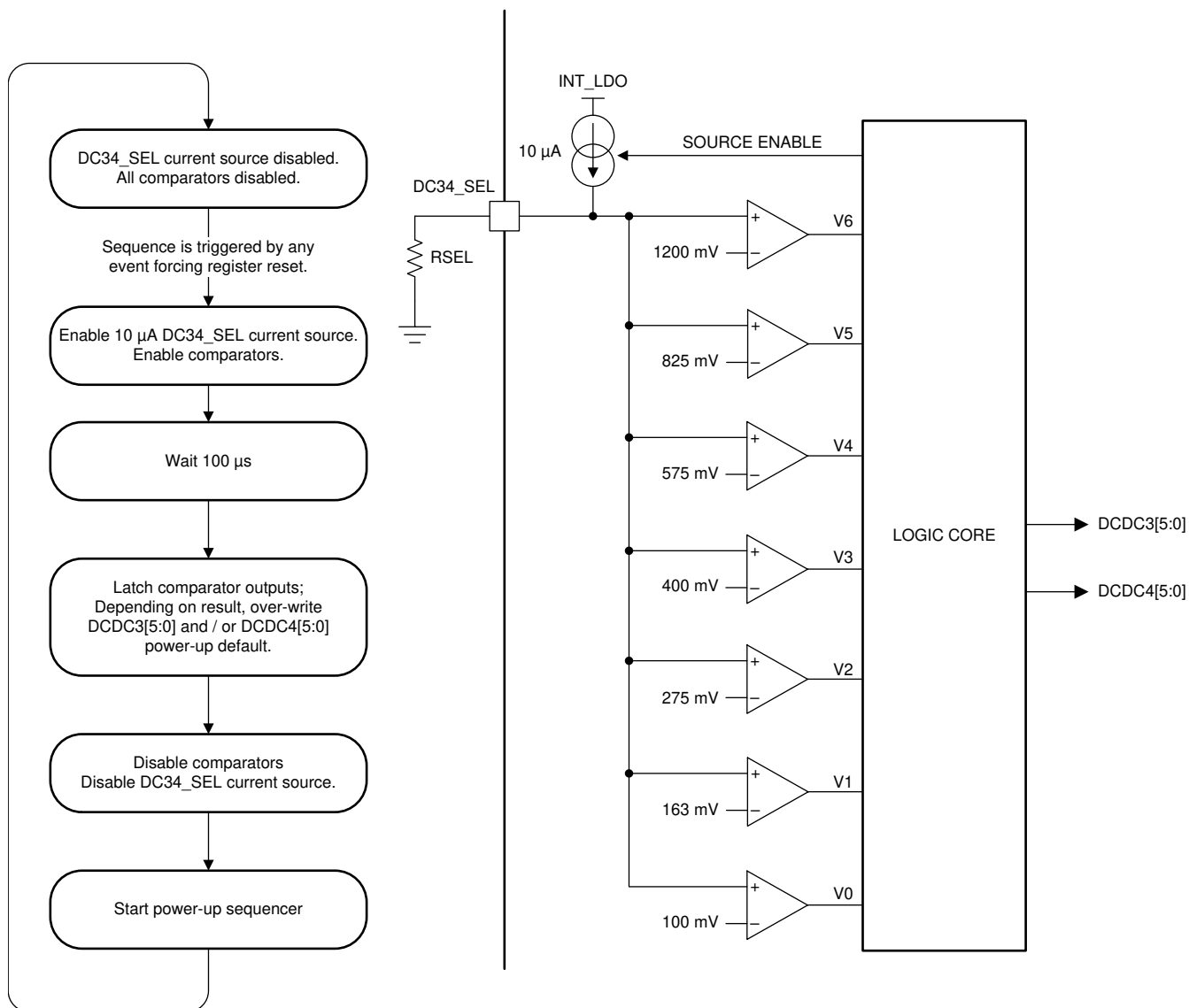


Figure 7-15. Left: Flow Chart for Selecting DCDC Power-Up Default Voltage Right: Comparator Circuit

Table 7-2. Power-Up Default Values of DCDC3 and DCDC4

RSEL [KΩ]			POWER-UP DEFAULT	
MIN	TYP	MAX	DCDC3[5:0]	DCDC4[5:0]
0	0	7.7	0xCh (1.2 V)	0x32h (3.3 V)
11.8	12.1	12.4	0x12 (1.35 V)	0x32h (3.3 V)
19.5	20	20.5	0x18 (1.5 V)	0x32h (3.3 V)
30.9	31.6	32.3	Programmed default (1.8 V)	0x32h (3.3 V)
44.4	45.3	46.3	0x3D (3.3 V)	0x01 (1.2 V)
64.8	66.1	67.3	0xCh (1.2 V))	0x07 (1.35 V)
93.6	95.3	97.2	0xCh (1.2 V)	0x0D (1.5 V)
146	150	Tied to INT_LDO	0xCh (1.2 V)	0x14 (1.8 V)

7.3.1.11 I/O Configuration

The device has two GPIOs and one GPO pin, which are configured as follows:

- GPIO1:
 - General-purpose, open-drain output is controlled by the GPO1 user bit or sequencer.
 - DDR3 reset input signal from SOC. The signal is either latched or passed-through to the GPO2 pin. See [Table 7-3](#) for details.
- GPO2:
 - General-purpose output is controlled by the GPO2 user bit.
 - DDR3 reset output signal. Signal is controlled by GPIO1 and PGOOD. See [Table 7-4](#) for details.
 - Output buffer is configured as open-drain or push-pull.
- GPIO3:
 - General-purpose, open-drain output id controlled by the GPO3 user bit or sequencer.
 - Reset input-signal for DCDC1 and DCDC2.

Table 7-3. GPIO1 Configuration

IO1_SEL (EEPROM)	GPO1 (USER BIT)	PGOOD (PMIC SIGNAL)	GPIO1 (I/O PIN)	COMMENTS
0	0	X	0	Open-drain output, driving low
0	1	X	HiZ	Open-drain output, HiZ
1	X	0	X	Pin is configured as input and intended as DDR RESET signal. Coming out of POR, GPO2 is driven low. Otherwise, GPO2 status is latched at falling edge of PGOOD. See Figure 7-17 .
1	X	1	0	Pin is configured as input and intended as DDR RESET signal. GPO2 is driven low.
1	X	1	1	Pin is configured as input and intended as DDR RESET signal. GPO2 is driven high.

Table 7-4. GPO2 Configuration

IO1_SEL (EEPROM)	GPO2_BUF (EEPROM)	GPO2 (USER BIT)	COMMENTS
0	0	0	GPO2 is open drain output controlled by GPO2 user bit (driving low).
0	0	1	GPO2 is open drain output controlled by GPO2 user bit (HiZ).
0	1	0	GPO2 is push-pull output controlled by GPO2 user bit (driving low).
0	1	1	GPO2 is push-pull output controlled by GPO2 user bit (driving high).
1	0	X	GPO2 is open drain output controlled by GPIO1 and PGOOD.
1	1	X	GPO2 is push-pull output controlled by GPIO1 and PGOOD.

Table 7-5. GPIO3 Configuration

DC12_RST (EEPROM)	GPO3 (USER BIT)	GPIO3 (I/O PIN)	COMMENTS
0	0	0	Open-drain output, driving low
0	1	HiZ	Open-drain output, HiZ
1	X	Active low	GPIO3 is DCDC1 and DCDC2 reset input signal to PMIC (active low). See Section 7.3.1.11.1 for details.

7.3.1.11.1 Using GPIO3 as Reset Signal to DCDC1 and DCDC2

The GPIO3 is an edge-sensitive reset input to the PMIC, when the DC12_RST bit set to 1. The reset signal affects DCDC1 and DCDC2 only, so that only those two registers are reset to the power-up default whenever GPIO3 input transitions from high to low, while all other registers maintain their current values. DCDC1 and DCDC2 transition back to the default value following the SLEW settings, and are not power cycled. This function recovers the processor from reset events while in low-power mode.

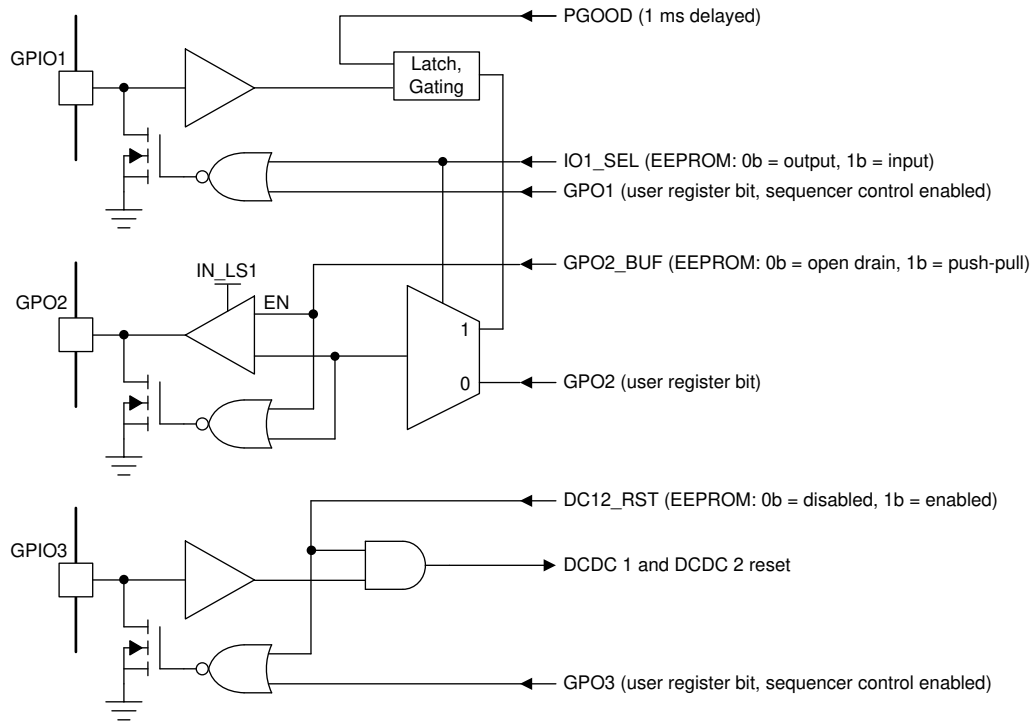


Figure 7-16. I/O Pin Logic

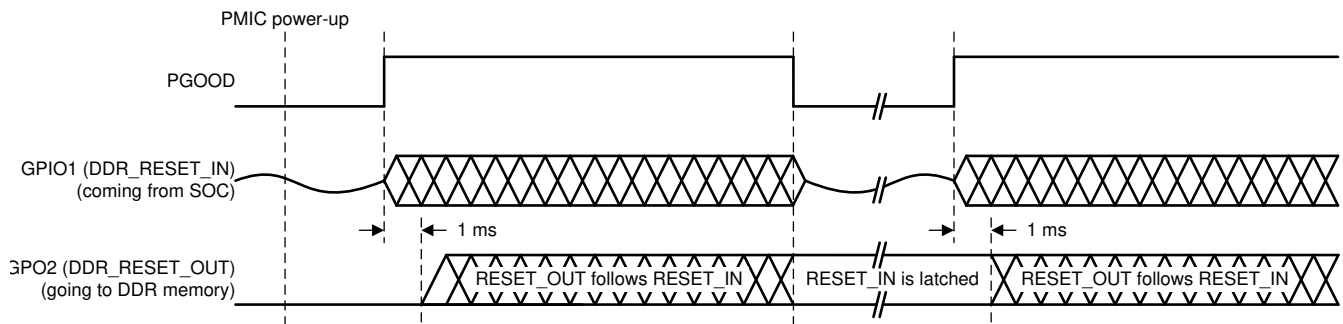


Figure 7-17. DDR3 Reset Timing Diagram

Note

GPIO must be configured as input (IO1_SEL = 1b). GPO2 is automatically configured as output.

7.3.1.12 Push Button Input (PB)

The PB pin is a CMOS-type input used to power-up the PMIC. Typically, the PB pin is connected to a momentary switch to ground and an external pullup resistor. The power-up sequence is triggered if the PB input is held low for 600 ms.

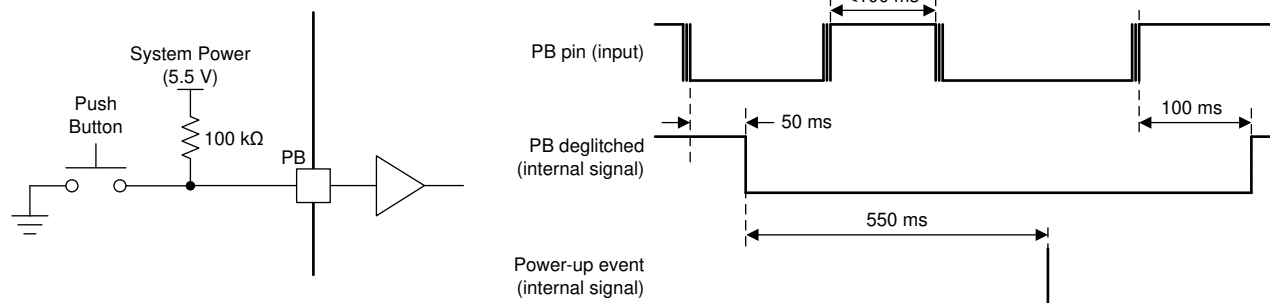


Figure 7-18. Left: Typical PB Input Circuit Right: Push-Button Input (PB) Deglitch and Power-Up Timing

In ACTIVE mode, the TPS6521855 monitors the PB input and issues an interrupt when the pin status changes, such as when it drops below or rises above the PB input-low or input-high thresholds. The interrupt is masked by the PBM bit in the INT_MASK1 register.

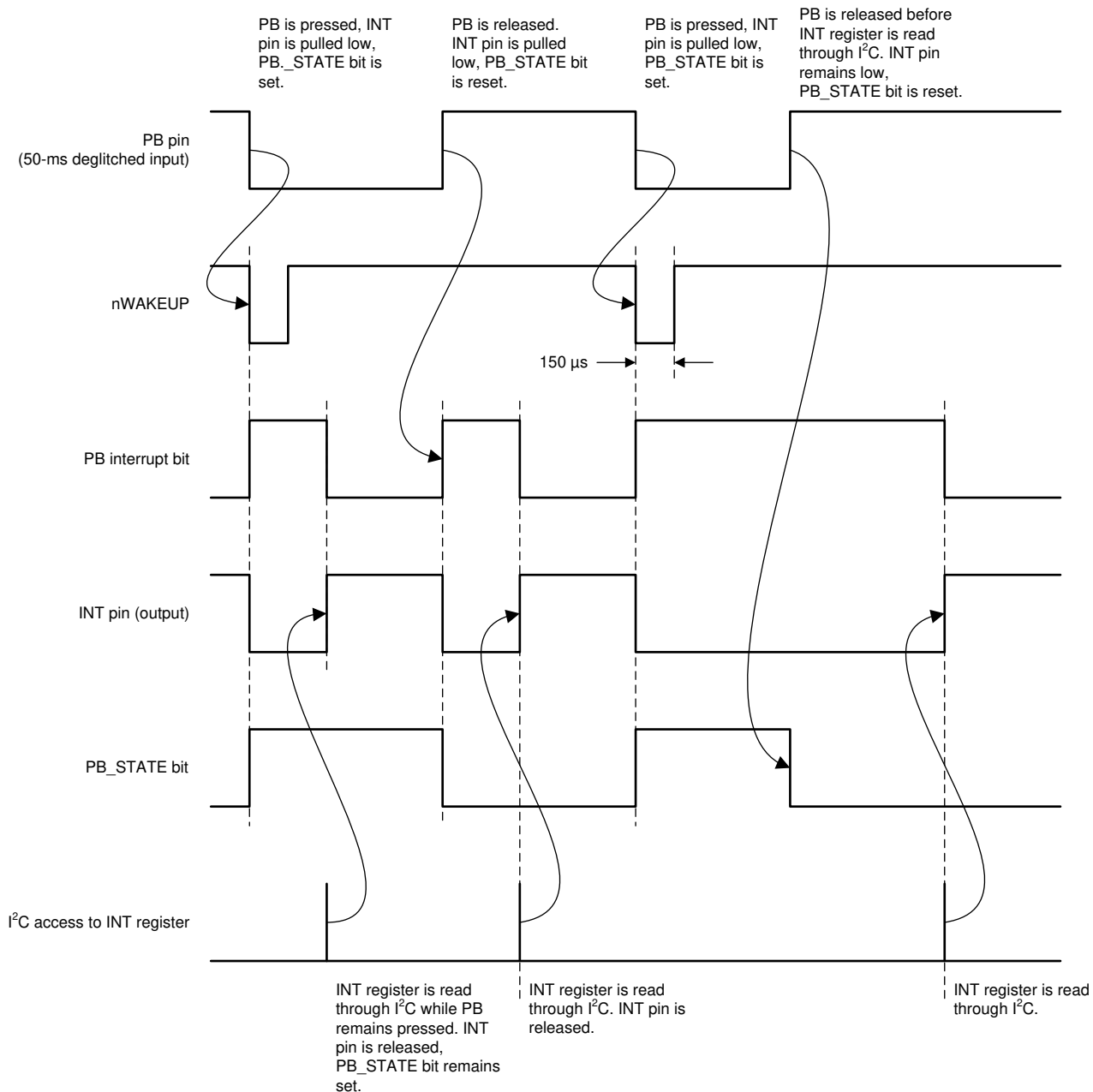


Figure 7-19. PB Input-Low or Input-High Thresholds

Note

Interrupts are issued whenever the PB pin status changes. The PB_STATE bit reflects the current status of the PB input. nWAKEUP is pulled low for 150 μ s on every falling edge of PB.

7.3.1.12.1 Signaling PB-Low Event on the nWAKEUP Pin

In ACTIVE state, the nWAKEUP pin is pulled low for five 32-kHz clock cycles (approximately 150 μ s) whenever a falling edge on the PB input is detected. This allows the host processor to wakeup from DEEP SLEEP mode of operation. It is recommended to pull-up the nWAKEUP pin to DCDC6 output through a 1-M Ω resistor.

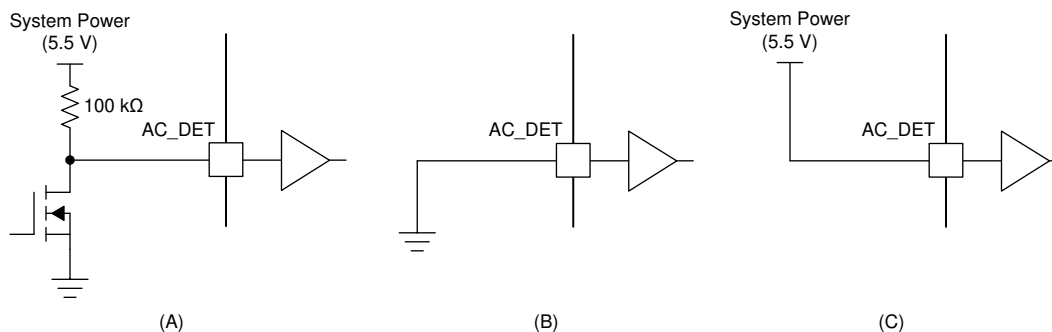
7.3.1.12.2 Push Button Reset

If the PB input is pulled low for 8 s (15 s if TRST = 1b) or longer, then all rails except for DCDC5 and DCDC6 are disabled, and the device enters the RECOVERY state. The device powers up automatically after the 500 ms power-down sequence is complete, regardless of the state of the PB input. Holding the PB pin low for 8 s (15 s if TRST = 1b), only turns off the device temporarily and forces a system restart, and is not a power-down function. If the PB is held low continuously, the device power-cycles in 8-s and 15-s intervals.

7.3.1.13 AC_DET Input (AC_DET)

The AC_DET pin is a CMOS-type input used in three different ways to control the power-up of the PMIC:

- In a battery operated system, AC_DET is typically connected to an external battery charger with an open-drain power-good output pulled low when a valid charger supply is connected to the system. A falling edge on the AC_DET pin causes the PMIC to power up.
- In a non-portable system, the AC_DET pin may be shorted to ground and the device powers up whenever system power is applied to the chip.
- If none of the above behaviors are desired, AC_DET may be tied to system power (IN_BIAS). Power-up is then controlled through the push-button input or PWR_EN input.



- A. Portable Systems
B. Non-portable Systems
C. Disabled

Figure 7-20. AC_DET Pin Configurations

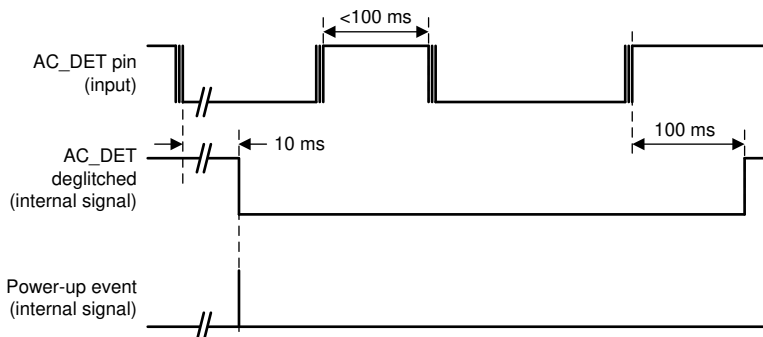


Figure 7-21. AC_DET Input Deglitch and Power-Up Timing (Portable Systems)

In ACTIVE state, the TPS6521855 monitors the AC_DET input and issues an interrupt when the pin status changes, such as when it drops below or rises above the AC_DET input-low or input-high thresholds. The interrupt is masked by the ACM bit in the INT_MASK1 register.

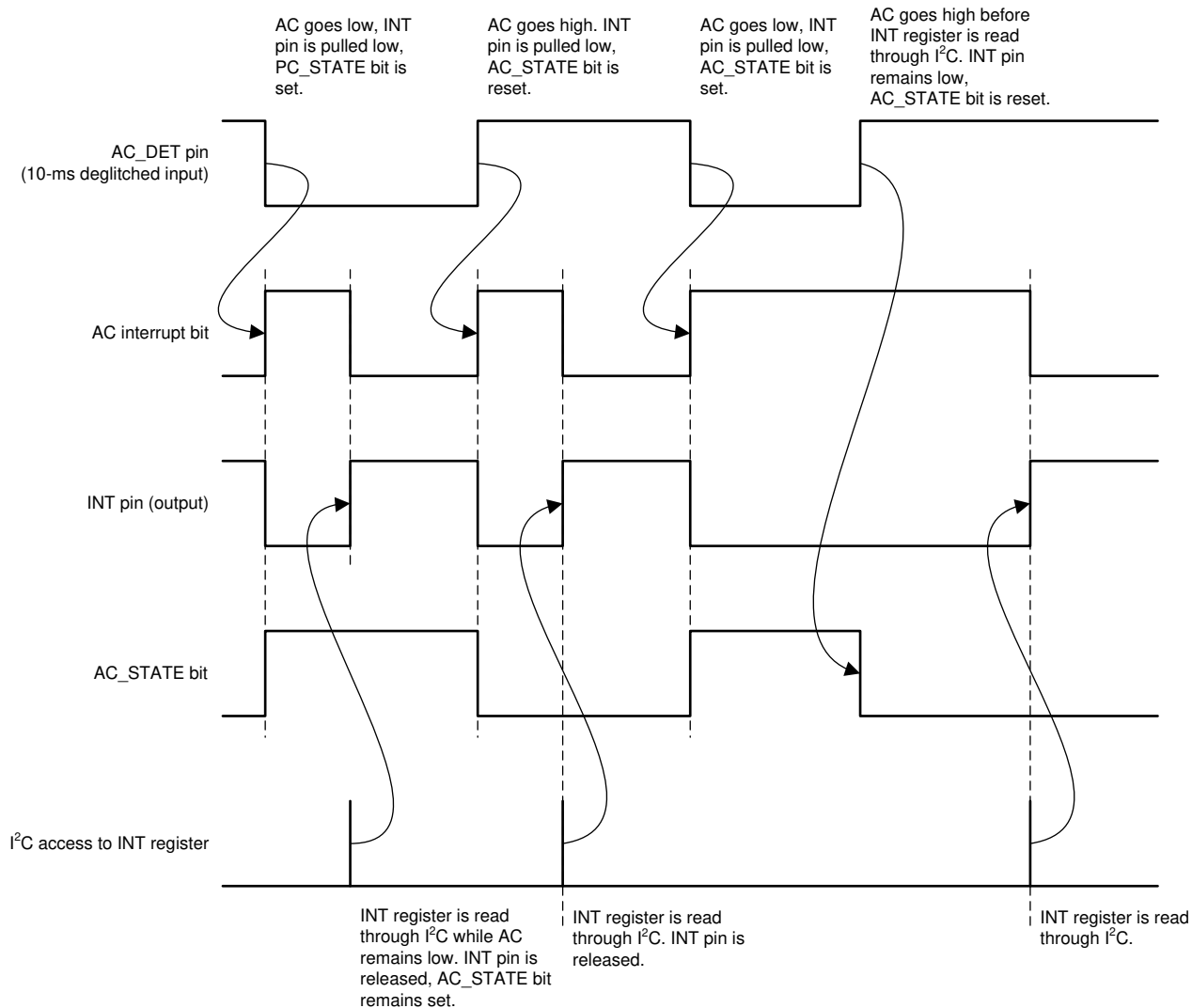


Figure 7-22. AC_STATE Pin

Note

Interrupts are issued whenever the AC_DET pin status changes. The AC_STATE bit reflects the current status of the AC_DET input.

7.3.1.14 Interrupt Pin (INT)

The interrupt pin signals any event or fault condition to the host processor. Whenever a fault or event occurs in the device, the corresponding interrupt bit is set in the INT register, and the open-drain output is pulled low. The INT pin is released (returns to Hi-Z state) and fault bits are cleared when the host reads the INT register. If a failure persists, the corresponding INT bit remains set and the INT pin is pulled low again after a maximum of 32 μ s.

The MASK register masks events from generating interrupts. The MASK settings affect the INT pin only, and have no impact on the protection and monitor circuits.

7.3.1.15 I²C Bus Operation

The TPS6521855 hosts a slave I²C interface (address 0x24) that supports data rates up to 400 kbps, auto-increment addressing.¹

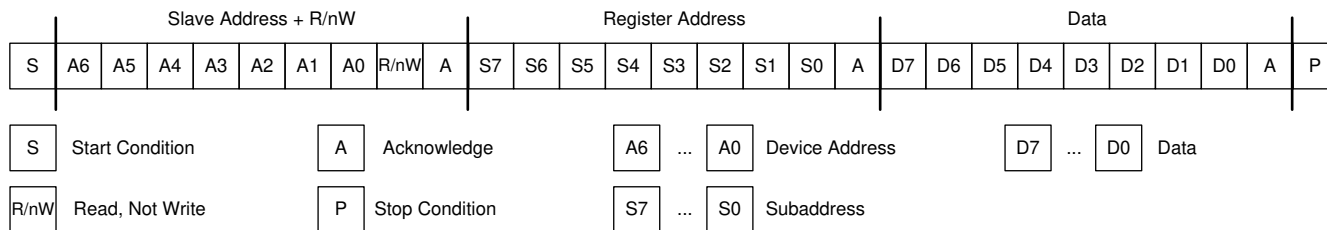


Figure 7-23. Subaddress in I²C Transmission

The I²C bus is a communications link between a controller and a series of slave terminals. The link is established using a two-wired bus consisting of a serial clock signal (SCL) and a serial data signal (SDA). The serial clock is sourced from the controller in all cases where the serial data line is bi-directional for data communication between the controller and the slave terminals. Each device has an open drain output to transmit data on the serial data line. An external pullup resistor must be placed on the serial data line to pull the drain output high during data transmission.

Data transmission initiates with a start bit from the controller as shown in [Figure 7-25](#). The start condition is recognized when the SDA line transitions from high to low during the high portion of the SCL signal. Upon reception of a start bit, the device receives serial data on the SDA input and checks for valid address and control information. If the appropriate slave address is set for the device, the device issues an acknowledge pulse and prepares to receive register address and data. Data transmission is completed by either the reception of a stop condition or the reception of the data word sent to the device. A stop condition is recognized as a low to high transition of the SDA input during the high portion of the SCL signal. All other transitions of the SDA line must occur during the low portion of the SCL signal. An acknowledge issues after the reception of valid slave address, register-address, and data words. The I²C interfaces an auto-sequence through the register addresses, so that multiple data words can be sent for a given I²C transmission. Reference [Figure 7-24](#) and [Figure 7-25](#) for details.

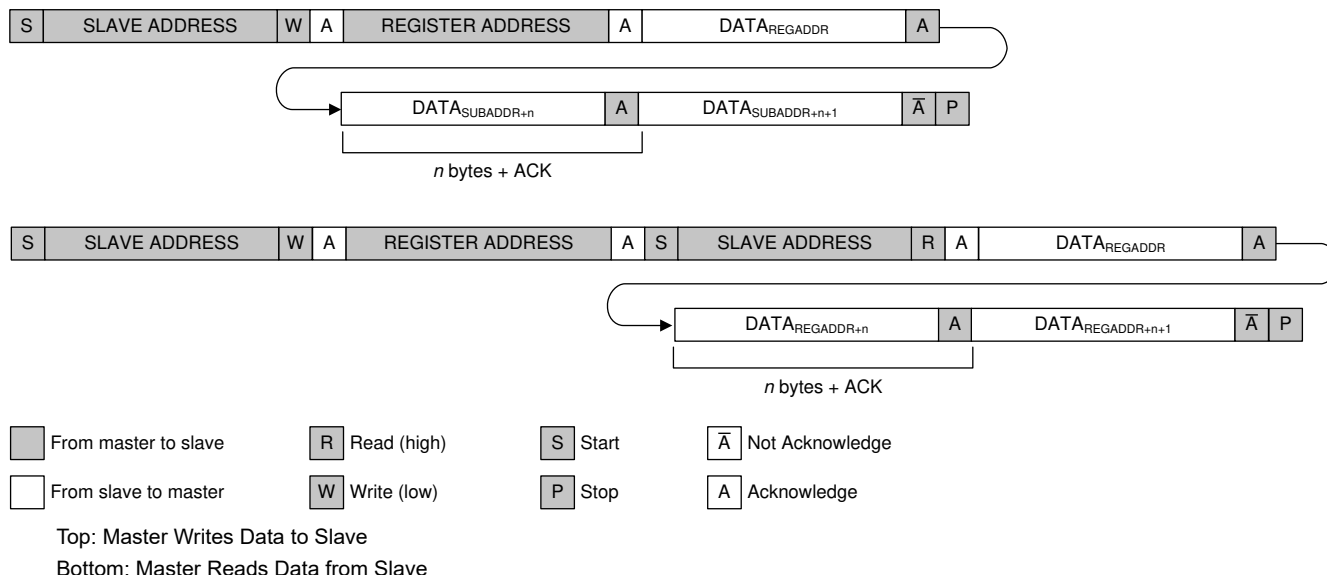


Figure 7-24. I²C Data Protocol

¹ Note: The SCL duty cycle at 400 kHz must be >40%.

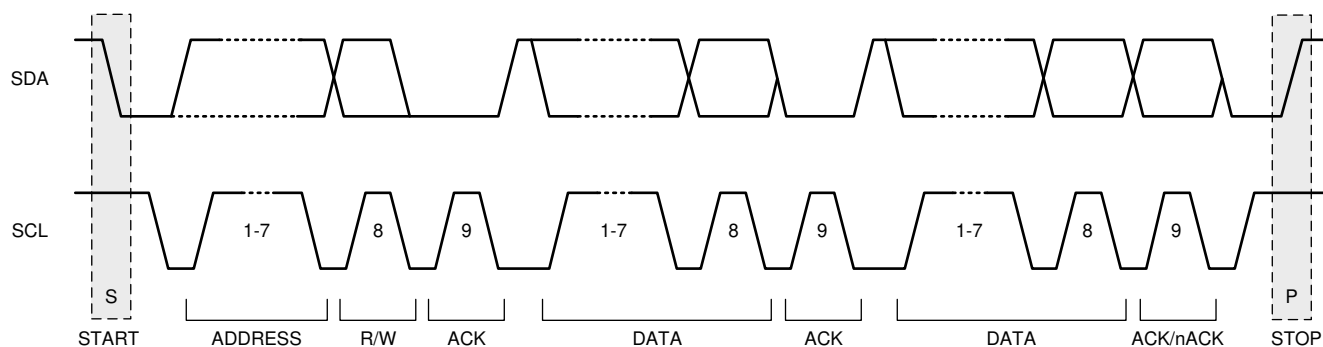


Figure 7-25. I²C Protocol and Transmission Timing I²C Start Stop and Acknowledge Protocol

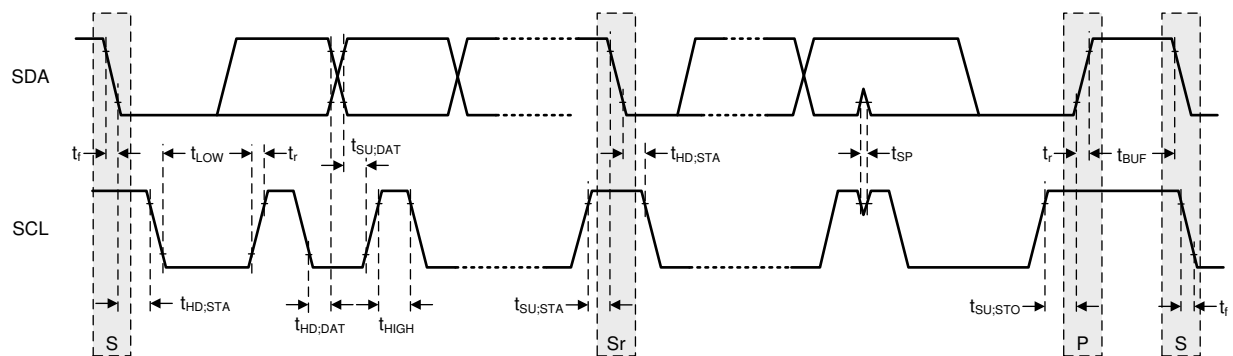
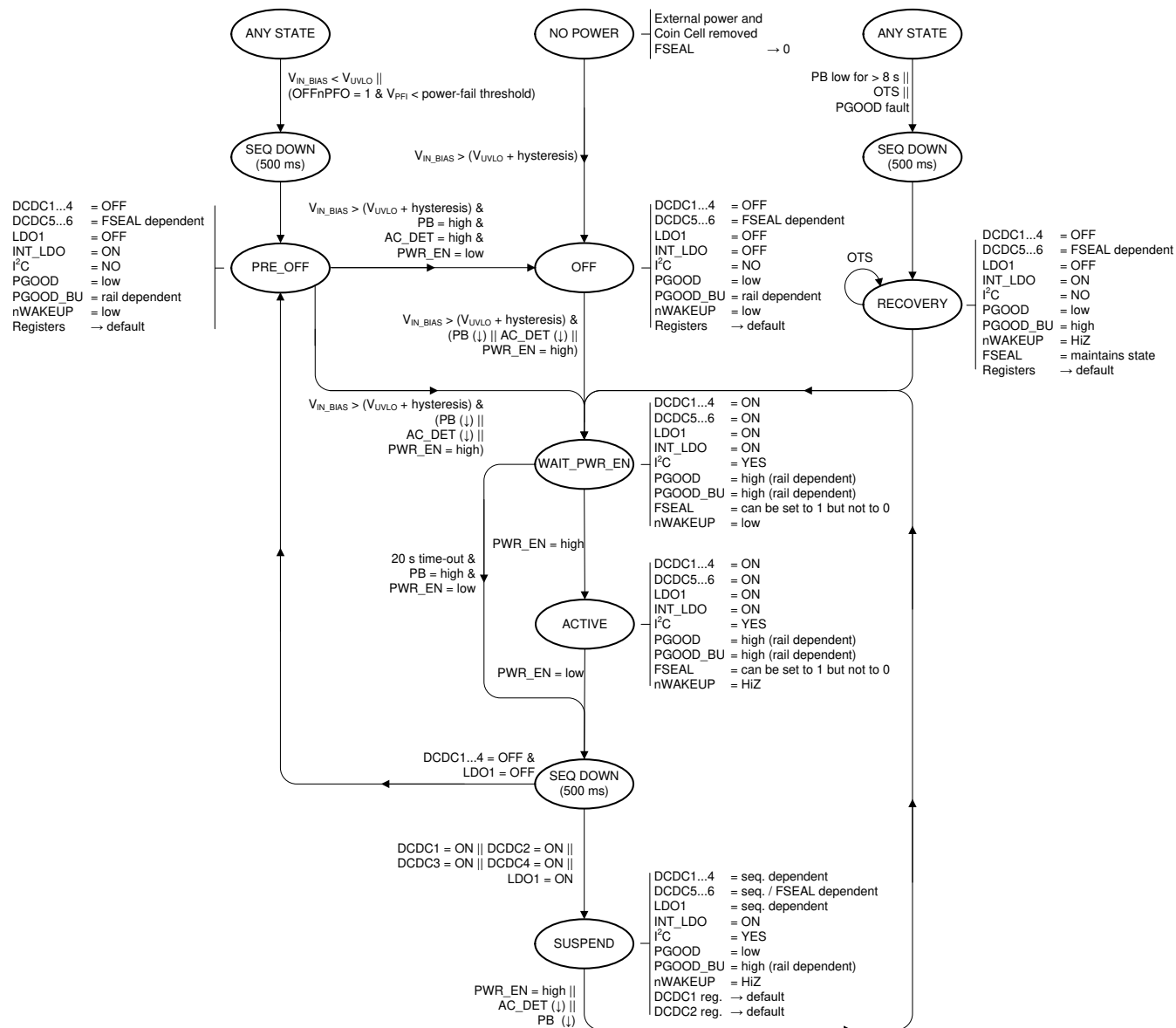


Figure 7-26. I²C Protocol and Transmission Timing I²C Data Transmission Timing

7.4 Device Functional Modes

7.4.1 Modes of Operation



PB (↓) has 50 ms debounce.

AC_DET (↓) has 10 ms debounce.

(↓) = denotes falling edge of signal.

Figure 7-27. Modes of Operation Diagram

7.4.2 OFF

In OFF mode, the PMIC is completely shut down with the exception of a few circuits to monitor the AC_DET, PWR_EN, and PB input. All power rails are turned off and the registers are reset to their default values. The I²C communication interface is turned off. This is the lowest-power mode of operation. To exit OFF mode V_{IN_BIAS} must exceed the UVLO threshold and one of the following wake-up events must occur:

- The PB input is pulled low.
- THE AC_DET input is pulled low.
- The PWR_EN input is pulled high.

To enter the OFF state, ensure that all power rails are assigned to the sequencer, then pull the PWR_EN pin low. Additionally, if the OFFnPFO bit is set to 1b and the PFI input falls below the power fail threshold the device transitions to the OFF state. If the freshness seal is broken, DCDC5 and DCDC6 remains on in the OFF state. If a PGOOD or OTS fault occurs while in the ACTIVE state, TPS6521855 will transition to the RESET state.

7.4.3 ACTIVE

This is the typical mode of operation when the system is up and running. All DCDC converters, LDOs, and load switches are operational and can be controlled through the I²C interface. After a wake-up event, the PMIC enables all rails controlled by the sequencer and pulls the nWAKEUP pin low to signal the event to the host processor. The device only enters the ACTIVE state if the host asserts the PWR_EN pin within 20 s after the wake-up event. Otherwise it will enter the OFF state. The nWAKEUP pin returns to HiZ mode after the PWR_EN pin is asserted. The ACTIVE state can also be directly entered from the SUSPEND state by pulling the PWR_EN pin high. See the SUSPEND state description for details. To exit the ACTIVE mode, the PWR_EN pin must be pulled low.

7.4.4 SUSPEND

The SUSPEND state is a low-power mode of operation intended to support system standby. Typically all power rails are turned off with the exception of any rail with an SEQ register set to 0h. DCDC5 and DCDC6 also remain enabled if the freshness seal is broken. To enter the SUSPEND state, pull the PWR_EN pin low. All power rails controlled by the power-down sequencer are shut down, and after 500 ms the device enters the SUSPEND state. All rails not controlled by the power-down sequencer will maintain its state. Note: all register values are reset as the device enters the SUSPEND state. The device enters the ACTIVE state after it detects a wake-up event as described in the previous sections.

7.4.5 RESET

The TPS6521855 can be reset by holding the PB pin low for more than 8 or 15 s, depending on the value of the TRST bit. All rails are shut down by the sequencer and all register values reset to their default values. Rails not controlled by the sequencer are shut down additionally. Note: the RESET function power-cycles the device and only temporarily shuts down the output rails. Resetting the device does not lead to an OFF state. If the PB_IN pin is kept low for an extended amount of time, the device continues to cycle between the ACTIVE and RESET state, entering the RESET every 8 or 15 s.

The device is also reset if a PGOOD or OTS fault occurs. The TPS6521855 remains in the RECOVERY state until the fault is removed, at which time it transitions back to the ACTIVE state.

7.5 Register Maps

7.5.1 Password Protection

Registers 0x11 through 0x26 are protected against accidental write by a 8-bit password. The password must be written prior to writing to a protected register and automatically resets to 0x00 after the next I²C transaction, regardless of the register accessed or transaction type (read or write). The password is required for write access only and is not required for read access.

To write to a protected register:

1. Write the address of the destination register, XORed with the protection password (0x7D), to the PASSWORD register (0x10).
2. Write the data to the password protected register.
3. If the content of the PASSWORD register is XORed, with an address send that matches 0x7D, then the data transfers to the protected register. Otherwise, the transaction is ignored. In either case the PASSWORD register resets to 0x00 after the transaction.

The cycle must be repeated for any other register that is Level1 write protected.

7.5.2 Freshness Seal (FSEAL) Bit

The FSEAL (freshness seal) bit prevents accidental shut-down of the always-on supplies, DCDC5 and DCDC6. The FSEAL bit exists in a default state of 0b, and can be set to 1b and reset to 0b once for factory testing. The second time the bit is set to 1b, it remains 1b and cannot reset again under software control. Coin-cell battery and main supply must be disconnected from the device to reset the FSEAL bit again. With the FSEAL bit set to 1b, DCDC5 and DCDC6 are forced ON regardless of the state of the DC5_EN and DC6_EN bit, and the rails do not turn off when the device enters the OFF state.

A consecutive write of [0xB1, 0xFE, and 0xA3] to the password register sets the FSEAL bit to 1b. The three bytes must be written consecutively for the sequence to be valid. No other read or write transactions are allowed between the three bytes, or the sequence is invalid. After a valid sequence, the FSEAL bit in the STATUS register reflects the new setting.

After setting the FSEAL bit, the device can enter the OFF state or any other mode of operation without affecting the state of the FSEAL bit, provided the coin-cell supply remains connected to the chip.

A second write of [0xB1, 0xFE, and 0xA3] to the password register resets the FSEAL bit to 0b. The three bytes must be written consecutively for the sequence to be valid.

A third write of [0xB1, 0xFE, and 0xA3] to the password register sets the FSEAL bit to 1b and locks it into this state for as long as the coin-cell supply (CC) remains connected to the device.

7.5.3 FLAG Register

The FLAG register contains a bit for each power rail and GPO to keep track of the enable state of the rails while the system is suspended. The following rules apply to the FLAG register:

- The power-up default value for any flag bit is 0.
- Flag bits are read-only and cannot be written to.
- Upon entering a SUSPEND state, the flag bits are set to same value as their corresponding ENABLE bits. Rails and GPOs enabled in a SUSPEND state have flag bits set to 1, while all other flag bits are set to 0. Flag bits are not updated while in the SUSPEND state or when exiting the SUSPEND state.
- The FLAG register is static in WAIT_PWR_EN and ACTIVE state. The FLAG register reflects the enable state of DCDC1, DCDC2, DCDC3, DCDC4, and LDO1; and, reflects the enable state of GPO1, GPO2, and GPO3 during the last SUSPEND state.

The host processor reads the FLAG register to determine if the system powered up from the OFF or SUSPEND state. In the SUSPEND state, typically the DDR memory is kept in self refresh mode and therefore the DC3_FLG or DC4_FLG bits are set.

7.5.4 TPS6521855 Registers

Table 7-6 lists the memory-mapped registers for the TPS6521855. All register offset addresses not listed in Table 7-6 should be considered as reserved locations and the register contents should not be modified.

Table 7-6. TPS6521855 Registers

SUBADDRESS	ACRONYM	REGISTER NAME	R/W	PASSWORD PROTECTED	SECTION
0x00	CHIPID	CHIP ID	R	No	Section 7.5.5
0x01	INT1	INTERRUPT 1	R	No	Section 7.5.6
0x02	INT2	INTERRUPT 2	R	No	Section 7.5.7
0x03	INT_MASK1	INTERRUPT MASK 1	R/W	No	Section 7.5.8
0x04	INT_MASK2	INTERRUPT MASK 2	R/W	No	Section 7.5.9
0x05	STATUS	STATUS	R	No	Section 7.5.10
0x06	CONTROL	CONTROL	R/W	No	Section 7.5.11
0x07	FLAG	FLAG	R	No	Section 7.5.12
0x10	PASSWORD	PASSWORD	R/W	No	Section 7.5.13
0x11	ENABLE1	ENABLE 1	R/W	Yes	Section 7.5.14
0x12	ENABLE2	ENABLE 2	R/W	Yes	Section 7.5.15
0x13	CONFIG1	CONFIGURATION 1	R/W	Yes	Section 7.5.16
0x14	CONFIG2	CONFIGURATION 2	R/W	Yes	Section 7.5.17
0x15	CONFIG3	CONFIGURATION 3	R/W	Yes	Section 7.5.18
0x16	DCDC1	DCDC1 CONTROL	R/W	Yes	Section 7.5.19
0x17	DCDC2	DCDC2 CONTROL	R/W	Yes	Section 7.5.20
0x18	DCDC3	DCDC3 CONTROL	R/W	Yes	Section 7.5.21
0x19	DCDC4	DCDC4 CONTROL	R/W	Yes	Section 7.5.22
0x1A	SLEW	SLEW RATE CONTROL	R/W	Yes	Section 7.5.23
0x1B	LDO1	LDO1 CONTROL	R/W	Yes	Section 7.5.24
0x20	SEQ1	SEQUENCER 1	R/W	Yes	Section 7.5.25
0x21	SEQ2	SEQUENCER 2	R/W	Yes	Section 7.5.26
0x22	SEQ3	SEQUENCER 3	R/W	Yes	Section 7.5.27
0x23	SEQ4	SEQUENCER 4	R/W	Yes	Section 7.5.28
0x24	SEQ5	SEQUENCER 5	R/W	Yes	Section 7.5.29
0x25	SEQ6	SEQUENCER 6	R/W	Yes	Section 7.5.30
0x26	SEQ7	SEQUENCER 7	R/W	Yes	Section 7.5.31

Table 7-7 explains the common abbreviations used in this section.

Table 7-7. Common Abbreviations

Abbreviation	Description
R	Read
W	Write
R/W	Read and write capable
E2	Backed by EEPROM
h	Hexadecimal notation of a group of bits
b	Hexadecimal notation of a bit or group of bits
X	Do not care reset value

7.5.5 CHIPID Register (subaddress = 0x00) [reset = 0x55]

CHIPID is shown in [Figure 7-23](#) and described in [Table 7-8](#).

Return to [Table 7-6](#).

Figure 7-23. CHIPID Register

7	6	5	4	3	2	1	0
CHIP					REV		
R-Ah					R-5h		

Table 7-8. CHIPID Register Field Descriptions

Bit	Field	Type	Reset	Description
7-3	CHIP	R	Ah	Chip ID: 0h = TPS65218 1h = Future use 2h = TPS6521815 3h = Future use 4h = TPS6521825 5h = Future use 6h = TPS6521835 7h = Future use 8h = TPS6521845 9h = Future use Ah = TPS6521855 ... 1Fh = Future use
2-0	REV	R	5h	Revision code: 0h = Revision 1.0 1h = Revision 1.1 2h = Revision 2.0 3h = Revision 2.1 4h = Revision 3.0 5h = Revision 4.0 (D0) 6h = Future use 7h = Future use

7.5.6 INT1 Register (subaddress = 0x01) [reset = 0x00]

INT1 is shown in [Figure 7-24](#) and described in [Table 7-9](#).

Return to [Table 7-6](#).

Figure 7-24. INT1 Register

7	6	5	4	3	2	1	0
RESERVED		VPRG	AC	PB	HOT	CC_AQC	PRGC
R-00b		R-0b	R-0b	R-0b	R-0b	R-0b	R-0b

Table 7-9. INT1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R	00b	
5	VPRG	R	0b	Programming voltage interrupt: 0b = No significance. 1b = Input voltage is too low for programming power-up default values.

Table 7-9. INT1 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
4	AC	R	0b	AC_DET pin status change interrupt. Note: Status information is available in STATUS register. 0b = No change in status. 1b = AC_DET status change (AC_DET pin changed high to low or low to high).
3	PB	R	0b	Push-button status change interrupt. Note: Status information is available in STATUS register 0b = No change in status. 1b = Push-button status change (PB changed high to low or low to high).
2	HOT	R	0b	Thermal shutdown early warning: 0b = Chip temperature is below HOT threshold. 1b = Chip temperature exceeds HOT threshold.
1	CC_AQC	R	0b	Coin cell battery voltage acquisition complete interrupt: 0b = No significance. 1b = Backup battery status comparators have settled and results are available in STATUS register.
0	PRGC	R	0b	EEPROM programming complete interrupt: 0b = No significance. 1b = Programming of power-up default settings has completed successfully.

7.5.7 INT2 Register (subaddress = 0x02) [reset = 0x00]

INT2 is shown in [Figure 7-25](#) and described in [Table 7-10](#).

Return to [Table 7-6](#).

Figure 7-25. INT2 Register

7	6	5	4	3	2	1	0
RESERVED		LS3_F	LS2_F	LS1_F	LS3_I	LS2_I	LS1_I
R-00b		R-0b	R-0b	R-0b	R-0b	R-0b	R-0b

Table 7-10. INT2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R	00b	
5	LS3_F	R	0b	Load switch 3 fault interrupt: 0b = No fault. Switch is working normally. 1b = Load switch exceeded operating temperature limit and is temporarily disabled.
4	LS2_F	R	0b	Load switch 2 fault interrupt: 0b = No fault. Switch is working normally. 1b = Load switch exceeded operating temperature limit or input voltage dropped below minimum value. Switch is temporarily disabled.
3	LS1_F	R	0b	Load switch 1 fault interrupt: 0b = No fault. Switch is working normally. 1b = Load switch exceeded operating temperature limit and is temporarily disabled.

Table 7-10. INT2 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
2	LS3_I	R	0b	Load switch 3 current-limit interrupt: 0b = Load switch is disabled or not in current limit. 1b = Load switch is actively limiting the output current (output load is exceeding current limit value).
1	LS2_I	R	0b	Load switch 2 current-limit interrupt: 0b = Load switch is disabled or not in current limit. 1b = Load switch is actively limiting the output current (output load is exceeding current limit value).
0	LS1_I	R	0b	Load switch 1 current-limit interrupt: 0b = Load switch is disabled or not in current limit. 1b = Load switch is actively limiting the output current (output load is exceeding current limit value).

7.5.8 INT_MASK1 Register (subaddress = 0x03) [reset = 0x00]

INT_MASK1 is shown in [Figure 7-26](#) and described in [Table 7-11](#).

Return to [Table 7-6](#).

Figure 7-26. INT_MASK1 Register

7	6	5	4	3	2	1	0
RESERVED	VPRGM	ACM	PBM	HOTM	CC_AQCM	PRGCM	
R-00b	R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b

Table 7-11. INT_MASK1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R	00b	
5	VPRGM	R/W	0b	Programming voltage interrupt mask bit. Note: mask bit has no effect on monitoring function: 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin).
4	ACM	R/W	0b	AC_DET interrupt masking bit: 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin). Note: mask bit has no effect on monitoring function.
3	PBM	R/W	0b	PB interrupt masking bit. Note: mask bit has no effect on monitoring function. 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin).
2	HOTM	R/W	0b	HOT interrupt masking bit. Note: mask bit has no effect on monitoring function. 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin).
1	CC_AQCM	R/W	0b	C_AQC interrupt masking bit. Note: mask bit has no effect on monitoring function. 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin).

Table 7-11. INT_MASK1 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
0	PRGCM	R/W	0b	PRGC interrupt masking bit. Note: mask bit has no effect on monitoring function. 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin).

7.5.9 INT_MASK2 Register (subaddress = 0x04) [reset = 0x00]

INT_MASK2 is shown in [Figure 7-27](#) and described in [Table 7-12](#).

Return to [Table 7-6](#).

Figure 7-27. INT_MASK2 Register

7	6	5	4	3	2	1	0
RESERVED		LS3_FM	LS2_FM	LS1_FM	LS3_IM	LS2_IM	LS1_IM
R-00b		R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b

Table 7-12. INT_MASK2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R	00b	
5	LS3_FM	R/W	0b	LS3 fault interrupt mask bit. Note: mask bit has no effect on monitoring function. 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin).
4	LS2_FM	R/W	0b	LS2 fault interrupt mask bit. Note: mask bit has no effect on monitoring function. 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin).
2	LS3_IM	R/W	0b	LS3 current-limit interrupt mask bit. Note: mask bit has no effect on monitoring function. 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin).
1	LS2_IM	R/W	0b	LS2 current-limit interrupt mask bit. Note: mask bit has no effect on monitoring function. 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin).
0	LS1_IM	R/W	0b	LS1 current-limit interrupt mask bit. Note: mask bit has no effect on monitoring function. 0b = Interrupt is unmasked (interrupt event pulls nINT pin low). 1b = Interrupt is masked (interrupt has no effect on nINT pin).

7.5.10 STATUS Register (subaddress = 0x05) [reset = 00XXXXXXb]

Register mask: C0h

STATUS is shown in [Figure 7-28](#) and is described in [Table 7-13](#).

Return to [Table 7-6](#).

Figure 7-28. STATUS Register

7	6	5	4	3	2	1	0
FSEAL	EE	AC_STATE	PB_STATE	STATE		CC_STAT	

Figure 7-28. STATUS Register (continued)

R-0b	R-0b	R-X	R-X	R-X	R-X
------	------	-----	-----	-----	-----

Table 7-13. STATUS Register Field Descriptions

Bit	Field	Type	Reset	Description
7	FSEAL	R	0b	Freshness seal (FSEAL) status. Note: See Section 7.5.2 for details. 0b = FSEAL is in native state (fresh). 1b = FSEAL is broken.
6	EE	R	0b	EEPROM status: 0b = EEPROM values have not been changed from factory default setting. 1b = EEPROM values have been changed from factory default settings.
5	AC_STATE	R	X	AC_DET input status bit: 0b = AC_DET input is inactive (AC_DET input pin is high). 1b = AC_DET input is active (AC_DET input is low).
4	PB_STATE	R	X	PB input status bit: 0b = Push Button input is inactive (PB input pin is high). 1b = Push Button input is active (PB input pin is low).
3-2	STATE	R	X	State machine STATE indication: 0h = PMIC is in transitional state. 1h = PMIC is in WAIT_PWR_EN state. 2h = PMIC is in ACTIVE state. 3h = PMIC is in SUSPEND state.
1-0	CC_STAT	R	X	Coin cell state of charge. Note: Coin-cell voltage acquisition must be triggered first before status bits are valid. See CC_AQ bit in Section 7.5.11 . 0h = $V_{CC} < V_{LOW_LEVEL}$; Coin cell is not present or approaching end-of-life (EOL). 1h = $V_{LOW_LEVEL} < V_{CC} < V_{GOOD_LEVEL}$; Coin cell voltage is LOW. 2h = $V_{GOOD_LEVEL} < V_{CC} < V_{IDEAL_LEVEL}$; Coin cell voltage is GOOD. 3h = $V_{IDEAL} < V_{CC}$; Coin cell voltage is IDEAL.

7.5.11 CONTROL Register (subaddress = 0x06) [reset = 0x00]

CONTROL is shown in [Figure 7-29](#) and described in [Table 7-14](#).

Return to [Table 7-6](#).

Figure 7-29. CONTROL Register

7	6	5	4	3	2	1	0
RESERVED						OFFnPFO	CC_AQ
R-0000 00b						R/W-0b	R/W-0b

Table 7-14. CONTROL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-2	RESERVED	R	0000 00b	
1	OFFnPFO	R/W	0b	Power-fail shutdown bit: 0b = nPFO has no effect on PMIC state. 1b = All rails are shut down and PMIC enters OFF state when PFI comparator trips (nPFO is low).

Table 7-14. CONTROL Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
0	CC_AQ	R/W	0b	Coin Cell battery voltage acquisition start bit: 0b = No significance 1b = Triggers voltage acquisition. Bit is automatically reset to 0.

7.5.12 FLAG Register (subaddress = 0x07) [reset = 0x00]

FLAG is shown in [Figure 7-30](#) and described in [Table 7-15](#).

Return to [Table 7-6](#).

Figure 7-30. FLAG Register

7	6	5	4	3	2	1	0
GPO3_FLG	GPO2_FLG	GPO1_FLG	LDO1_FLG	DC4_FLG	DC3_FLG	DC2_FLG	DC1_FLG
R-0b	R-0b	R-0b	R-0b	R-0b	R-0b	R-0b	R-0b

Table 7-15. FLAG Register Field Descriptions

Bit	Field	Type	Reset	Description
7	GPO3_FLG	R	0b	GPO3 Flag bit: 0b = Device powered up from OFF or SUSPEND state and GPO3 was disabled while in SUSPEND. 1b = Device powered up from SUSPEND state and GPO3 was enabled while in SUSPEND.
5	GPO1_FLG	R	0b	GPO1 Flag bit: 0b = Device powered up from OFF or SUSPEND state and GPO1 was disabled while in SUSPEND. 1b = Device powered up from SUSPEND state and GPO1 was enabled while in SUSPEND.
4	LDO1_FLG	R	0b	LDO1 Flag bit: 0b = Device powered up from OFF or SUSPEND state and LDO1 was disabled while in SUSPEND. 1b = Device powered up from SUSPEND state and LDO1 was enabled while in SUSPEND.
3	DC4_FLG	R	0b	DCDC4 Flag bit: 0b = Device powered up from OFF or SUSPEND state and DCDC4 was disabled while in SUSPEND. 1b = Device powered up from SUSPEND state and DCDC4 was enabled while in SUSPEND.
2	DC3_FLG	R	0b	DCDC3 Flag bit: 0b = Device powered up from OFF or SUSPEND state and DCDC3 was disabled while in SUSPEND. 1b = Device powered up from SUSPEND state and DCDC3 was enabled while in SUSPEND.
1	DC2_FLG	R	0b	DCDC2 Flag bit: 0b = Device powered up from OFF or SUSPEND state and DCDC2 was disabled while in SUSPEND. 1b = Device powered up from SUSPEND state and DCDC2 was enabled while in SUSPEND.

Table 7-15. FLAG Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
0	DC1_FLG	R	0b	DCDC1 Flag bit: 0b = Device powered up from OFF or SUSPEND state and DCDC1 was disabled while in SUSPEND. 1b = Device powered up from SUSPEND state and GDCDC1PO3 was enabled while in SUSPEND.

7.5.13 PASSWORD Register (subaddress = 0x10) [reset = 0x00]

PASSWORD is shown in [Figure 7-31](#) and described in [Table 7-16](#).

Return to [Table 7-6](#).

Figure 7-31. PASSWORD Register

7	6	5	4	3	2	1	0
PWRD							
R/W-00h							

Table 7-16. PASSWORD Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	PWRD	R/W	00h	Register is used for accessing password protected registers (see Section 7.5.1 for details). Breaking the freshness seal (see Section 7.5.2 for details). Programming power-up default values . Read-back always yields 0x00.

7.5.14 ENABLE1 Register (subaddress = 0x11) [reset = 0x0F]

ENABLE1 is shown in and described in [Table 7-17](#).

Return to [Table 7-6](#).

Password protected.

Figure 7-32. ENABLE1 Register

7	6	5	4	3	2	1	0
RESERVED	DC6_EN	DC5_EN	DC4_EN	DC3_EN	DC2_EN	DC1_EN	
R-00b	R/W-0b	R/W-0b	R/W-1b	R/W-1b	R/W-1b	R/W-1b	R/W-1b

Table 7-17. ENABLE1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R	00b	
5	DC6_EN	R/W	0b	DCDC6 enable bit. DCDC6 can only be disabled if FSEAL = 0. See Section 7.5.2 for details. 0b = Disabled 1b = Enabled
4	DC5_EN	R/W	0b	DCDC5 enable bit. Note: At power-up and down this bit is automatically updated by the internal power sequencer. DCDC5 can only be disabled if FSEAL = 0. See Section 7.5.2 for details. 0b = Disabled 1b = Enabled
3	DC4_EN	R/W	1b	DCDC4 enable bit. Note: At power-up and down this bit is automatically updated by the internal power sequencer. 0b = Disabled 1b = Enabled
2	DC3_EN	R/W	1b	DCDC3 enable bit. Note: At power-up and down this bit is automatically updated by the internal power sequencer. 0b = Disabled 1b = Enabled
1	DC2_EN	R/W	1b	DCDC2 enable bit. Note: At power-up and down this bit is automatically updated by the internal power sequencer. 0b = Disabled 1b = Enabled
0	DC1_EN	R/W	1b	DCDC1 enable bit. Note: At power-up and down this bit is automatically updated by the internal power sequencer. 0b = Disabled 1b = Enabled

7.5.15 ENABLE2 Register (subaddress = 0x12) [reset = 0x13]

ENABLE2 is shown in and described in [Table 7-18](#).

Return to [Table 7-6](#).

Password protected.

Figure 7-33. ENABLE2 Register

7	6	5	4	3	2	1	0
RESERVED	GPIO3	GPIO2	GPIO1	LS3_EN	LS2_EN	LS1_EN	LDO1_EN
R-0b	R/W-0b	R/W-0b	R/W-1b	R/W-0b	R/W-0b	R/W-1b	R/W-1b

Table 7-18. ENABLE2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RESERVED	R	0b	
6	GPIO3	R/W	0b	General purpose output 3 / reset polarity. Note: If DC12_RST bit (register 0x14) is set to 1 this bit has no function. 0b = GPIO3 output is driven low. 1b = GPIO3 output is HiZ.
5	GPIO2	R/W	0b	General purpose output 2. Note: If IO_SEL bit (register 0x13) is set to 1 this bit has no function. 0b = GPIO2 output is driven low. 1b = GPIO2 output is HiZ.
4	GPIO1	R/W	1b	General purpose output 1. Note: If IO_SEL bit (register 0x13) is set to 1 this bit has no function. 0b = GPIO1 output is driven low. 1b = GPIO1 output is HiZ.
3	LS3_EN	R/W	0b	Load switch 3 (LS3) enable bit. 0b = Disabled 1b = Enabled
2	LS2_EN	R/W	0b	Load switch 2 (LS2) enable bit. 0b = Disabled 1b = Enabled
1	LS1_EN	R/W	1b	Load switch 1 (LS1) enable bit. 0b = Disabled 1b = Enabled Note: At power-up and down this bit is automatically updated by the internal power sequencer.
0	LDO1_EN	R/W	1b	LDO1 enable bit. 0b = Disabled 1b = Enabled Note: At power-up and down this bit is automatically updated by the internal power sequencer.

7.5.16 CONFIG1 Register (subaddress = 0x13) [reset = 0x00]

CONFIG1 is shown in [Figure 7-34](#) and described in [Table 7-19](#).

Return to [Table 7-6](#).

Password protected.

Figure 7-34. CONFIG1 Register

7	6	5	4	3	2	1	0
TRST	GPO2_BUF	IO1_SEL	PGDLY	STRICT	UVLO		
R/W-0b	R/W-0b	R/W-0b	R/W-00b	R/W-0b	R/W-00b		

Table 7-19. CONFIG1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	TRST	R/W, E2	0b	Push-button reset time constant: 0b = 8 s 1b = 15 s

Table 7-19. CONFIG1 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
6	GPO2_BUF	R/W, E2	0b	GPO2 output buffer configuration: 0b = GPO2 buffer is configured as open-drain. 1b = GPO2 buffer is configured as push-pull (high-level is driven to IN_LS1).
5	IO1_SEL	R/W, E2	0b	GPIO1 / GPO2 configuration bit. See Section 7.3.1.11 for details. 0b = GPIO1 is configured as general-purpose, open-drain output. GPO2 is independent output. 1b = GPIO1 is configured as input, controlling GPO2. Intended for DDR3 reset signal control.
4-3	PGDLY	R/W, E2	01b	Power-Good delay. Note: Power-good delay applies to rising-edge only (power-up), not falling edge (power-down or fault). 00b = 10 ms 01b = 20 ms 10b = 50 ms 11b = 150 ms
2	STRICT	R/W	0b	Supply Voltage Supervisor Sensitivity selection. See Section 6.5 for details. 0b = Power-good threshold (VOUT falling) has wider limits. Over-voltage is not monitored. 1b = Power-good threshold (VOUT falling) has tight limits. Over-voltage is monitored.
1-0	UVLO	R/W, E2	00b	UVLO setting 00b = 2.75 V 01b = 2.95 V 10b = 3.25 V 11b = 3.35 V

7.5.17 CONFIG2 Register (subaddress = 0x14) [TPS65218 reset = 0xC0; TPS65218B101 reset = 0x80; TPS6521855 reset = 0x40]

CONFIG2 is shown in [Figure 7-35](#) and described in [Table 7-20](#).

Return to [Table 7-6](#).

Password protected.

Figure 7-35. CONFIG2 Register

7	6	5	4	3	2	1	0
DC12_RST	UVLOHYS	RESERVED		LS3ILIM		LS2ILIM	
R/W-0b	R/W-1b	R-00b		R/W-00b		R/W-00b	

Table 7-20. CONFIG2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	DC12_RST	R/W, E2	0b	DCDC1 and DCDC2 reset-pin enable: 0b = GPIO3 is configured as general-purpose output. 1b = GPIO3 is configured as warm-reset input to DCDC1 and DCDC2.
6	UVLOHYS	R/W, E2	1b	UVLO hysteresis: 0b = 200 mV 1b = 400 mV
5-4	RESERVED	R	00b	

Table 7-20. CONFIG2 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
3-2	LS3ILIM	R/W	00b	Load switch 3 (LS3) current limit selection: 00b = 100 mA, (MIN = 98 mA) 01b = 200 mA, (MIN = 194 mA) 10b = 500 mA, (MIN = 475 mA) 11b = 1000 mA, (MIN = 900 mA) See the LS3 current limit specification in for more details.
1-0	LS2ILIM	R/W	00b	Load switch 2 (LS2) current limit selection: 00b = 100 mA, (MIN = 94 mA) 01b = 200 mA, (MIN = 188 mA) 10b = 500 mA, (MIN = 465 mA) 11b = 1000 mA, (MIN = 922 mA) See the LS2 current limit specification in Section 6.5 for more details.

7.5.18 CONFIG3 Register (subaddress = 0x15) [reset = 0x0]

CONFIG3 is shown in [Figure 7-36](#) and described in [Table 7-21](#).

Return to [Table 7-6](#).

Password protected.

Figure 7-36. CONFIG3 Register

7	6	5	4	3	2	1	0
RESERVED		LS3nPFO	LS2nPFO	LS1nPFO	LS3DCHRG	LS2DCHRG	LS1DCHRG
R-00b		R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b

Table 7-21. CONFIG3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R	00b	
5	LS3nPFO	R/W	0b	Load switch 3 power-fail disable bit: 0b = Load switch status is not affected by power-fail comparator. 1b = Load switch is disabled if power-fail comparator trips (nPFO is low).
4	LS2nPFO	R/W	0b	Load switch 2 power-fail disable bit: 0b = Load switch status is not affected by power-fail comparator. 1b = Load switch is disabled if power-fail comparator trips (nPFO is low).
3	LS1nPFO	R/W	0b	Load switch 1 power-fail disable bit: 0b = Load switch status is not affected by power-fail comparator. 1b = Load switch is disabled if power-fail comparator trips (nPFO is low).
2	LS3DCHRG	R/W	0b	Load switch 3 discharge enable bit: 0b = Active discharge is disabled. 1b = Active discharge is enabled (load switch output is actively discharged when switch is OFF).
1	LS2DCHRG	R/W	0b	Load switch 2 discharge enable bit: 0b = Active discharge is disabled. 1b = Active discharge is enabled (load switch output is actively discharged when switch is OFF).
0	LS1DCHRG	R/W	0b	Load switch 1 discharge enable bit: 0b = Active discharge is disabled. 1b = Active discharge is enabled (load switch output is actively discharged when switch is OFF).

7.5.19 DCDC1 Register (offset = 0x16) [reset = 0x99]

DCDC1 is shown in [Figure 7-37](#) and described in [Table 7-22](#).

Return to [Table 7-6](#).

Note 1: This register is password protected. For more information, see [Section 7.5.1](#).

Note 2: A 5-ms blanking time of the over-voltage and under-voltage monitoring occurs when a write is performed on the DCDC1 register.

Note 3: To change the output voltage of DCDC1, the GO bit or the GODSBL bit must be set to 1b in register 0x1A.

Figure 7-37. DCDC1 Register

7	6	5	4	3	2	1	0
PFM	RESERVED	DCDC1					
R/W-1b	R-0b	R/W-19h					

Table 7-22. DCDC1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	PFM	R/W	1b	Pulse Frequency Modulation (PFM, also known as pulse-skip-mode) enable. PFM mode improves light-load efficiency. Actual PFM mode operation depends on load condition. 0b = Disabled (forced PWM) 1b = Enabled
6	RESERVED	R	0b	

Table 7-22. DCDC1 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
5-0	DCDC1	R/W, E2	19h	DCDC1 output voltage setting: 0h = 0.850 1h = 0.860 2h = 0.870 3h = 0.880 4h = 0.890 5h = 0.900 6h = 0.910 7h = 0.920 8h = 0.930 9h = 0.940 Ah = 0.950 Bh = 0.960 Ch = 0.970 Dh = 0.980 Eh = 0.990 Fh = 1.000 10h = 1.010 11h = 1.020 12h = 1.030 13h = 1.040 14h = 1.050 15h = 1.060 16h = 1.070 17h = 1.080 18h = 1.090 19h = 1.100 1Ah = 1.110 1Bh = 1.120 1Ch = 1.130 1Dh = 1.140 1Eh = 1.150 1Fh = 1.160 20h = 1.170 21h = 1.180 22h = 1.190 23h = 1.200

Table 7-22. DCDC1 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
				24h = 1.210
				25h = 1.220
				26h = 1.230
				27h = 1.240
				28h = 1.250
				29h = 1.260
				2Ah = 1.270
				2Bh = 1.280
				2Ch = 1.290
				2Dh = 1.300
				2Eh = 1.310
				2Fh = 1.320
				30h = 1.330
				31h = 1.340
				32h = 1.350
				33h = 1.375
				34h = 1.400
				35h = 1.425
				36h = 1.450
				37h = 1.475
				38h = 1.500
				39h = 1.525
				3Ah = 1.550
				3Bh = 1.575
				3Ch = 1.600
				3Dh = 1.625
				3Eh = 1.650
				3Fh = 1.675

7.5.20 DCDC2 Register (subaddress = 0x17) [reset = 0x8F]

DCDC2 is shown in [Figure 7-38](#) and described in [Table 7-23](#).

Return to [Table 7-6](#).

Note 1: This register is password protected. For more information, see [Section 7.5.1](#).

Note 2: A 5-ms blanking time of the over-voltage and under-voltage monitoring occurs when a write is performed on the DCDC2 register.

Note 3: To change the output voltage of DCDC2, the GO bit or the GODSBL bit must be set to 1b in register 0x1A.

Figure 7-38. DCDC2 Register

7	6	5	4	3	2	1	0
PFM	RESERVED						DCDC2
R/W-1b	R-0b						R/W-Fh

Table 7-23. DCDC2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	PFM	R/W	1b	Pulse frequency modulation (PFM, also known as pulse-skip-mode) enable. PFM mode improves light-load efficiency. Actual PFM mode operation depends on load condition. 0b = Disabled (forced PWM) 1b = Enabled

Table 7-23. DCDC2 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
6	RESERVED	R	0b	
5-0	DCDC2	R/W, E2	Fh	DCDC2 output voltage setting: 0h = 0.850 1h = 0.860 2h = 0.870 3h = 0.880 4h = 0.890 5h = 0.900 6h = 0.910 7h = 0.920 8h = 0.930 9h = 0.940 Ah = 0.950 Bh = 0.960 Ch = 0.970 Dh = 0.980 Eh = 0.990 Fh = 1.000 10h = 1.010 11h = 1.020 12h = 1.030 13h = 1.040 14h = 1.050 15h = 1.060 16h = 1.070 17h = 1.080 18h = 1.090 19h = 1.100 1Ah = 1.110 1Bh = 1.120 1Ch = 1.130 1Dh = 1.140 1Eh = 1.150 1Fh = 1.160 20h = 1.170 21h = 1.180 22h = 1.190 23h = 1.200

Table 7-23. DCDC2 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
				24h = 1.210
				25h = 1.220
				26h = 1.230
				27h = 1.240
				28h = 1.250
				29h = 1.260
				2Ah = 1.270
				2Bh = 1.280
				2Ch = 1.290
				2Dh = 1.300
				2Eh = 1.310
				2Fh = 1.320
				30h = 1.330
				31h = 1.340
				32h = 1.350
				33h = 1.375
				34h = 1.400
				35h = 1.425
				36h = 1.450
				37h = 1.475
				38h = 1.500
				39h = 1.525
				3Ah = 1.550
				3Bh = 1.575
				3Ch = 1.600
				3Dh = 1.625
				3Eh = 1.650
				3Fh = 1.675

7.5.21 DCDC3 Register (subaddress = 0x18) [reset = 0x1Fh]

DCDC3 is shown in [Figure 7-39](#) and described in [Table 7-24](#).

Return to [Table 7-6](#).

Note 1: This register is password protected. For more information, see [Section 7.5.1](#).

Note 2: A 5-ms blanking time of the over-voltage and under-voltage monitoring occurs when a write is performed on the DCDC3 register.

Note

Power-up default may differ depending on RSEL value. See [Section 7.3.1.10](#) for details.

Figure 7-39. DCDC3 Register

7	6	5	4	3	2	1	0
PFM	RESERVED						DCDC3
R/W-1b	R-0b						R/W-1Fh

Table 7-24. DCDC3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	PFM	R/W	1b	Pulse Frequency Modulation (PFM, also known as pulse-skip-mode) enable. PFM mode improves light-load efficiency. Actual PFM mode operation depends on load condition. 0b = Disabled (forced PWM) 1b = Enabled
6	RESERVED	R	0b	
5-0	DCDC3	R/W, E2	1Fh	DCDC3 output voltage setting: 0h = 0.900 1h = 0.925 2h = 0.950 3h = 0.975 4h = 1.000 5h = 1.025 6h = 1.050 7h = 1.075 8h = 1.100 9h = 1.125 Ah = 1.150 Bh = 1.175 Ch = 1.200 Dh = 1.225 Eh = 1.250 Fh = 1.275 10h = 1.300 11h = 1.325 12h = 1.350 13h = 1.375 14h = 1.400 15h = 1.425 16h = 1.450 17h = 1.475 18h = 1.500 19h = 1.525 1Ah = 1.550 1Bh = 1.600 1Ch = 1.650 1Dh = 1.700 1Eh = 1.750 1Fh = 1.800 20h = 1.850 21h = 1.900 22h = 1.950 23h = 2.000

Table 7-24. DCDC3 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
				24h = 2.050
				25h = 2.100
				26h = 2.150
				27h = 2.200
				28h = 2.250
				29h = 2.300
				2Ah = 2.350
				2Bh = 2.400
				2Ch = 2.450
				2Dh = 2.500
				2Eh = 2.550
				2Fh = 2.600
				30h = 2.650
				31h = 2.700
				32h = 2.750
				33h = 2.800
				34h = 2.850
				35h = 2.900
				36h = 2.950
				37h = 3.000
				38h = 3.050
				39h = 3.100
				3Ah = 3.150
				3Bh = 3.200
				3Ch = 3.250
				3Dh = 3.300
				3Eh = 3.350
				3Fh = 3.400

7.5.22 DCDC4 Register (subaddress = 0x19) [reset = 0xA2]

DCDC4 is shown in [Figure 7-40](#) and described in [Table 7-25](#).

Return to [Table 7-6](#).

Note 1: This register is password protected. For more information, see [Section 7.5.1](#).

Note 2: A 5-ms blanking time of the over-voltage and under-voltage monitoring occurs when a write is performed on the DCDC4 register.

Note

Power-up default may differ depending on RSEL value. See [Section 7.3.1.10](#) for details. The Reserved setting should not be selected and the output voltage settings should not be modified while the converter is operating.

Figure 7-40. DCDC4 Register

7	6	5	4	3	2	1	0
PFM	RESERVED						DCDC4
R/W-1b	R-0b						R/W-22h

Table 7-25. DCDC4 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	PFM	R/W	1b	Pulse Frequency Modulation (PFM, also known as pulse-skip-mode) enable. PFM mode improves light-load efficiency. Actual PFM mode operation depends on load condition. 0b = Disabled (forced PWM) 1b = Enabled
6	RESERVED	R	0b	
5-0	DCDC4	R/W, E2	22h	DCDC4 output voltage setting: 0h = 1.175 1h = 1.200 2h = 1.225 3h = 1.250 4h = 1.275 5h = 1.300 6h = 1.325 7h = 1.350 8h = 1.375 9h = 1.400 Ah = 1.425 Bh = 1.450 Ch = 1.475 Dh = 1.500 Eh = 1.525 Fh = 1.550 10h = 1.600 11h = 1.650 12h = 1.700 13h = 1.750 14h = 1.800 15h = 1.850 16h = 1.900 17h = 1.950 18h = 2.000 19h = 2.050 1Ah = 2.100 1Bh = 2.150 1Ch = 2.200 1Dh = 2.250 1Eh = 2.300 1Fh = 2.3500 20h = 2.400 21h = 2.450 22h = 2.500 23h = 2.550

Table 7-25. DCDC4 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
				24h = 2.600
				25h = 2.650
				26h = 2.700
				27h = 2.750
				28h = 2.800
				29h = 2.850
				2Ah = 2.900
				2Bh = 2.950
				2Ch = 3.000
				2Dh = 3.050
				2Eh = 3.100
				2Fh = 3.150
				30h = 3.200
				31h = 3.250
				32h = 3.300
				33h = 3.350
				34h = 3.400
				35h = reserved
				36h = reserved
				37h = reserved
				38h = reserved
				39h = reserved
				3Ah = reserved
				3Bh = reserved
				3Ch = reserved
				3Dh = reserved
				3Eh = reserved
				3Fh = reserved

7.5.23 SLEW Register (subaddress = 0x1A) [reset = 0x06]

SLEW is shown in [Figure 7-41](#) and described in [Table 7-26](#).

Return to [Table 7-6](#).

Note

Slew-rate control applies to DCDC1 and DCDC2 only. If changing from a higher voltage to lower voltage while STRICT = 1 and converters are in a no load state, PFM bit for DCDC1 and DCDC2 must be set to 0.

Figure 7-41. SLEW Register

7	6	5	4	3	2	1	0
GO	GODSBL	RESERVED			SLEW		
R/W-0b	R/W-0b	R-000b			R/W-6h		

Table 7-26. SLEW Register Field Descriptions

Bit	Field	Type	Reset	Description
7	GO	R/W	0b	Go bit. Note: Bit is automatically reset at the end of the voltage transition. 0b = No change 1b = Initiates the transition from present state to the output voltage setting currently stored in DCDC1 and DCDC2 register. SLEW setting does apply.
6	GODSBL	R/W	0b	Go disable bit 0b = Enabled 1b = Disabled; DCDC1 and DCDC2 output voltage changes whenever set-point is updated in DCDC1 and DCDC2 register without having to write to the GO bit. SLEW setting does apply.
5-3	RESERVED	R	000b	
2-0	SLEW	R/W	6h	Output slew rate setting: 0h = 160 μ s/step (0.0625 mV/ μ s at 10 mV per step) 1h = 80 μ s/step (0.125 mV/ μ s at 10 mV per step) 2h = 40 μ s/step (0.250 mV/ μ s at 10 mV per step) 3h = 20 μ s/step (0.500 mV/ μ s at 10 mV per step) 4h = 10 μ s/step (1.0 mV/ μ s at 10 mV per step) 5h = 5 μ s/step (2.0 mV/ μ s at 10 mV per step) 6h = 2.5 μ s/step (4.0 mV/ μ s at 10 mV per step) 7h = Immediate; slew rate is only limited by control loop response time. Note: The actual slew rate depends on the voltage step per code. Refer to DCDCx registers for details.

7.5.24 LDO1 Register (subaddress = 0x1B) [reset = 0x3D]

LDO1 is shown in [Figure 7-42](#) and described in [Table 7-27](#).

Return to [Table 7-6](#).

Note 1: This register is password protected. For more information, see [Section 7.5.1](#).

Note 2: A 5-ms blanking time of the over-voltage and under-voltage monitoring occurs when a write is performed on the LDO1 register.

Figure 7-42. LDO1 Register

7	6	5	4	3	2	1	0
RESERVED			LDO1				
R-00b			R/W-3Dh				

Table 7-27. LDO1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R	00b	

Table 7-27. LDO1 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
5-0	LDO1	R/W, E2	3Dh	LDO1 output voltage setting: 0h = 0.900 1h = 0.925 2h = 0.950 3h = 0.975 4h = 1.000 5h = 1.025 6h = 1.050 7h = 1.075 8h = 1.100 9h = 1.125 Ah = 1.150 Bh = 1.175 Ch = 1.200 Dh = 1.225 Eh = 1.250 Fh = 1.275 10h = 1.300 11h = 1.325 12h = 1.350 13h = 1.375 14h = 1.400 15h = 1.425 16h = 1.450 17h = 1.475 18h = 1.500 19h = 1.525

Table 7-27. LDO1 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
				1Ah = 1.550
				1Bh = 1.600
				1Ch = 1.650
				1Dh = 1.700
				1Eh = 1.750
				1Fh = 1.800
				20h = 1.850
				21h = 1.900
				22h = 1.950
				23h = 2.000
				24h = 2.050
				25h = 2.100
				26h = 2.150
				27h = 2.200
				28h = 2.250
				29h = 2.300
				2Ah = 2.350
				2Bh = 2.400
				2Ch = 2.450
				2Dh = 2.500
				2Eh = 2.550
				2Fh = 2.600
				30h = 2.650
				31h = 2.700
				32h = 2.750
				33h = 2.800
				34h = 2.850
				35h = 2.900
				36h = 2.950
				37h = 3.000
				38h = 3.050
				39h = 3.100
				3Ah = 3.150
				3Bh = 3.200
				3Ch = 3.250
				3Dh = 3.300
				3Eh = 3.350
				3Fh = 3.400

7.5.25 SEQ1 Register (subaddress = 0x20) [reset = 0x00]

SEQ1 is shown in [Figure 7-43](#) and described in [Table 7-28](#).

Return to [Table 7-6](#).

Password protected.

Figure 7-43. SEQ1 Register

7	6	5	4	3	2	1	0
DLY8	DLY7	DLY6	DLY5	DLY4	DLY3	DLY2	DLY1
R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b	R/W-0b

Table 7-28. SEQ1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	DLY8	R/W, E2	0b	Delay8 (occurs after Strobe 8 and before Strobe 9.) 0b = 2 ms 1b = 5 ms
6	DLY7	R/W, E2	0b	Delay7 (occurs after Strobe 7 and before Strobe 8.) 0b = 2 ms 1b = 5 ms
5	DLY6	R/W, E2	0b	Delay6 (occurs after Strobe 6 and before Strobe 7.) 0b = 2 ms 1b = 5 ms
4	DLY5	R/W, E2	0b	Delay5 (occurs after Strobe 5 and before Strobe 6.) 0b = 2 ms 1b = 5 ms
3	DLY4	R/W, E2	0b	Delay4 (occurs after Strobe 4 and before Strobe 5.) 0b = 2 ms 1b = 5 ms
2	DLY3	R/W, E2	0b	Delay3 (occurs after Strobe 3 and before Strobe 4.) 0b = 2 ms 1b = 5 ms
1	DLY2	R/W, E2	0b	Delay2 (occurs after Strobe 2 and before Strobe 3.) 0b = 2 ms 1b = 5 ms
0	DLY1	R/W, E2	0b	Delay1 (occurs after Strobe 1 and before Strobe 2.) 0b = 2 ms 1b = 5 ms

7.5.26 SEQ2 Register (subaddress = 0x21) [reset = 0x00]

SEQ2 is shown in [Figure 7-44](#) and described in [Table 7-29](#).

Return to [Table 7-6](#).

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Figure 7-44. SEQ2 Register

7	6	5	4	3	2	1	0
DLYFCTR	RESERVED						DLY9
R/W -0b	R-000 000b						R/W -0b

Table 7-29. SEQ2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	DLYFCTR	R/W, E2	0b	Power-down delay factor: 0b = 1x 1b = 10x (delay times are multiplied by 10x during power-down.) Note: DLYFCTR has no effect on power-up timing.
6-1	RESERVED	R	000 000b	
0	DLY9	R/W, E2	0b	Delay9 (occurs after Strobe 9 and before Strobe 10.) 0b = 2 ms 1b = 5 ms

7.5.27 SEQ3 Register (subaddress = 0x22)[reset = 0x56]

SEQ3 is shown in [Figure 7-45](#) and described in [Table 7-30](#).

Return to [Table 7-6](#).

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Figure 7-45. SEQ3 Register

7	6	5	4	3	2	1	0
DC2_SEQ				DC1_SEQ			
R/W-5h				R/W-6h			

Table 7-30. SEQ3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	DC2_SEQ	R/W, E2	5h	DCDC2 enable STROBE: 0h = Rail is not controlled by sequencer. 1h = Rail is not controlled by sequencer. 2h = Rail is not controlled by sequencer. 3h = Enable at STROBE 3. 4h = Enable at STROBE 4. 5h = Enable at STROBE 5. 6h = Enable at STROBE 6. 7h = Enable at STROBE 7. 8h = Enable at STROBE 8. 9h = Enable at STROBE 9. Ah = Enable at STROBE 10. Bh = Rail is not controlled by sequencer. Ch = Rail is not controlled by sequencer. Dh = Rail is not controlled by sequencer. Eh = Rail is not controlled by sequencer. Fh = Rail is not controlled by sequencer.
3-0	DC1_SEQ	R/W, E2	6h	DCDC1 enable STROBE: 0h = Rail is not controlled by sequencer. 1h = Rail is not controlled by sequencer. 2h = Rail is not controlled by sequencer. 3h = Enable at STROBE 3. 4h = Enable at STROBE 4. 5h = Enable at STROBE 5. 6h = Enable at STROBE 6. 7h = Enable at STROBE 7. 8h = Enable at STROBE 8. 9h = Enable at STROBE 9. Ah = Enable at STROBE 10. Bh = Rail is not controlled by sequencer. Ch = Rail is not controlled by sequencer. Dh = Rail is not controlled by sequencer. Eh = Rail is not controlled by sequencer. Fh = Rail is not controlled by sequencer.

7.5.28 SEQ4 Register (subaddress = 0x23) [reset = 0x45]

SEQ4 is shown in [Figure 7-46](#) and described in [Table 7-31](#).

Return to [Table 7-6](#).

Password protected.

Figure 7-46. SEQ4 Register

7	6	5	4	3	2	1	0
DC4_SEQ				DC3_SEQ			
R/W-4h				R/W-5h			

Table 7-31. SEQ4 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	DC4_SEQ	R/W, E2	4h	DCDC4 enable STROBE: 0h = Rail is not controlled by sequencer. 1h = Rail is not controlled by sequencer. 2h = Rail is not controlled by sequencer. 3h = Enable at STROBE 3. 4h = Enable at STROBE 4. 5h = Enable at STROBE 5. 6h = Enable at STROBE 6. 7h = Enable at STROBE 7. 8h = Enable at STROBE 8. 9h = Enable at STROBE 9. Ah = Enable at STROBE 10. Bh = Rail is not controlled by sequencer. Ch = Rail is not controlled by sequencer. Dh = Rail is not controlled by sequencer. Eh = Rail is not controlled by sequencer. Fh = Rail is not controlled by sequencer.
3-0	DC3_SEQ	R/W, E2	5h	DCDC3 enable STROBE: 0h = Rail is not controlled by sequencer. 1h = Rail is not controlled by sequencer. 2h = Rail is not controlled by sequencer. 3h = Enable at STROBE 3. 4h = Enable at STROBE 4. 5h = Enable at STROBE 5. 6h = Enable at STROBE 6. 7h = Enable at STROBE 7. 8h = Enable at STROBE 8. 9h = Enable at STROBE 9. Ah = Enable at STROBE 10. Bh = Rail is not controlled by sequencer. Ch = Rail is not controlled by sequencer. Dh = Rail is not controlled by sequencer. Eh = Rail is not controlled by sequencer. Fh = Rail is not controlled by sequencer.

7.5.29 SEQ5 Register (subaddress = 0x24) [reset = 0x00]

SEQ5 is shown in [Figure 7-47](#) and described in [Table 7-32](#).

Return to [Table 7-6](#).

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Figure 7-47. SEQ5 Register

7	6	5	4	3	2	1	0
RESERVED		DC6_SEQ		RESERVED		DC5_SEQ	

Figure 7-47. SEQ5 Register (continued)

R-0h	R/W-0h	R-0h	R/W-0h
------	--------	------	--------

Table 7-32. SEQ5 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R	0h	
5-4	DC6_SEQ	R/W	0h	DCDC6 enable STROBE. Note: STROBE 1 and STROBE 2 are executed only if FSEAL = 0. DCDC5 and 6 cannot be disabled by sequencer once freshness seal is broken. 0h = Rail is not controlled by sequencer. 1h = Enable at STROBE 1. 2h = Enable at STROBE 2. 3h = Rail is not controlled by sequencer.
3-2	RESERVED	R	0h	
1-0	DC5_SEQ	R/W, E2	0h	DCDC5 enable STROBE. Note: STROBE 1 and STROBE 2 are executed only if FSEAL = 0. DCDC5 and 6 cannot be disabled by sequencer once freshness seal is broken. 0h = Rail is not controlled by sequencer. 1h = Enable at STROBE 1. 2h = Enable at STROBE 2. 3h = Rail is not controlled by sequencer.

7.5.30 SEQ6 Register (subaddress = 0x25) [reset = 0x73]

SEQ6 is shown in [Figure 7-48](#) and described in [Table 7-33](#).

Return to [Table 7-6](#).

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Figure 7-48. SEQ6 Register

7	6	5	4	3	2	1	0
LS1_SEQ				LDO1_SEQ			
R/W-7h				R/W-3h			

Table 7-33. SEQ6 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	LS1_SEQ	R/W, E2	7h	LS1 enable STROBE: 0h = Rail is not controlled by sequencer. 1h = Rail is not controlled by sequencer. 2h = Rail is not controlled by sequencer. 3h = Enable at STROBE 3. 4h = Enable at STROBE 4. 5h = Enable at STROBE 5. 6h = Enable at STROBE 6. 7h = Enable at STROBE 7. 8h = Enable at STROBE 8. 9h = Enable at STROBE 9. Ah = Enable at STROBE 10. Bh = Rail is not controlled by sequencer. Ch = Rail is not controlled by sequencer. Dh = Rail is not controlled by sequencer. Eh = Rail is not controlled by sequencer. Fh = Rail is not controlled by sequencer.

Table 7-33. SEQ6 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
3-0	LDO1_SEQ	R/W, E2	3h	LDO1 enable STROBE: 0h = Rail is not controlled by sequencer. 1h = Rail is not controlled by sequencer. 2h = Rail is not controlled by sequencer. 3h = Enable at STROBE 3. 4h = Enable at STROBE 4. 5h = Enable at STROBE 5. 6h = Enable at STROBE 6. 7h = Enable at STROBE 7. 8h = Enable at STROBE 8. 9h = Enable at STROBE 9. Ah = Enable at STROBE 10. Bh = Rail is not controlled by sequencer. Ch = Rail is not controlled by sequencer. Dh = Rail is not controlled by sequencer. Eh = Rail is not controlled by sequencer. Fh = Rail is not controlled by sequencer.

7.5.31 SEQ7 Register (subaddress = 0x26) [reset = 0x03]

SEQ7 is shown in [Figure 7-49](#) and described in [Table 7-34](#).

Return to [Table 7-6](#).

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Figure 7-49. SEQ7 Register

7	6	5	4	3	2	1	0
GPO3_SEQ				GPO1_SEQ			
R/W-0h				R/W-3h			

Table 7-34. SEQ7 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	GPO3_SEQ	R/W, E2	0h	GPO3 enable STROBE: 0h = Rail is not controlled by sequencer. 1h = Rail is not controlled by sequencer. 2h = Rail is not controlled by sequencer. 3h = Enable at STROBE 3. 4h = Enable at STROBE 4. 5h = Enable at STROBE 5. 6h = Enable at STROBE 6. 7h = Enable at STROBE 7. 8h = Enable at STROBE 8. 9h = Enable at STROBE 9. Ah = Enable at STROBE 10. Bh = Rail is not controlled by sequencer. Ch = Rail is not controlled by sequencer. Dh = Rail is not controlled by sequencer. Eh = Rail is not controlled by sequencer. Fh = Rail is not controlled by sequencer.

Table 7-34. SEQ7 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
3-0	GPO1_SEQ	R/W, E2	3h	GPO1 enable STROBE: 0h = Rail is not controlled by sequencer. 1h = Rail is not controlled by sequencer. 2h = Rail is not controlled by sequencer. 3h = Enable at STROBE 3. 4h = Enable at STROBE 4. 5h = Enable at STROBE 5. 6h = Enable at STROBE 6. 7h = Enable at STROBE 7. 8h = Enable at STROBE 8. 9h = Enable at STROBE 9. Ah = Enable at STROBE 10. Bh = Rail is not controlled by sequencer. Ch = Rail is not controlled by sequencer. Dh = Rail is not controlled by sequencer. Eh = Rail is not controlled by sequencer. Fh = Rail is not controlled by sequencer.

8 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

The TPS6521855 is designed to pair with AM64x Arm®Cortex®-A53 Processors. The typical application in [Section 8.2](#) is based on and uses terminology consistent with the Sitara™ family of processors.

8.1.1 Applications Without Backup Battery

In applications that require always-on supplies but no battery backup, the CC input to the power path must be connected to ground.

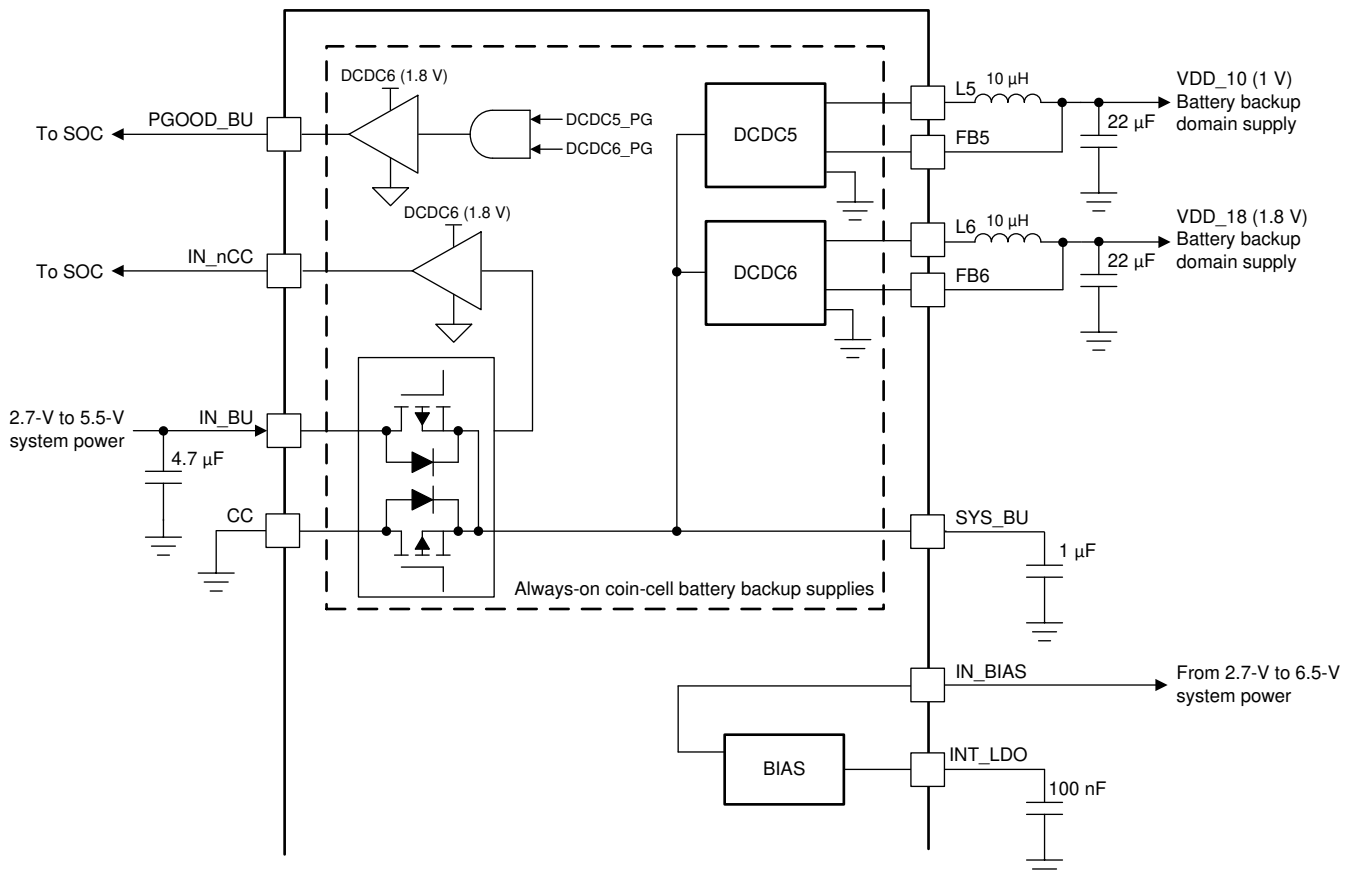


Figure 8-1. CC Input to Power Path

Note

In applications without backup battery, CC input must be tied to ground.

8.1.2 Applications Without Battery Backup Supplies

In applications that do not require always-on supplies, both inputs and the output of the power-path can simply be grounded. All pins related to DCDC5 and DCDC6 are also tied to ground, and PGOOD_BU and IN_nCC are kept floating. With the backup supplies completely disabled, the FSEAL bit in the STATUS register is undefined and should be ignored.

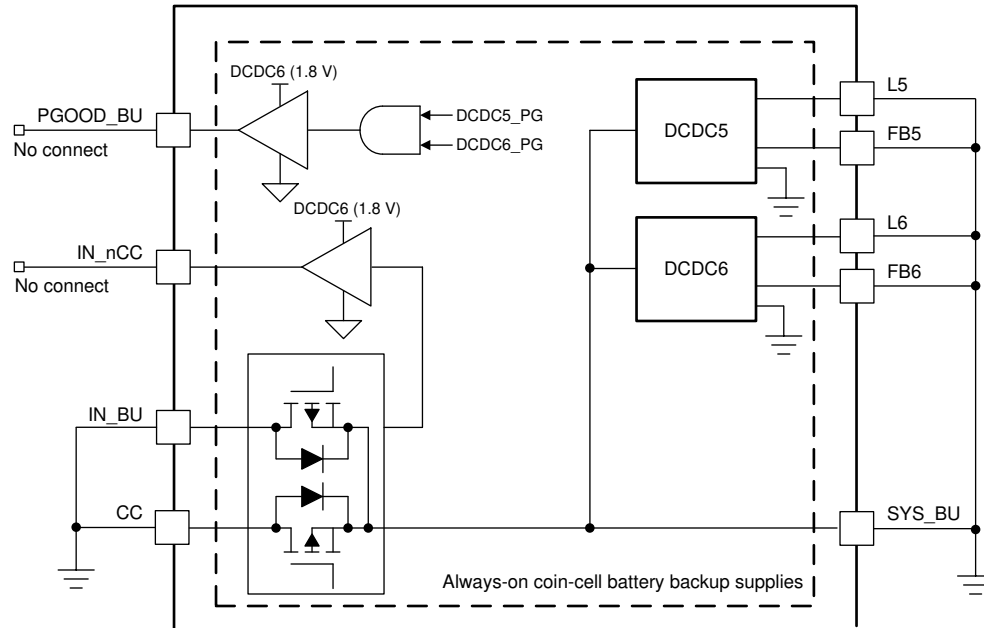


Figure 8-2. DCDC5 and DCDC6 Pins

Note

In applications that do not require always-on supplies, PGOOD_BU and IN_nCC can be kept floating. All other pins are tied to ground.

8.2 Typical Application

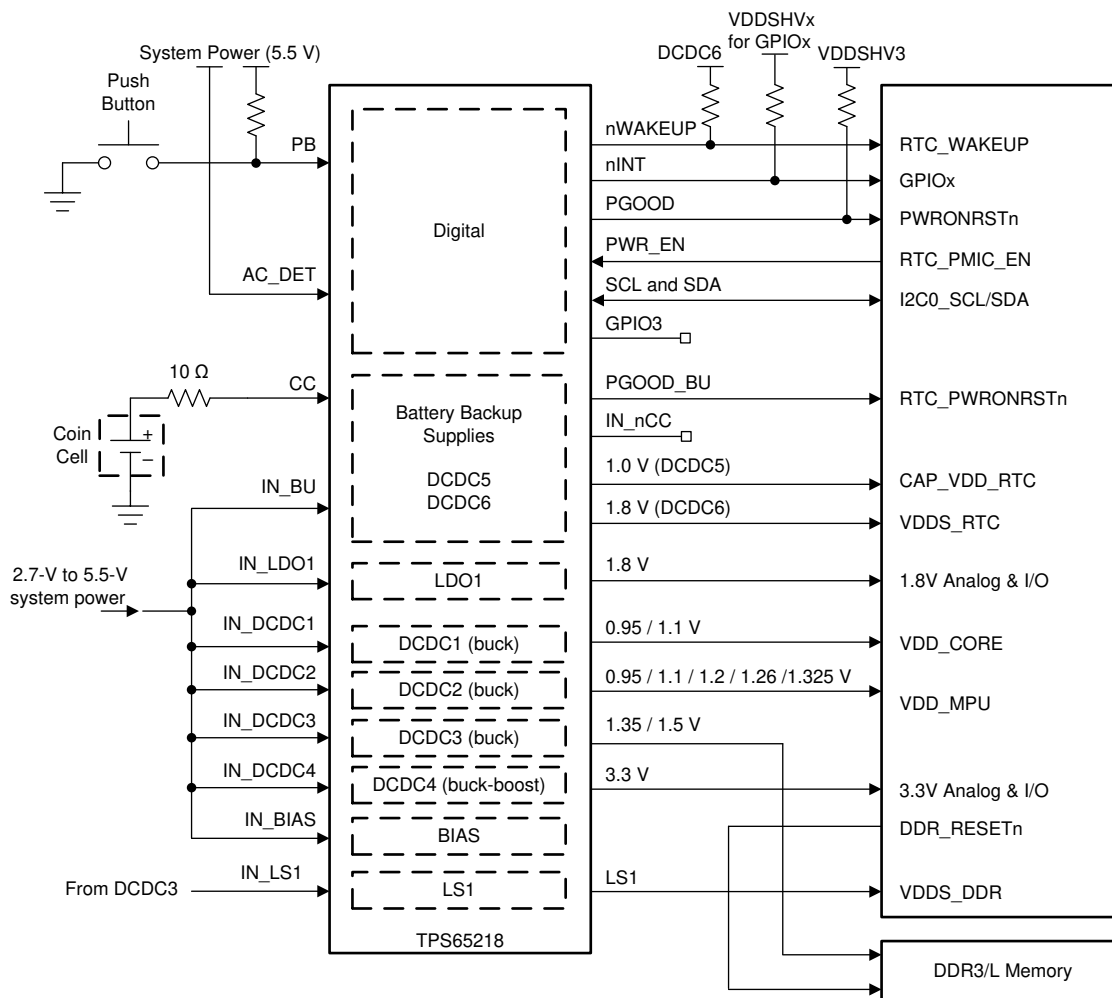


Figure 8-3. Typical Application Schematic

8.2.1 Design Requirements

Table 8-1 lists the design requirements.

Table 8-1. Design Parameters for TPS65218D0 (1)

	VOLTAGE	SEQUENCE
DCDC1	1.1 V	8
DCDC2	1.1 V	9
DCDC3	1.2 V	5
DCDC4	3.3 V	7
LDO1	1.8 V	3

(1) Default output voltages shown for TPS65218D0. For other TPS65218xx variants, refer to DCDC1-4 and LDO1 registers in [Section 7.5.4](#).

8.2.2 Detailed Design Procedure

8.2.2.1 Output Filter Design

The step down converters (DCDC1, DCDC2, and DCDC3) on TPS6521855 are designed to operate with effective inductance values in the range of 1 to 2.2 μH and with effective output capacitance in the range of 10 to 100 μF . The internal compensation is optimized to operate with an output filter of $L = 1.5 \mu\text{H}$ and $C_{\text{OUT}} = 10 \mu\text{F}$.

The buck boost converter (DCDC4) on TPS6521855 is designed to operate with effective inductance values in the range of 1.2 to 2.2 μH . The internal compensation is optimized to operate with an output filter of $L = 1.5 \mu\text{H}$ and $C_{\text{OUT}} = 47 \mu\text{F}$.

The two battery backup converters (DCDC5 and DCDC6) are designed to operate with effective inductance values in the range of 4.7 to 22 μH . The internal compensation is optimized with an output filter of $L = 10 \mu\text{H}$ and $C_{\text{OUT}} = 20 \mu\text{F}$.

Larger or smaller inductor/capacitance values can be used to optimize performance of the device for specific operation conditions.

8.2.2.2 Inductor Selection for Buck Converters

The inductor value affects its peak to peak ripple current, the PWM to PFM transition point, the output voltage ripple, and the efficiency. The selected inductor must be rated for its DC resistance and saturation current. The inductor ripple current (ΔI_L) decreases with higher inductance and increases with higher V_{IN} or V_{OUT} . [Equation 1](#) calculates the maximum inductor current ripple under static load conditions. The saturation current of the inductor should be rated higher than the maximum inductor current as calculated with [Equation 2](#). This is recommended as during heavy load transient the inductor current will rise above the calculated value.

$$\Delta I_L = V_{\text{OUT}} \times \frac{1 - \frac{V_{\text{OUT}}}{V_{\text{IN}}}}{L \times f} \quad (1)$$

$$I_{L\text{max}} = I_{\text{OUTmax}} + \frac{\Delta I_L}{2} \quad (2)$$

where

- F = Switching frequency
- L = Inductor value
- ΔI_L = Peak-to-peak inductor ripple current
- $I_{L\text{max}}$ = Maximum inductor current

The following inductors have been used with the TPS6521855 (see [Table 8-2](#)).

Table 8-2. List of Recommended Inductors

PART NUMBER	VALUE	SIZE (mm) [L × W × H]	MANUFACTURER
INDUCTORS FOR DCDC1, DCDC2, DCDC3, DCDC4			
SPM3012T-1R5M	1.5 μ H, 2.8 A, 77 m Ω	3.2 × 3.0 × 1.2	TDK
IHLP1212BZER1R5M11	1.5 μ H, 4.0 A, 28.5 m Ω	3.6 × 3.0 × 2.0	Vishay
INDUCTORS FOR DCDC5, DCDC6			
MLZ2012N100L	10 μ H, 110 mA, 300 m Ω	2012 / 0805 (2.00 × 1.25 × 1.25)	TDK
LQM21FN100M80	10 μ H, 100 mA, 300 m Ω	2012 / 0805 (2.00 × 1.25 × 1.25)	Murata

8.2.2.3 Output Capacitor Selection

The hysteretic PWM control scheme of the TPS6521855 switching converters allows the use of tiny ceramic capacitors. Ceramic capacitors with low ESR values have the lowest output voltage ripple and are recommended. The output capacitor requires either an X7R or X5R dielectric.

At light load currents the converter operates in power save mode, and the output voltage ripple is dependent on the output capacitor value and the PFM peak inductor current. Higher output capacitor values minimize the voltage ripple in PFM Mode and tighten DC output accuracy in PFM mode.

The two battery backup converters (DCDC5 and DCDC6) always operate in PFM mode. For these converters, a capacitor of at least 20 μ F is recommended on the output to help minimize voltage ripple.

The buck-boost converter requires additional output capacitance to help maintain converter stability during high load conditions. At least 40 μ F of output capacitance is recommended and an additional 100-nF capacitor can be added to further filter output ripple at higher frequencies.

Table 8-2 lists the recommended capacitors.

Table 8-3. List of Recommended Capacitors

PART NUMBER	VALUE	SIZE (mm) [L × W × H]	MANUFACTURER
CAPACITORS FOR VOLTAGES UP TO 5.5 V⁽¹⁾			
GRM188R60J105K	1 μ F	1608 / 0603 (1.6 × 0.8 × 0.8)	Murata
GRM21BR60J475K	4.7 μ F	2012 / 0805 (2.0 × 1.25 × 1.25)	Murata
GRM31MR60J106K	10 μ F	3216 / 1206 (3.2 × 1.6 × 1.6)	Murata
GRM31CR60J226K	22 μ F	3216 / 1206 (3.2 × 1.6 × 1.6)	Murata
CAPACITORS FOR VOLTAGES UP TO 3.3 V⁽¹⁾			
GRM21BR60J106K	10 μ F	2012 / 0805 (2.0 × 1.25 × 1.25)	Murata
GRM31CR60J476M	47 μ F	3216 / 1206 (3.2 × 1.6 × 1.6)	Murata

(1) The DC bias effect of ceramic capacitors must be considered when selecting a capacitor.

8.2.3 Application Curves

at $T_J = 25^\circ\text{C}$ unless otherwise noted

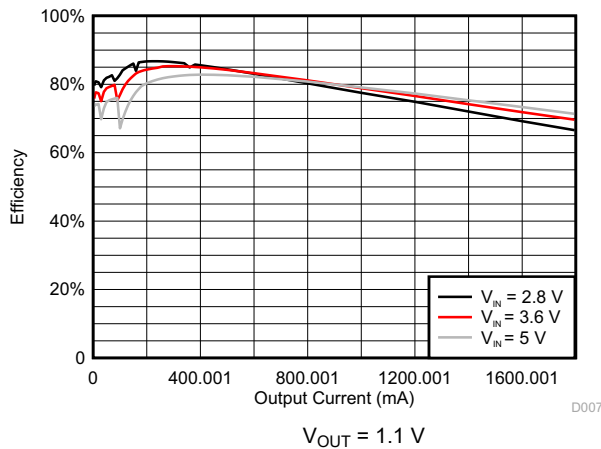


Figure 8-4. DCDC1/DCDC2 Efficiency

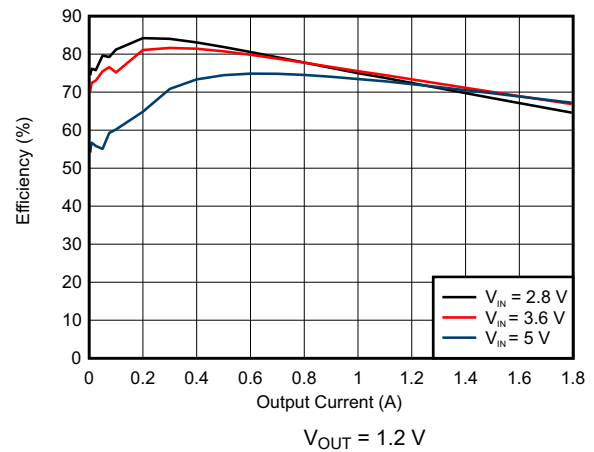


Figure 8-5. DCDC3 Efficiency

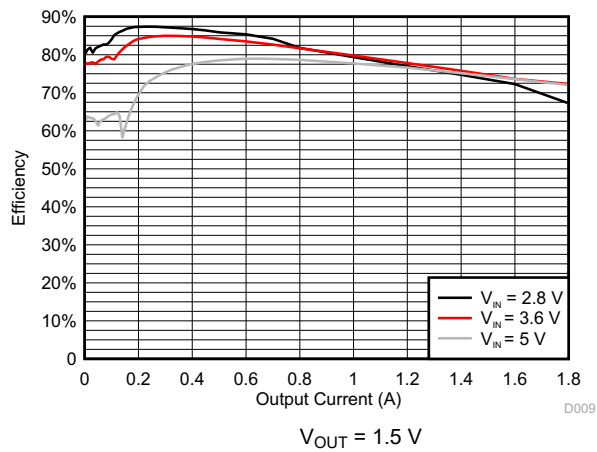


Figure 8-6. DCDC3 Efficiency

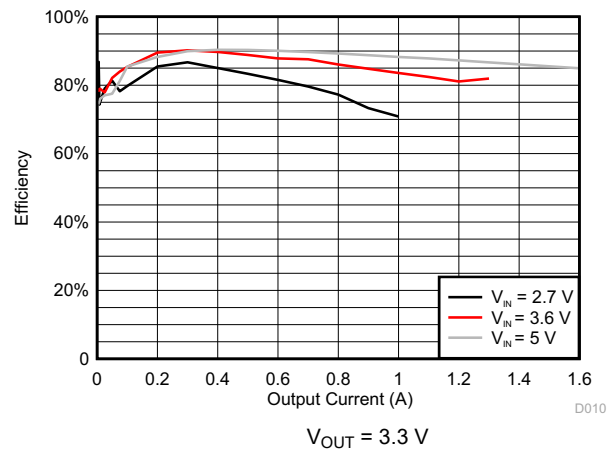


Figure 8-7. DCDC4 Efficiency

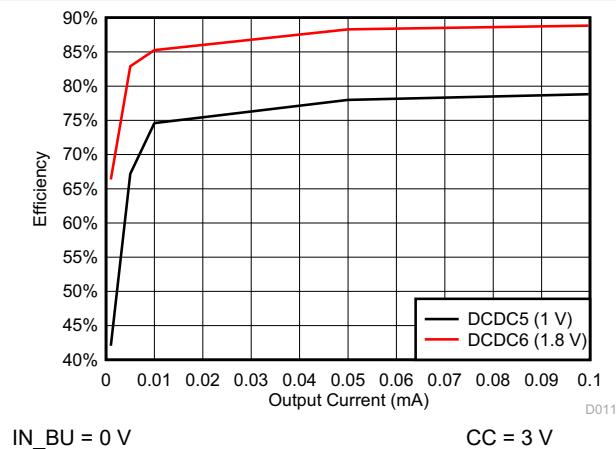


Figure 8-8. DCDC5/DCDC6 Efficiency

9 Power Supply Recommendations

The device is designed to operate with an input voltage supply range between 2.7 V and 5.5 V. This input supply can be from a single cell Li-Ion battery or other externally regulated supply. If the input supply is located more than a few inches from the TPS6521855 additional bulk capacitance may be required in addition to the ceramic bypass capacitors. An electrolytic capacitor with a value of 47 μF is a typical choice.

The coin cell back up input is designed to operate with an input voltage supply between 2.2 V and 3.3 V. This input should be supplied by a coin cell battery with 3-V nominal voltage.

10 Layout

10.1 Layout Guidelines

Follow these layout guidelines:

- The IN_X pins should be bypassed to ground with a low ESR ceramic bypass capacitor. The typical recommended bypass capacitance is 4.7- μF with a X5R or X7R dielectric.
- The optimum placement is closest to the IN_X pins of the device. Take care to minimize the loop area formed by the bypass capacitor connection, the IN_X pin, and the thermal pad of the device.
- The thermal pad should be tied to the PCB ground plane with a minimum of 25 vias. See [Figure 10-2](#) for an example.
- The LX trace should be kept on the PCB top layer and free of any vias.
- The FBX traces should be routed away from any potential noise source to avoid coupling.
- DCDC4 Output capacitance should be placed immediately at the DCDC4 pin. Excessive distance between the capacitance and DCDC4 pin may cause poor converter performance.

10.2 Layout Example

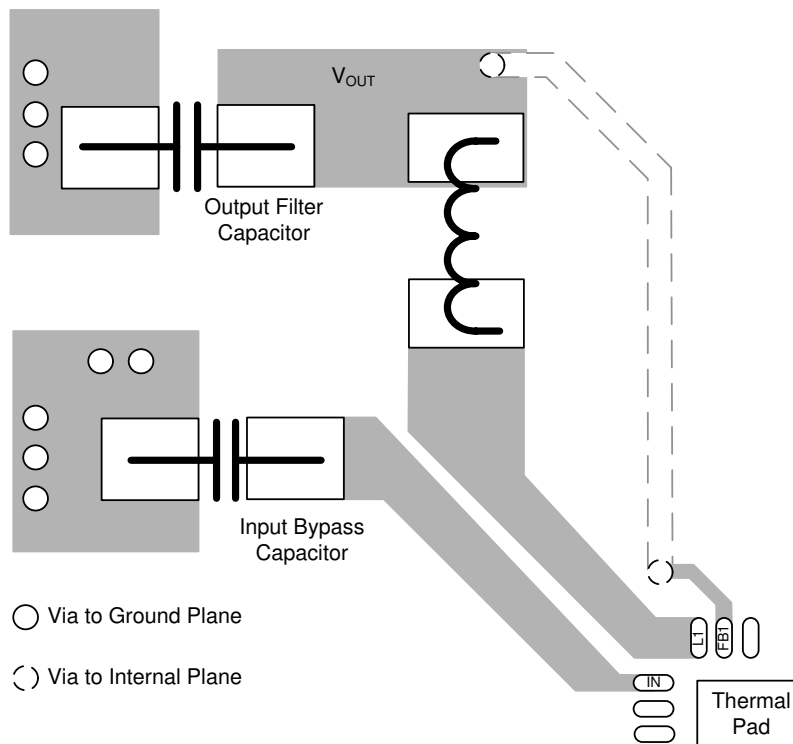
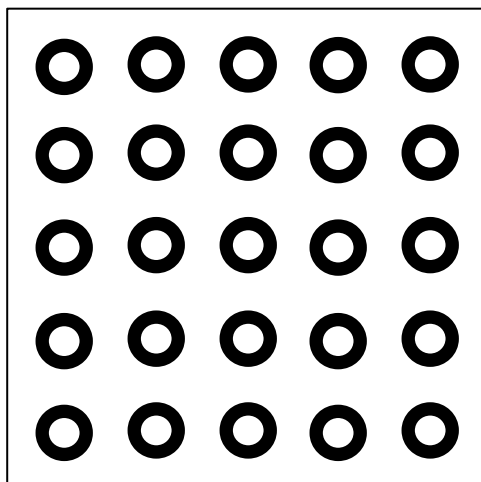


Figure 10-1. Layout Recommendation



Recommended Thermal Pad by size
Hole size (s) = 8 mil
Diameter (d) = 16 mil

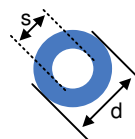


Figure 10-2. Thermal Pad Layout Recommendation

11 Device and Documentation Support

11.1 Documentation Support

11.1.1 Related Documentation

For related documentation see the following:

- Texas Instruments, [Basic Calculation of a Buck Converter's Power Stage](#) application report
- Texas Instruments, [Design Calculations for Buck-Boost Converters](#) application report
- Texas Instruments, [Empowering Designs With Power Management IC \(PMIC\) for Processor Applications](#) application report
- Texas Instruments, [TPS65218EVM user's guide](#)
- Texas Instruments, [TPS65218 Power Management Integrated Circuit \(PMIC\) for Industrial Applications](#) application report

11.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.3 Support Resources

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

11.4 Trademarks

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11.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.6 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

12.1 Package Option Addendum

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TPS6521855RSLR	Active	Production	VQFN (RSL) 48	2500 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	T6521855
TPS6521855RSLR.A	Active	Production	VQFN (RSL) 48	2500 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	T6521855
TPS6521855RSLT	Active	Production	VQFN (RSL) 48	250 SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	T6521855
TPS6521855RSLT.A	Active	Production	VQFN (RSL) 48	250 SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	T6521855

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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GENERIC PACKAGE VIEW

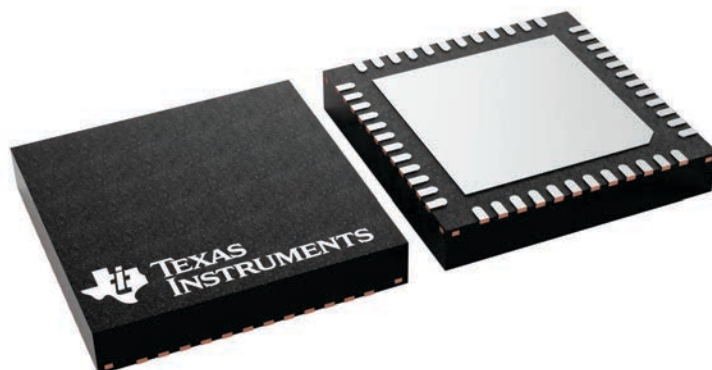
RSL 48

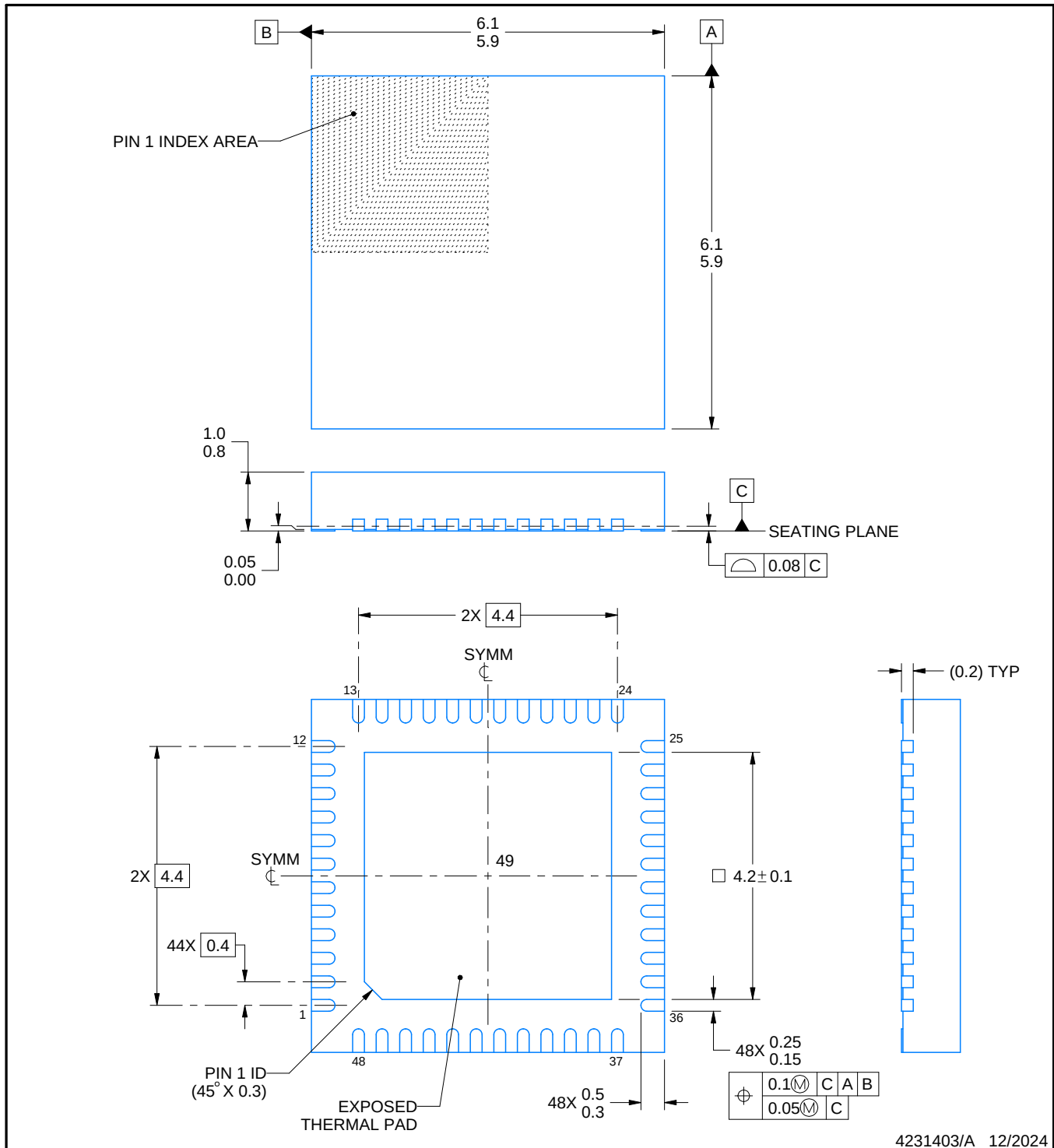
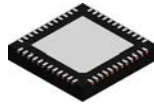
VQFN - 1 mm max height

6 x 6, 0.4 mm pitch

QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.





NOTES:

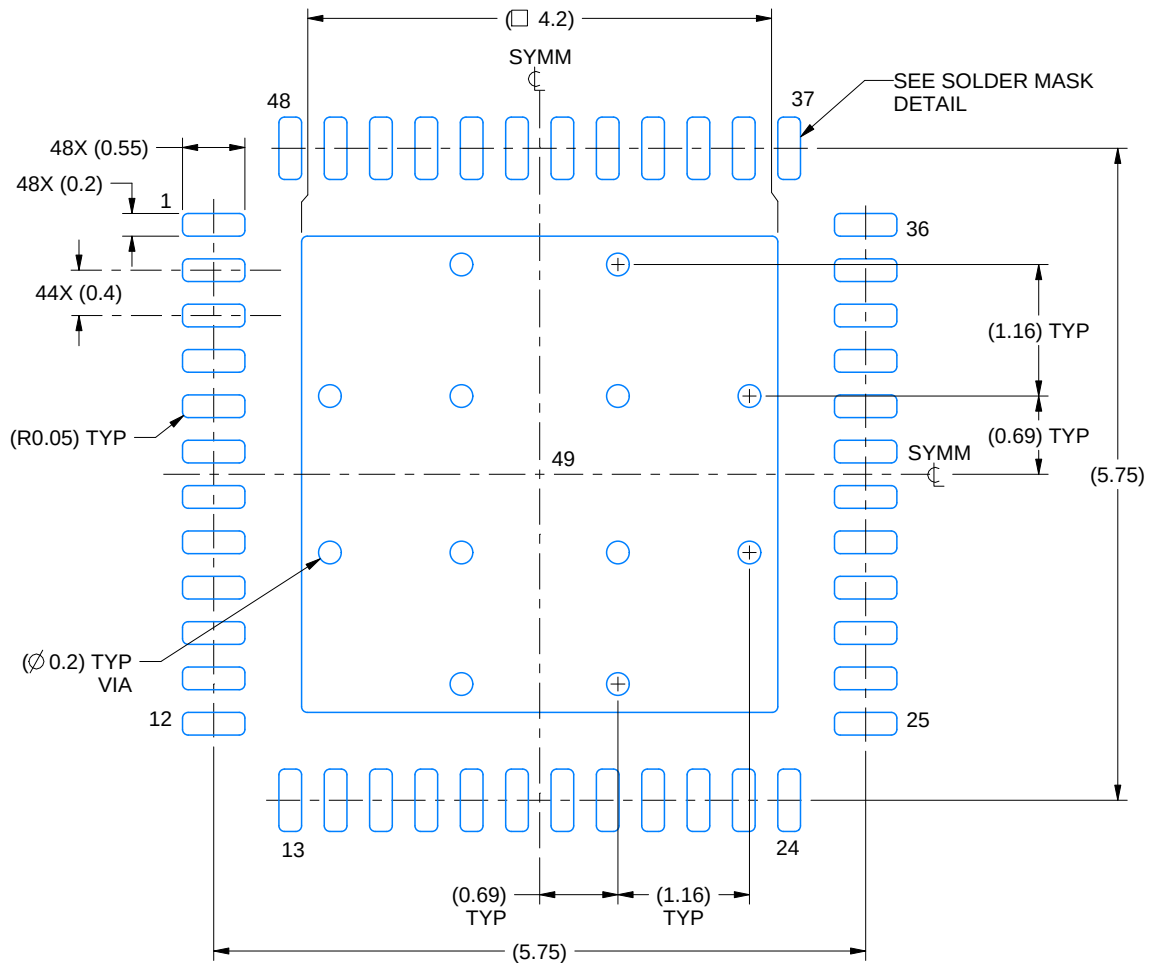
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

EXAMPLE BOARD LAYOUT

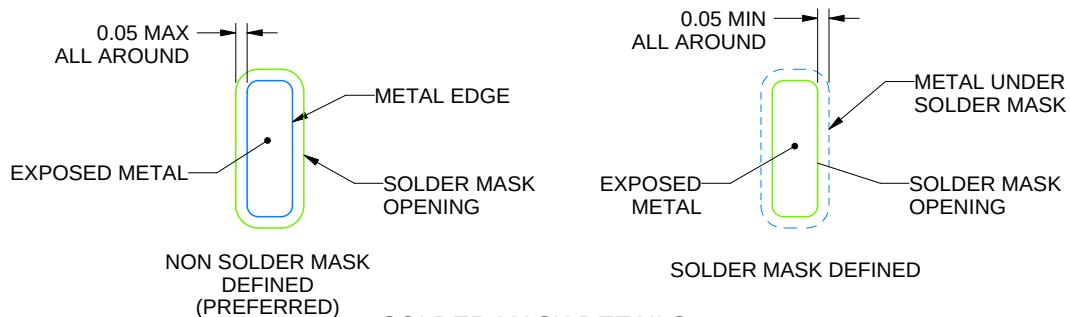
RSL0048G

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 15X



SOLDER MASK DETAILS

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NOTES: (continued)

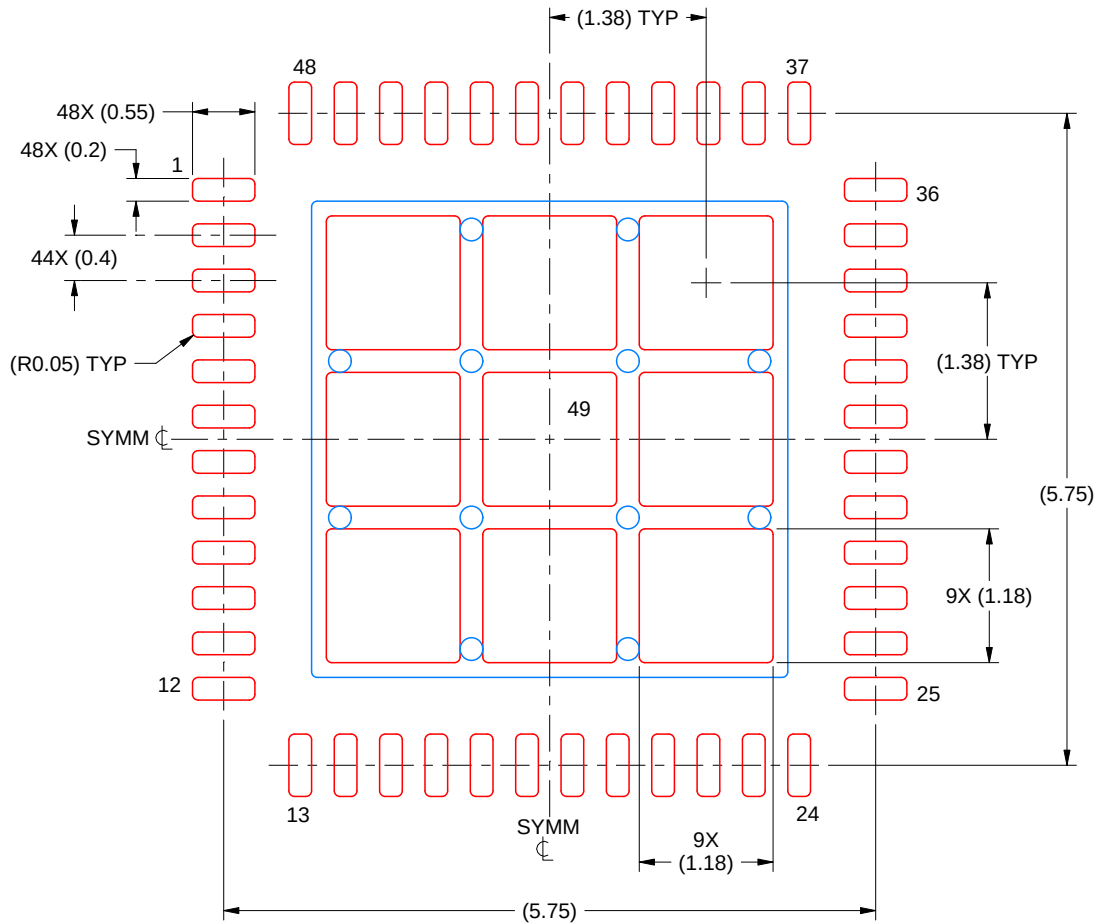
- This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/sluea271).
- Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

EXAMPLE STENCIL DESIGN

RSL0048G

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



SOLDER PASTE EXAMPLE
BASED ON 0.1 MM THICK STENCIL
SCALE: 15X

EXPOSED PAD 49
71% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE

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NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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